Introduction

This report shows the analysis performed on Power MOSFET devices, in which the goal is the evaluation of the intrinsic $R_g$ parameter while it works in real applications. Generally, the $R_g$ parameter is an intrinsic resistance value of the device itself, which cannot be changed because it's linked to the manufacturing process. The $R_g$ parameter, according to the external driving circuit, allows the switching operation mode to be defined in terms of turn-on/off period and also coupling power dissipation of the external driver itself.

Starting from this statement, the analysis focused on devices having different intrinsic internal $R_g$ and these were tested in a simple testing board with a fixed driver. The various tests performed allow us to understand the electro-thermal behavior of the device better and to find new conclusions on this parameter, which are often not known.
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1 Brief introduction to Power MOSFET intrinsic gate resistance

Power MOSFETs are 3-pin voltage-controlled devices: with a suitable voltage applied between gate and source, higher than the Power MOSFET threshold voltage, a current flows through the device channel between drain and source.

Figure 1. Power MOSFET symbol, typical circuit and device structure

Figure 1 represents the Power MOSFET symbol, a typical circuit used for characterization tests and the device structure. The gate-source junction in the silicon is isolated by the oxide layer (gate oxide) and the drain-source current $I_d$ flows only if $V_{gs} > V_{th}$ is applied. Generally, even though the oxide layer is present in the gate-source structure, a leakage current flows through it. In other words, the gate-source structure can be represented for simplicity as a highly capacitive impedance; the real part of the impedance is the intrinsic $R_g$ of the MOSFET.

The intrinsic gate resistance is an equivalent electrical resistance due to many device structure contributions (oxide, P-body, gate finger distributions...). The $R_g$ value is a critical parameter that deeply impacts the device's switching performance, together with the power conversion efficiency and device thermal management. The higher the $R_g$, the larger the device's switching and gate drive losses, and consequently, the higher the working temperature of the MOSFET. In this case, there is the need for additional cooling components (i.e. heatsinks). Figure 2 shows a simple representation of the internal parameters of a device.
Figure 2. Internal parameters of the device

In order to better understand the impact of $R_g$ on the device's switching performance, two different analyses are performed:

1. “Unclamped inductive switching” test on a characterization board; the device under test is a 120 A / 40 V LL $V_{th}$ device selected with different intrinsic $R_g$ values.

2. Application analysis on a 2.5” HDD board, where “good” parts (with correct $R_g$ value) are compared with “bad” devices (with high $R_g$) in terms of switching behavior and device temperature.
2 R_g impact evaluation by UIS test

The electrical schematic used is shown in Figure 3:

**Figure 3. Electrical schematic for UIS test**

First of all, the dynamic MOSFET parameters (Ciss, Crss, Coss, R_g) are measured and the relevant values are reported in Table 1. Then, the UIS test is performed (V_{dd} = 12/18 V, L = 10 µH, t_{on} = 8 µs, T = 100 µs) on the low and high R_g parts. In this way, it is possible to make a first evaluation of the R_g impact.

The UIS test is also performed on standard devices, varying the external gate resistance and monitoring the case temperature at steady-state. Additional tests are performed with resistive and capacitive load at various external R_{g,ext}. Based on the results obtained, we try to carry out the correlation between case temperature and R_g and the possible suggestions for a specific R_g limit for final test screening.

**Table 1. Dynamic parameters of devices under test**

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In Figure 4 the typical waveforms for a good part (device #5) during an entire switching cycle are reported.
It’s important to highlight that when the $V_{GS}$ value goes down, the current begins to decrease and the $V_{DS}$ increases its value, achieving the avalanche condition. During the discharge the device must dissipate a power represented by the $P_d$ curve (violet and with a triangular shape). If a high $R_g$ device is tested, the relevant waveform is reported in Figure 5.
In this image, the D.U.T. is the sample #4 that has an intrinsic $R_g$ around 54 $\Omega$. Comparing Figure 4 and Figure 5, it is easy to see that the device behavior and the relevant waveforms are very different. In fact, when the $V_{gs}$ (yellow trace) goes down, the drain current (purple trace) continues to increase.

To better understand this phenomenon, a simple image is used:

**Figure 6. MOSFET gate driving circuits with turn-on/off current paths**
The image shows the electrical connection between the driver and D.U.T. and the current flowing during switching-on and off.

The “Driver” is composed of two Power MOSFETs in push-pull configuration. The D.U.T. turn-on is achieved when a positive gate-source voltage \( V_{GS} = V_S \) is applied to the gate, switching on the upper MOSFET; and vice-versa, the D.U.T. turns off when the lower MOSFET of the driver is in ON state, pulling down the D.U.T. gate to GND.

The red arrows show the current path charging internal capacitances when D.U.T. is turned on, and discharging capacitances when it is turned off. The image points out the internal \( R_g \) resistance and \( C_{gs} \) capacitance, since \( T_{on} \) and \( T_{off} \) are affected by those values. \( T_{on} \) and \( T_{off} \) represent times to complete the D.U.T. turn-on and turn-off.

The combination of \( R_g \) and \( C_{gs} \) is a simple RC circuit whose constant time \( \tau = RC \) affects charge and discharge time. There are also other parameters that contribute to the turn-on/off of D.U.T. but it is important to underline that \( R_g \) is a key factor. In this case, with inductive load, the power dissipated by the device with higher \( R_g \) is bigger than the standard \( R_g \) device one because the switching slowdown, especially at turn-off, produces an additional current increase, due to the fact that the device remains on slightly longer, even if the gate-source voltage is already low.

A similar behavior may be obtained adding an external \( R_g \) resistor to a standard device. By inserting an external resistor of 50 \( \Omega \) we have the following waveform:

![Figure 7. High Rg switching waveforms (with 50 \( \Omega \) additional external resistor)](image)

The curve shows that the external \( R_g \) enlarges switching times and the main effect appears at turn-off. In fact, the \( V_{gs} \) is down and the current increases itself for an additional 1.6 \( \mu s \).
In order to measure the impact of $R_g$, we performed many tests at the same electrical conditions on an $R_g$ standard device inserting an external $R_g$ driver and catching the case temperature at steady-state.

At bench, we performed many trials at various resistances using the same electrical circuit board at different loads, which are the following:

- inductor load
- capacitive load (see Figure 8)
- resistor load (see Figure 8).

Figure 8. Testing circuit schematics

The results show that the device with high inner $R_g$ has a higher temperature than the device with equivalent external $R_g$. The values obtained were plotted for each load configuration, obtaining the following curves:

Figure 9. Inductive load
Figure 10. Capacitive load

Figure 11. Resistive load
3 \( R_g \) impact for MOSFETs in buck/buck-boost configurations

Let's consider now the \( R_g \) impact on MOSFET switching behavior and thermal management in a real customer application. In particular, the MOSFET is used as a control or synchronous switch in a single-phase synchronous buck or buck-boost converter. These topologies are widely used in the computer and peripherals sector, when a fixed output voltage is generated from a regulated input voltage by adjusting properly the device turn-on time and therefore the converter duty cycle \((D = \frac{V_{OUT}}{V_{IN}})\). The output voltage feeds various system blocks (i.e. CPU, DDR, etc.…).

Too high \( R_g \) values can affect the MOSFET performance in the application, particularly:

a) Rising/falling edges slowing down.

b) LS false turn-on risk enhancement.

c) Driver/MOSFET temperature increase.

3.1 Rising/falling edges slowing down

Initially, let's consider a buck-boost converter (Figure 12), that lowers the input voltage (5 V) generating -5 V as \( V_{OUT} \). Ch2 (drain voltage) and Ch3 (gate voltage) indicate the probe placement. Two equal FETs, with different \( R_g \) values, are compared as the control switch.

Figure 12. Buck-boost converter

In Figure 13 and Figure 14 respectively, the waveforms for a “good” part (standard \( R_g \) value) and “bad” part (high \( R_g \) value) are illustrated.
Looking at the green trace (Ch2, drain voltage) in Figure 13, the input voltage (5 V) and the output voltage (-5 V) are clearly evident, together with the oscillations due to the converter DCM. On the other hand, in Figure 14 the “high $R_g$” device shows an incorrect behavior. In fact, the converter works in “overcurrent protection mode” when the 5 V is pulled down to 3.5 V and the output voltage has an incorrect value. In Figure 15, more switching cycles for the “bad” part are shown.

Analyzing the drain voltage waveform, the slow drain falling edge indicates that the FET is not turned off although the gate voltage is high (P-channel device). It is evident that the slow falling-down of the FET drain voltage becomes more dangerous during steady-state conditions, when the device turns on and off with a certain $f_{sw}$. In fact, the device cannot be turned-off effectively at each switching cycle. So, this slow MOSFET turn-off causes an undesired switching loss increase, and therefore, a power dissipation and temperature rise, finally producing the device failure.
3.2 Synchronous buck converter for motherboard: LS false turn-on risk enhancement

In Figure 16, the schematic of a single-phase synchronous buck converter is shown (V\text{IN} = 12\, \text{V}, \, V\text{OUT} = 1.5\, \text{V}, \, f\text{SW} = 500\, \text{kHz}, \, I\text{OUT,MAX} = 30\, \text{A}); Q4-6 is the high-side device, while Q1-3 is the low-side FET.

![Figure 16. Schematic of a single-phase synchronous buck converter](image)

The LS device can be affected by the so-called “LS false turn-on,” which can be potentially dangerous for the MOSFET itself and the reliability of the entire converter. When the high-side turns on, a high dV/dt appears across the low-side device (Figure 17). Through the Miller capacitance, a capacitive current flows (i\text{C} = C_{gd} \cdot \frac{dV}{dt}) coupling to the LS gate pin. If the total resistance formed by the intrinsic, external, and driver resistances is much lower than the equivalent MOSFET impedance between gate and source, this current flows through the above mentioned resistive path. This causes a spurious bouncing across gate and source MOSFET pins; if this induced voltage is higher than minimum threshold voltage, the LS can be partially turned on, creating a low-resistance path between supply voltage and GND. In other words, undesired power dissipation is present in each switching cycle, worsening the converter efficiency, thermal management, and reliability.

![Figure 17. CdV/dt false turn-on event](image)
In order to evaluate the $R_g$ impact on the LS false turn-on, two identical FETs (same silicon) but different $R_g$ values ($1.5 \, \Omega$ vs. $4 \, \Omega$) are mounted in the converter shown in Figure 16. Figure 18 and 19 illustrate the LS gate-source waveforms for the two LS FETs.

Comparing the two images, the “high $R_g$” MOSFET has a higher and larger (over the minimum threshold voltage) spurious bouncing than the standard device. This causes a “shoot-through” event (for each switching cycle), that increases the converter power losses. So, higher device (MOSFETs and driver) temperatures are measured when “high $R_g$” samples are mounted on the board in the low-side position, as shown in the thermal captures of Figure 20 (standard part) and Figure 21 (high $R_g$).

3.3 Synchronous buck converter for HDD: LS false turn-on risk enhancement

Figure 22 shows (inside the light blue rectangle) a single phase synchronous buck converter, which provides $1.18 \, \text{V}$ as output voltage, with $1.1 \, \text{MHz}$ as switching frequency.
In this board two different sample categories of the same device (20 V / 5A SLL Vth) are compared: the “good” parts, with standard $R_g$ (aligned to datasheet values) and the “bad” parts, with high $R_g$ values. The dynamic parameters are reported in Table 2 and 3.

**Table 2. Dynamic parameters for “good” part**

<table>
<thead>
<tr>
<th>$C_{iss}$ [pF]</th>
<th>$C_{oss}$ [pF]</th>
<th>$C_{rss}$ [pF]</th>
<th>$R_g$ [Ω]</th>
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<td>375.14</td>
<td>173.54</td>
<td>46.08</td>
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**Table 3. Dynamic parameters for “bad” part**

<table>
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<tr>
<th>$C_{iss}$ [pF]</th>
<th>$C_{oss}$ [pF]</th>
<th>$C_{rss}$ [pF]</th>
<th>$R_g$ [Ω]</th>
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<td>335.14</td>
<td>172.48</td>
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The main analysis key points are:
- Switching behavior evaluation and waveform capture
- Driver/MOSFET thermal measurements at board startup.

In Figure 23 and Figure 24, the $V_{DS}$ and $V_{OUT}$ waveforms for “good” and “bad” parts, respectively, are illustrated.
As shown in the previous images, the “bad” part shows an incorrect output voltage value (0.473 V vs. 1.18 V), due to the different MOSFET switching speed and switching times. The thermal measurements are made at the board startup and no load conditions, using a thermal camera to detect MOSFET and driver temperatures. Figure 25 and Figure 24 show, respectively, the images for “good” and “bad” parts.

For the “good” sample, the MOSFET temperature is 35.4 °C, while for the “bad” device its 87.4 °C. A similar temperature increase is detected for the driver: 37.8 °C for the first configuration and 73.4 °C for the second one. It is obvious that such high $R_g$ values cause:

- MOSFET temperatures to rise due to switching loss enlargements (the higher the $R_g$, the longer the MOSFET switching times)
- Driver temperature increases because of gate drive losses rising.

Unfortunately, full load conditions haven’t been reached due to the quick device temperature increase till maximum rating.
4 Conclusions

From the experimental results, we can summarize that a higher $R_g$ value not only worsens the MOSFET's working conditions, by increasing the temperature and switching losses, it also worsens application efficiency and working conditions by fully modifying the device's switching behavior and doesn't achieve the converter values set by design. Moreover, a higher $R_g$ heavily affects the driver/PWM controller safety working condition, forcing it to sustain a higher temperature, as well as dissipating a larger power to charge up the MOSFET input capacitance. It is also dangerous for producing the cross conduction that may cause system disruption by the static $dV/dt$. 
5 Revision history

Table 4. Document revision history

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<td>Initial release.</td>
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