Introduction

M-Bus (meter bus) is a common automatic meter reader (AMR) standard for remote energy meter reading in compliance with European standard (EN 13757-2 physical and link layer and EN 13757-3 application layer). M-Bus is also compliant with the European Standard EN 1434 on heat meters.

The M-Bus interface is based on the very cost effective two-wire, twist cable transmission, and is compatible with all network topologies (linear, star, etc.) except ring networks. When queried, meters send their data to a concentrator from which the data can be read locally or remotely.

Wireless M-Bus is the radio variant of M-Bus for automatic meter reading at sub-1-GHz radio frequencies. While European standard EN13757-3:2013 for the application layer remains the same as M-Bus, the applicable physical and link layer European standard becomes EN13757-4:2013 Wireless meter readout, as well as ETSI EN 300 220 v2.3.1 for short range radio equipment.

The Wireless M-Bus firmware stack is based on EN 13757-4:2013 (Communication systems for meters and remote reading of meters — Part 4: Wireless meter readout (Radio meter reading for operation in SRD bands)). This European Standard specifies the required physical and link layer parameters for systems using radio to read remote meters, focusing primarily on the use of unlicensed, short range device (SRD) telemetry bands. The standard encompasses systems for walk-by, drive-by and fixed installations.

Several different modes of operation are defined for meter communication, with specific parameters governing only the operational and technical requirements of these differing modes, leaving the bulk of common parameters to facilitate common software and architecture components.

Mode nomenclature consists of a letter and a number. The letter specifies the mode type and the number specifies whether the mode supports unidirectional (1) or bidirectional (2) data transfer.

Figure 1: Basic Wireless M-Bus architecture
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The standard defines the communication protocol between remote meters and mobile readout devices, stationary receivers, data collectors etc.

**Figure 2: Typical application scenario**

![Diagram](image1)

This document describes the wM-Bus physical (Phy) and link layers of the Wireless M-Bus firmware stack application, developed by STMicroelectronics in compliance with applicable European standards.

**Figure 3: Firmware architecture**

![Diagram](image2)
1 Definitions, acronyms and abbreviations

**Meters**: devices that request/send data to the other devices via the wM-Bus standard.

**Other devices**: usually concentrator devices which exchange the information with meters. They are the mobile readout devices.

**Firmware**: the firmware referred to in this document is developed and tested on the Spirit1 + STEVAL-IKR001Vx board and is compliant with wM-Bus 2013 standard (NEN-EN 13757-3:2013 & NEN-EN 13757-4:2013).

<table>
<thead>
<tr>
<th>Acronym</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACC-DMD</td>
<td>Access-Demand</td>
</tr>
<tr>
<td>ACC-NR</td>
<td>Access-No Reply</td>
</tr>
<tr>
<td>ACK</td>
<td>Acknowledgement</td>
</tr>
<tr>
<td>AMR</td>
<td>Automatic Meter Reading</td>
</tr>
<tr>
<td>CNF-IR</td>
<td>Confirm Installation Request</td>
</tr>
<tr>
<td>MHz</td>
<td>Mega Hertz</td>
</tr>
<tr>
<td>REQ-UD</td>
<td>Request User Data(Class1/2)</td>
</tr>
<tr>
<td>RSP-UD</td>
<td>Respond User Data</td>
</tr>
<tr>
<td>SND-IR</td>
<td>Send Installation Request</td>
</tr>
<tr>
<td>SND-NKE</td>
<td>Send Link Reset</td>
</tr>
<tr>
<td>SND-UD</td>
<td>Send User Data</td>
</tr>
<tr>
<td>USB</td>
<td>Universal Serial Bus</td>
</tr>
<tr>
<td>wM-Bus</td>
<td>Wireless Meter Bus</td>
</tr>
</tbody>
</table>

Table 1: Acronyms and abbreviations
2 Hardware platform

ST's Wireless M-Bus firmware stack application is based on its proprietary dual chip platform: the new SPIRIT1 RF Sub-1 GHz transceiver and the STM32L15 ultra-low-power ARM Cortex-M3 microcontroller.

Figure 4: Application layers

2.1 SPIRIT1

SPIRIT1 is a very low power, high performance RF transceiver, ideal for RF wireless applications in the sub-1-GHz band. It is designed to operate at 169, 315, 433, 868, and 915 MHz and supports 2-FSK, GFSK, MSK, OOK, and ASK modulations. The air data rate is programmable from 1 to 500 kbps, depending on the selected modulation.

Its integrated SMPS allows very low power consumption:
- 9 mA in Rx and 21 mA in Tx mode at +11 dBm.

Furthermore, it uses a very small number of discrete external components and integrates a configurable baseband modem for data management, modulation and demodulation. Data can be managed in a proprietary, fully programmable packet format as well as the M-Bus standard compliant format (all performance classes).

The SPIRIT1 provides native hardware support for the low level wM-Bus Phy protocol.

2.1.1 SPIRIT1 function:
- wM-Bus Modes
- Header, Sync and trailer fields
- Manchester/3-out-of-6-encoding
- Sync detection
2.2 **ST’s ultra-low power EnergyLite™ MCU family**

Gas, water and heat meters with wM-Bus technologies are usually battery powered devices that need to be highly efficient to preserve battery life.

The 8-bit (STM8L) and 32-bit (STM32L) EnergyLite™ family of MCUs combines high performance and ultra-low power, offering specific features for ultra-low power applications such as advanced ultra-low power modes and optimized dynamic run consumption, as well as special safety features.

The ultra-low-power EnergyLite platform, based on STMicroelectronics’ 130 nm ultra-low-leakage process technology, provides a common technology, design and peripheral framework across the product range.

The ARM® Cortex™-M3-based STM32 L1 series extends the ultra-low power concept without compromising performance, offering a wide assortment of features, memory sizes and package pin quantities. The range covers 32 to 384 Kbytes Flash memory (with up to 48 Kbytes of RAM and 12 Kbytes of true embedded EEPROM) and 48 to 144 pins.

This innovative architecture, with voltage scaling and an ultra-low-power MSI oscillator, gives your design more performance for a very low power budget. The generous suite of embedded peripherals, including USB, LCD interface, OpAmp, comparator, ADC with fast on/off mode, DAC, capacitive touch and AES renders the STM32 L1 series an expandable platform able to fit all your requirements.

### 2.2.1 STM32L function:

- wM-Bus application layer
  - wireless M-Bus application layer partially implementing EN13757-3.
- wM-Bus link layer
  - MAC packet and CRC handling
  - encryption/decryption initiate/read.
- wM-Bus Phy
  - init Phy for wM-Bus
  - interrupt services
3 Wireless M-Bus protocol overview

Some of the salient features of the Wireless M-Bus standard are:

- support for unidirectional and bidirectional communication between meters and other devices
- support for different of communication modes (S, T, R, N (Except N2g), C and F), depending upon the requirement of the application
- support for AES-128 encryption for data security
- operates both in the license-free ISM and SRD frequency bands at 169, 315, 433, 868, and 915 MHz
- provision for indicating faults and alarms.

More details can be found in the EN 13757-4 standard.

For the physical layer, the EN 13757-4 standard also specifies various performance classes depending on the maximum power to be transmitted and lowest receiver sensitivity that the meter provides.

The data link layer of the EN 13757-4 standard supports two different frame formats: A and B. In a standard Wireless M-Bus received frame, the data link layer immediately follows the preamble chip sequence, carrying link layer data plus optional application layer payload information. For C, F and modes, the frame format can be determined from the pattern of the preamble chip sequence. The Wireless M-Bus standard allows for the encryption of the payload data using optimized encryption modes like AES 128 CBC.

3.1 wM-Bus modes

The following table summarizes the various modes supported by STMicroelectronics wM-Bus stack.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Communication</th>
<th>Frequency band</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S1</td>
<td>Unidirectional</td>
<td>868 MHz</td>
<td>Stationary mode: metering devices send their data several times a day. The data collector may be a battery operated device and optimized for stationary operation.</td>
</tr>
<tr>
<td>S1-m</td>
<td>Unidirectional</td>
<td>868 MHz</td>
<td>Same as S1, but the data collector is a mobile receiver.</td>
</tr>
<tr>
<td>S2</td>
<td>Bidirectional</td>
<td>868 MHz</td>
<td>Bidirectional version of S1.</td>
</tr>
<tr>
<td>T1</td>
<td>Unidirectional</td>
<td>868 MHz</td>
<td>In the frequent transmit mode, meters send the data every few seconds to collectors in range. The interval is configurable (seconds or minutes).</td>
</tr>
<tr>
<td>T2</td>
<td>Bidirectional</td>
<td>868 MHz</td>
<td>Bidirectional version of T1.</td>
</tr>
<tr>
<td>R2</td>
<td>Bidirectional</td>
<td>868 MHz</td>
<td>The frequent receive mode prevents multiple metering devices from interfering with each other by using separate frequency channels.</td>
</tr>
<tr>
<td>N1</td>
<td>Unidirectional</td>
<td>169 MHz</td>
<td>This mode is optimized for narrowband and long range</td>
</tr>
<tr>
<td>N2</td>
<td>Bidirectional</td>
<td>169 MHz</td>
<td>Bidirectional version of N1. This mode doesn't support N2g, which requires 4-GFSK modulation.</td>
</tr>
<tr>
<td>F2-m</td>
<td>Bidirectional</td>
<td>433 MHz</td>
<td>Bidirectional communication. It works on NRZ data encoding.</td>
</tr>
</tbody>
</table>
### Wireless M-Bus protocol overview

<table>
<thead>
<tr>
<th>Mode</th>
<th>Communication</th>
<th>Frequency band</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>F2</td>
<td>Bidirectional</td>
<td>433 MHz</td>
<td>Bidirectional communication. It works on NRZ data encoding.</td>
</tr>
<tr>
<td>C1</td>
<td>Unidirectional</td>
<td>868 MHz</td>
<td>Unidirectional communication. It works on NRZ data encoding.</td>
</tr>
<tr>
<td>C2</td>
<td>Bidirectional</td>
<td>868 MHz</td>
<td>Bidirectional communication. It works on NRZ data encoding.</td>
</tr>
</tbody>
</table>

#### 3.1.1 Stationary mode (S Mode)
This is intended for unidirectional or bidirectional communications between the meter and a stationary or mobile device.
- S1 transmit only sub-mode has a long header and is optimized for stationary battery operated devices
- S1-m sub-mode is designed for mobile receivers
- S2 mode is bidirectional

#### 3.1.2 Frequent transmit mode (T Mode)
In this mode, the meter transmits a very short frame (typically 3 to 8 ms) every few seconds, thus allowing walk-by and drive-by readouts.
- T1 transmit only sub-mode is limited to the minimal, periodic transmission of meter ID plus a readout value
- T2 bidirectional sub-mode frequently transmits a short frame containing at least its ID and then waits for a very short period after each transmission for a response, which triggers bidirectional communication. Alternatively, the initial frame also contains the readout value and the response is a reverse channel reserved for special services.

#### 3.1.3 Frequent receive mode (R2 Mode)
In this mode, the meter listens every few seconds for the reception of a wakeup message from a mobile transceiver, whereupon the device prepares for a few seconds of dialog with the initiating transceiver.
A multi-channel receive mode allows the simultaneous readout of several meters on separate frequency channels.

#### 3.1.4 Narrowband VHF mode (N-Mode)
This mode is optimized for narrowband operation in the 169-MHz frequency band allocated for meter reading and other services.
- N1a-f covers transmit only sub-modes
- N2a-f covers bidirectional sub-modes.
The range of sub-modes can be extended using repeaters.

#### 3.1.5 Frequent receive and transmit mode (F-Mode)
This mode is a frequent receive and transmit mode for long range communication in the 433 MHz band.
- F2-m is the bidirectional sub-mode where the meter listens every few seconds for a wake up signal from a stationary or mobile transceiver, upon which the device prepares for a few seconds of dialog with the initiating transceiver.
- F2 is the bidirectional sub-mode where the device transmits a frame and waits a short period for a response, which triggers bidirectional communication.

3.1.6 Compact Mode (C-Mode)

This compact Mode operates in the 868 MHz Band. It is similar to the T-Mode, but sends more info with the same energy. It functions in Unidirectional/Bidirectional mode. All communication from the Meter to Other devices is in the form of FSK Modulated data and all communication from Other Device to Meter takes place as GFSK Modulated data. All communication is NRZ encoded.

- C1 Mode: Unidirectional Mode
- C2 Mode: Bidirectional Mode
4 Wireless M-Bus physical layer

The physical structure of the frame includes the preamble (header plus synchronization fields), payload and postamble, as per the figure below.

4.1 Frame structure

4.1.1 Preamble

The preamble consists of the header plus synchronous patterns.

The synchronization word required by EN-13757-4 is 18 bits for S and R modes, 10 bits for T mode, 16 bits for N mode etc. The synchronization word is always preceded by the preamble sequence.

4.1.2 Payload

The block structure of the payload field storing the data to be transmitted is configured in the firmware.

4.1.3 Postamble (trailer)

The number of ‘01’ sequences is added to the postamble at the end of packet as per the wM-Bus standard.

4.2 Physical layer files

The firmware files for the Wireless M-Bus physical layer are:

- wmbus_phy.c routines
- wmbus_phy.h headers
5  Wireless M-Bus link layer

The wM-Bus link layer is compliant with EN13757-4:2013 to interface the physical layer (Phy) and the application layer (AL).

5.1  Data link layer functions

The data link layer

- provides services to transfer data between the physical and application layers
- generates outgoing CRC and verifies CRCs for incoming messages
- provides wM-Bus addressing
- acknowledges transfers for bidirectional communication modes
- wM-Bus frame formation and verification of incoming frames

5.2  Link layer specification

The Wireless M-Bus standard supports two different, A and B, frame formats.

In both formats:

- the first block has a fixed length of 10 bytes and includes the frame length (L-field), the control information (C-field) and the sender address (link layer address).
- the second block starts with the CI-field which declares the data structure.

5.2.1  Frame format A

Transmission frame format A complies with IEC 60870-5-1 format type FT3.

The first byte of the first block is the length field which specifies the number of subsequent user data bytes, including the control and address bytes and excluding the CRC bytes. If ((L-9) MOD 16) is not zero, then the last block shall contain ((L-9) MOD 16) data bytes + 2 CRC bytes. All the other blocks except the first block shall always contain 16 data bytes + 2 CRC bytes.

<table>
<thead>
<tr>
<th>Table 3: First block (format A)</th>
</tr>
</thead>
<tbody>
<tr>
<td>L-field</td>
</tr>
<tr>
<td>1 byte</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Table 4: Second block (format A)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CI-field</td>
</tr>
<tr>
<td>1 byte</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Table 5: Optional block (format A)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data-field</td>
</tr>
<tr>
<td>16 or if it is the last block ((L-9) modulo 16) bytes</td>
</tr>
</tbody>
</table>

5.2.2  Frame format B

The first byte of the first block is the length field which specifies the number of all subsequent bytes including all CRC bytes.
Table 6: First block (format B)

<table>
<thead>
<tr>
<th>Field</th>
<th>Format</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>L-field</td>
<td></td>
<td>1 byte</td>
</tr>
<tr>
<td>C-field</td>
<td></td>
<td>1 byte</td>
</tr>
<tr>
<td>M-field</td>
<td></td>
<td>2 bytes</td>
</tr>
<tr>
<td>A-field</td>
<td></td>
<td>6 bytes</td>
</tr>
</tbody>
</table>

Table 7: Second block (format B)

<table>
<thead>
<tr>
<th>Field</th>
<th>Format</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>CI-field</td>
<td></td>
<td>1 byte</td>
</tr>
<tr>
<td>Data-field</td>
<td></td>
<td>115 or if it is the last block (L-12) bytes</td>
</tr>
<tr>
<td>CRC-field</td>
<td></td>
<td>2 bytes</td>
</tr>
</tbody>
</table>

Table 8: Optional block (format B)

<table>
<thead>
<tr>
<th>Field</th>
<th>Format</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data-field</td>
<td></td>
<td>(L-129) bytes</td>
</tr>
<tr>
<td>CRC-field</td>
<td></td>
<td>2 bytes</td>
</tr>
</tbody>
</table>

5.2.3 The L-field

The L-field is the first byte of the first block.
- frame format A: consists of subsequent user data, control and address bytes, excluding CRC.
- frame format B: includes all subsequent bytes including CRC.

5.2.4 The C-Field

The general bit sequence structure of the C-field is shown below:

![Figure 7: The C-Field](image)

<table>
<thead>
<tr>
<th>RES</th>
<th>PRM</th>
<th>FCB</th>
<th>FCV</th>
<th>ACD</th>
<th>DFC</th>
<th>Function code</th>
<th>Primary to secondary</th>
<th>Secondary to primary</th>
</tr>
</thead>
</table>

RES:
- always '0'

PRM:
- '1' message from primary (initiating) station
- '0' message from secondary (responding) station

FCB, FCV and ACD, DFC:
- all bit coded according to EN 60870-5-2.

5.2.5 Manufacturer ID (M-field)

The 15 least significant bits of these two bytes form a three letter ISO 646 code (A...Z), as per clause 5.6 of EN 13757-3:2013. If the most significant bit is zero, then the address A must be a unique (hard coded) 6-byte manufacturer meter address. Any type of coding or numbering, including type/version/date may be used, as long as the ID is unique.

5.2.6 Address (A-field)

This address field A always contains the address of the sender (e.g., address of a meter with integrated RF-Module or address of an RF-Adapter hosting a meter without RF-Interface). It must at least be unique within the maximum transmission range, and it is the responsibility of each user/manufacturer to guarantee this.
If this protocol is used together with the Transport Layer or the Application Layer of EN 13757-3, then the A-field address structure is a concatenation of the 'Identification number', 'Version number' and 'Device type information'.

5.2.7 **CI-field**

The CI-field is the application header and specifies the type of data in the application data payload. While EN13757-4:2011 specifies a limited number of values, the Link Service Primitives allow any value to be used.

5.2.8 **Data field**

- The user data to be transmitted is stored in this field.

5.2.9 **Cyclic redundancy check (CRC-field)**

The CRC calculation is based on the information from the previous block according to FT3 of EN 60870-5-1.

The formula is:

- The CRC polynomial is: \( x^{16} + x^{13} + x^{12} + x^{11} + x^{10} + x^8 + x^6 + x^5 + x^2 + 1 \)

The initial value is 0; the final CRC is complemented.

5.3 **Link layer firmware implementation**

5.3.1 **File description**

The Link Layer Directory structure is shown below:

![Figure 8: Link layer directory structure](image)

The wM-Bus link layer implementation files are:

- wmbus_link.c routines
- wmbus_link.h headers
- wmbus_linkcommand.c command routines
- wmbus_linkcommand.h headers for wmbus_linkcommand.c
- wmbus_crc.c wM-Bus CRC routines

5.3.2 **State machine flow structure**

- There are two separate state machines for meters and other devices, where different events move the devices from IDLE to a new state according to the following state machine transition tables.
Table 9: State machine table for meters

<table>
<thead>
<tr>
<th>Current State</th>
<th>Event</th>
<th>Next State</th>
</tr>
</thead>
<tbody>
<tr>
<td>LL_SM_IDLE</td>
<td>SND-UD</td>
<td>LL_SM_SEND_ACK</td>
</tr>
<tr>
<td></td>
<td>SND-UD2</td>
<td>LL_SM_SEND_RSP_UD</td>
</tr>
<tr>
<td></td>
<td>REQ-UD2</td>
<td>LL_SM_SEND_RSP_UD</td>
</tr>
<tr>
<td></td>
<td>REQ-UD1</td>
<td>LL_SM_SEND_RSP_UD (If Alarm Data available)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>LL_SM_SEND_ACK (If Alarm Data not available)</td>
</tr>
<tr>
<td></td>
<td>CNF-IR</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>SND-NKE</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>ACK</td>
<td>LL_SM_SEND_ACC_NR</td>
</tr>
<tr>
<td>LL_SM_SEND_ACK</td>
<td></td>
<td>LL_SM_ACK_FAC_STATE</td>
</tr>
<tr>
<td>LL_SM_ACK_FAC_STATE</td>
<td>If(nRepeatation&lt;= N)</td>
<td>LL_SM_SEND_ACK</td>
</tr>
<tr>
<td></td>
<td>If(nRepeatation &gt; N)</td>
<td>LL_SM_IDLE</td>
</tr>
<tr>
<td>LL_SM_SEND_RSP_UD</td>
<td></td>
<td>LL_SM_RSPUD_FAC_STATE</td>
</tr>
<tr>
<td>LL_SM_SEND_ACC_NR</td>
<td></td>
<td>LL_SM_WAIT_STATE</td>
</tr>
<tr>
<td>LL_SM_RSPUD_FAC_STATE</td>
<td>If(nRepeatation&lt;= N)</td>
<td>LL_SM_SEND_RSP_UD</td>
</tr>
<tr>
<td></td>
<td>If(nRepeatation&gt; N)</td>
<td>LL_SM_IDLE</td>
</tr>
<tr>
<td>LL_SM_WAIT_STATE</td>
<td>If(time &lt;tResponseMax)</td>
<td>Wait to receive command</td>
</tr>
<tr>
<td></td>
<td>If(time &gt;tResponseMax)</td>
<td>LL_SM_IDLE</td>
</tr>
<tr>
<td>LL_SM_IDLE</td>
<td>SND-NR</td>
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<tr>
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<td>ACC-NR</td>
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<td>SND-IR</td>
<td>LL_SM_SEND_CNF_IR</td>
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<td>ACC-DMD</td>
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<td></td>
<td>RSP-UD</td>
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</tr>
<tr>
<td></td>
<td>ACK</td>
<td>If DataReqFlag is TRUE: LL_SM_SEND_REQ_UD2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If ResetLinkFlag is TRUE: LL_SM_SEND_NKE</td>
</tr>
<tr>
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<td></td>
<td>If SendDataFlag is TRUE: LL_SM_SEND_SND_UD</td>
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<td>LL_SM_WAIT_RSP_UD</td>
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<td>LL_SM_WAIT_RSP_UD</td>
<td>If(time &lt;=Timeout)</td>
<td>Wait to receive command</td>
</tr>
<tr>
<td></td>
<td>If(time&gt;Timeout)</td>
<td>LL_SM_IDLE</td>
</tr>
<tr>
<td>LL_SM_SEND_NKE</td>
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<td>LL_SM_IDLE</td>
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<td>LL_SM_SEND_SND_UD</td>
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<td>LL_SM_WAIT_ACK</td>
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<tr>
<td>LL_SM_WAIT_ACK</td>
<td>If(time &lt;=Timeout)</td>
<td>Wait to receive command</td>
</tr>
<tr>
<td></td>
<td>If(time&gt;Timeout)</td>
<td>LL_SM_IDLE</td>
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</table>
### 5.4 Application layer dependent parameters

Certain application layer dependent parameters for the link layer are passed from the application layer to the link layer through “WMBusLinkAppliParams_t” according to the following structure:

```c
typedef struct
{
    uint8_t LinkEllLength;/*!<Extended link layer length*/
    uint8_t LinkHeaderLength;/*!<Header length*/
    uint16_t LinkManufrID;/*!<Manufacturing id*/
    uint32_t LinkDeviceID;/*!<Device identification number*/
    uint8_t LinkDeviceVersion;/*!<Device version*/
    uint8_t LinkMeterType;/*!<Meter type*/
    uint8_t LinkAccessNumber;/*!<Access Number*/
    uint32_t LinkStatusField;/*!<Status field*/
    uint32_t LinkConfigWord;/*!<Configuration word*/
    uint32_t LinkTimeout;/*!<User defined timeout*/
    uint8_t LinkFreqAccessCycle;/*!<Frequent Access Cycle*/
    ExtendedLinkLayer_t LinkEllType;/*!<Extended link layer type*/
    uint8_t LinkEllAccessNum;/*!<Extended link layer access number*/
} WMBusLinkAppliParams_t;
```

“LinkAppliParams” is the “WMBusLinkAppliParams_t”-type structure defined in the link layer and is initialized by the application layer in the “WMBus_LinkSetAppliParams”
function via pointer. The user then calls the “WMBus_LinkSetAppliParams” function from the application layer to set the user-dependent parameters for the link layer.
6 Revision history

Table 11: Document revision history

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<thead>
<tr>
<th>Date</th>
<th>Version</th>
<th>Changes</th>
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<tr>
<td>02-Dec-2015</td>
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<td>Initial release.</td>
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