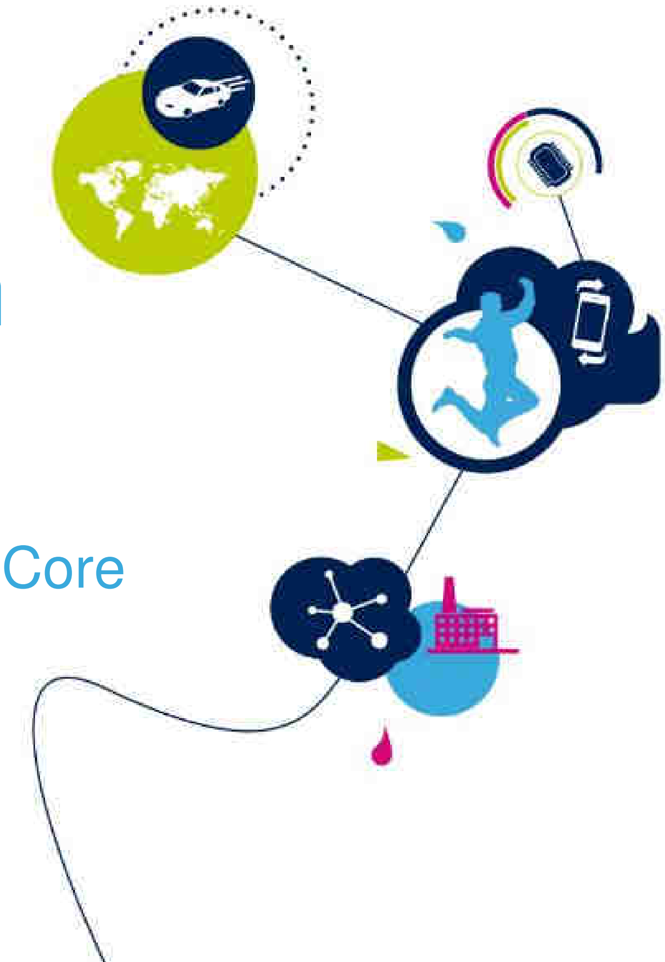
A Breakthrough Innovation in MEMS Sensors

Introducing LSM6DSOX, iNEMO 6DoF inertial measurement unit (IMU), with Machine Learning Core

Jay Esfandyari



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Technology Tour 2019

Schaumburg, IL | April 25

Agenda

- Artificial Intelligence in IoT
- ST Smart Sensor: 6-axis IMU with Machine Learning Core
- Why new sensors solutions are attractive?
- Solutions and Comparisons
- Tools
- Conclusions

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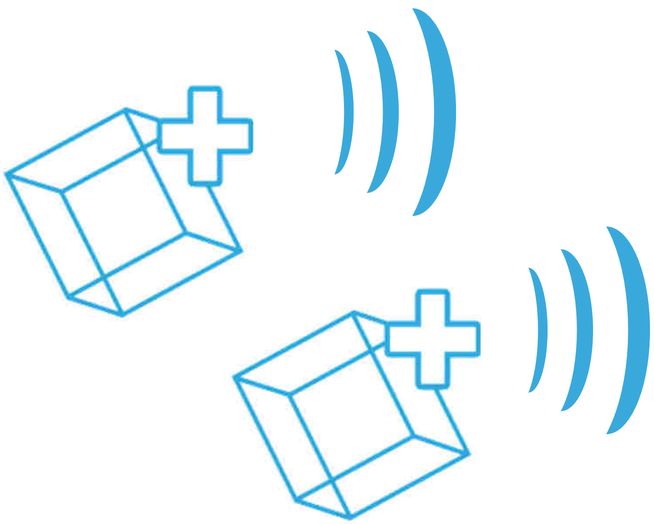
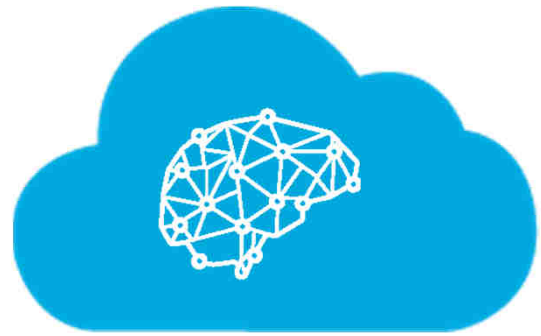
Artificial Intelligence in IoT





Logic Programming

Decision Tree

Machine Learning

A.I.

Search Algorithms

Deep Learning

Neural Networks

Data Mining

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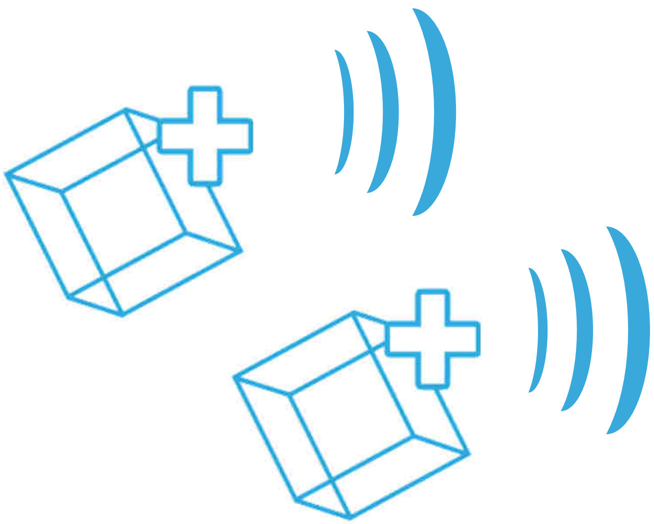
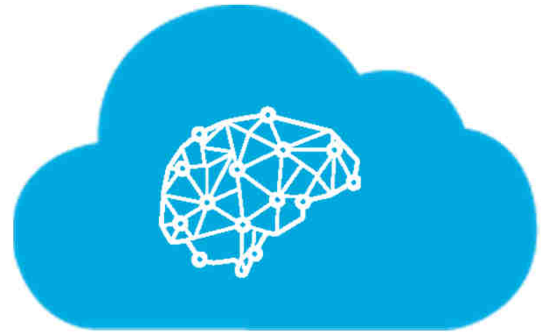
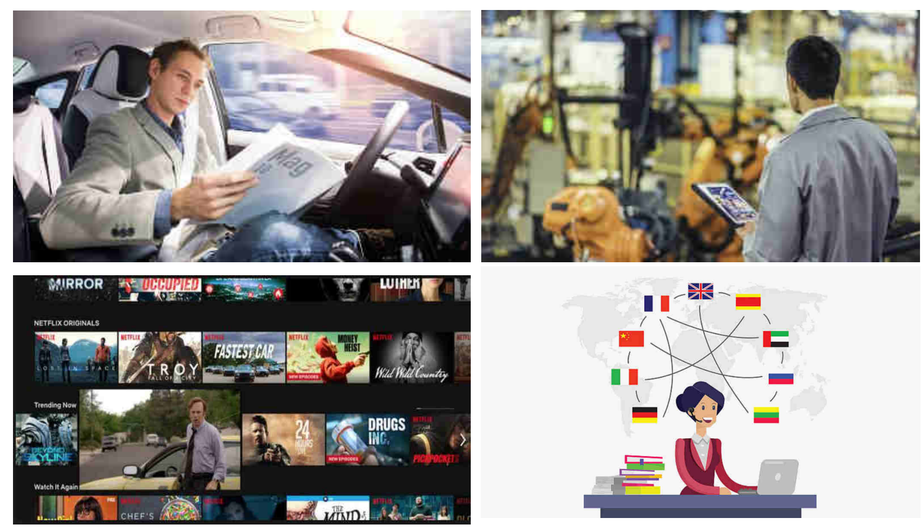
Artificial Intelligence in IoT

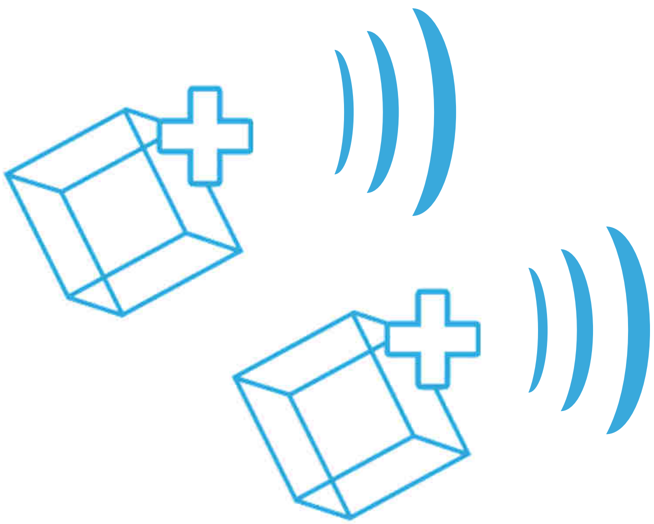


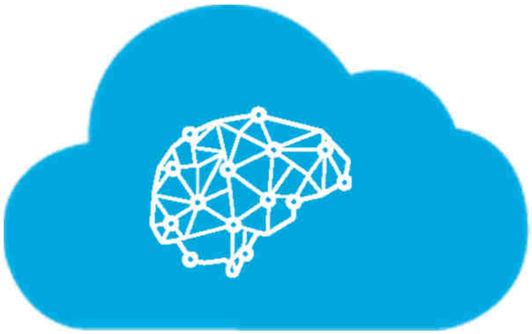




Analysis of vast
amount of information

Artificial Intelligence in IoT



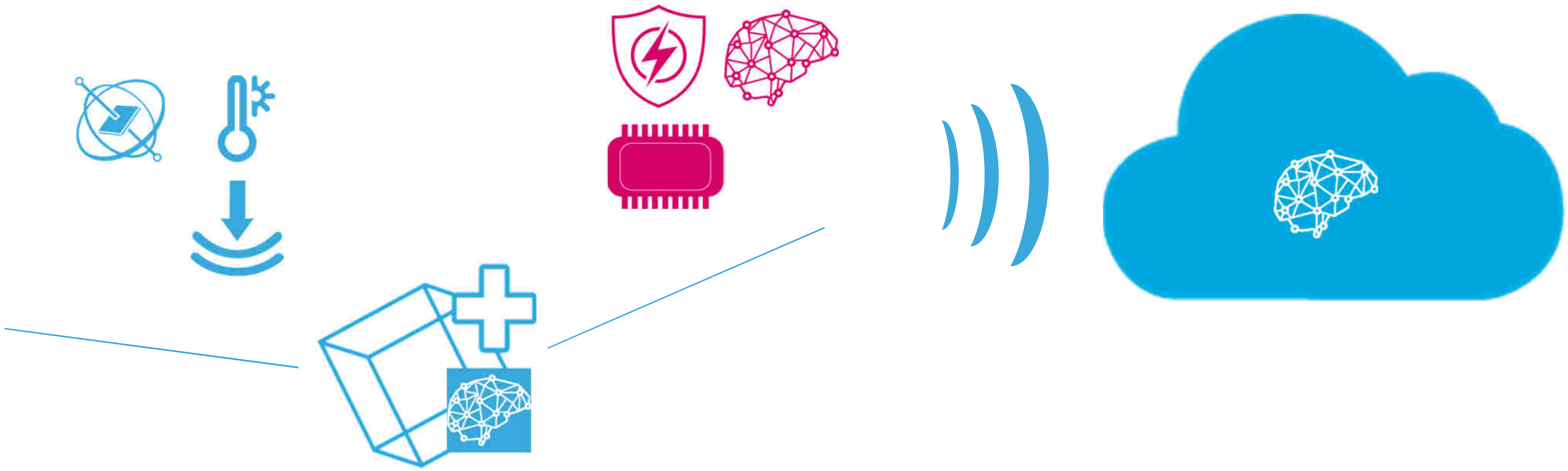


Centralized A.I. Architecture

Artificial Intelligence in IoT

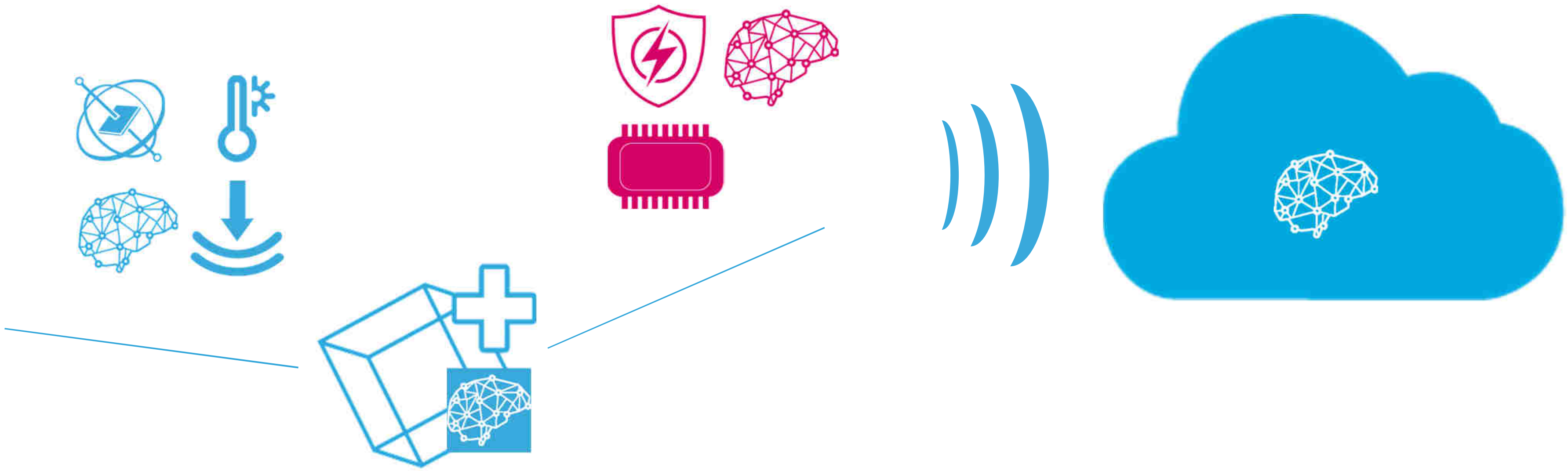
Edge A.I. Architecture

Artificial Intelligence in IoT



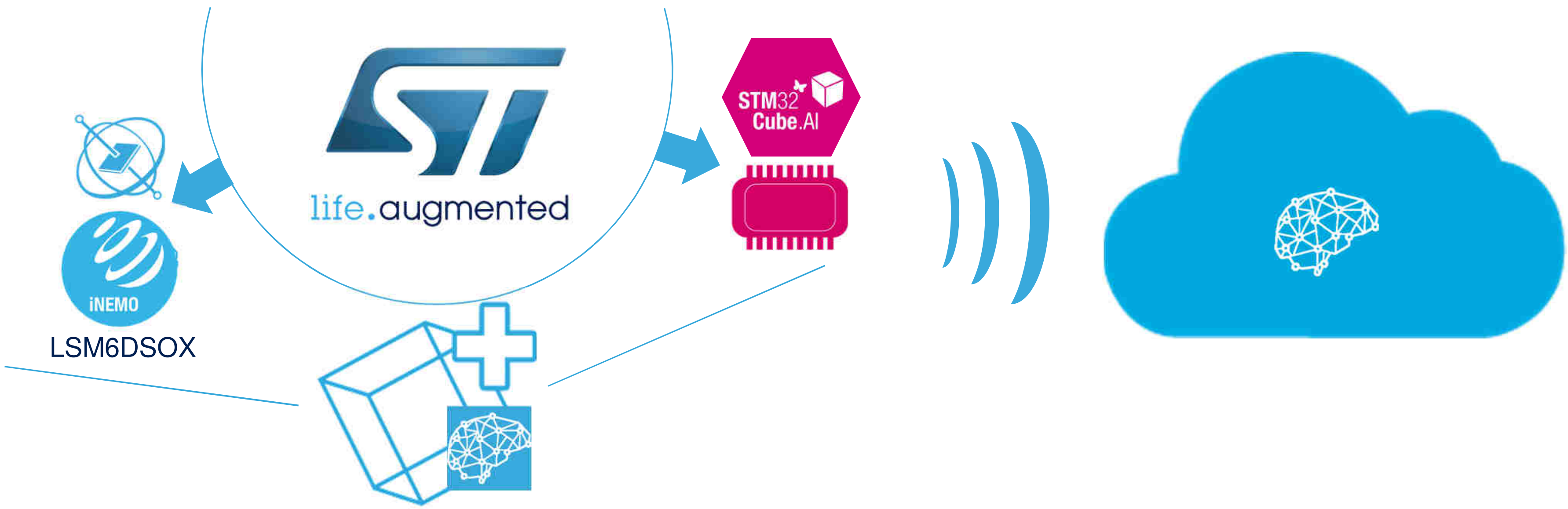
Edge A.I. Architecture

Artificial Intelligence in IoT

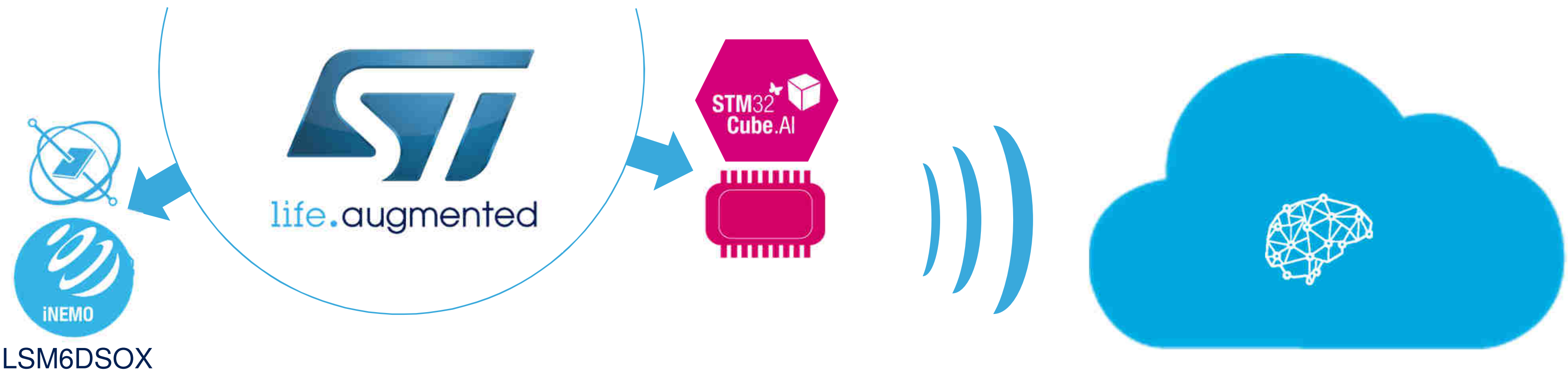


Edge A.I. Architecture

Artificial Intelligence in IoT



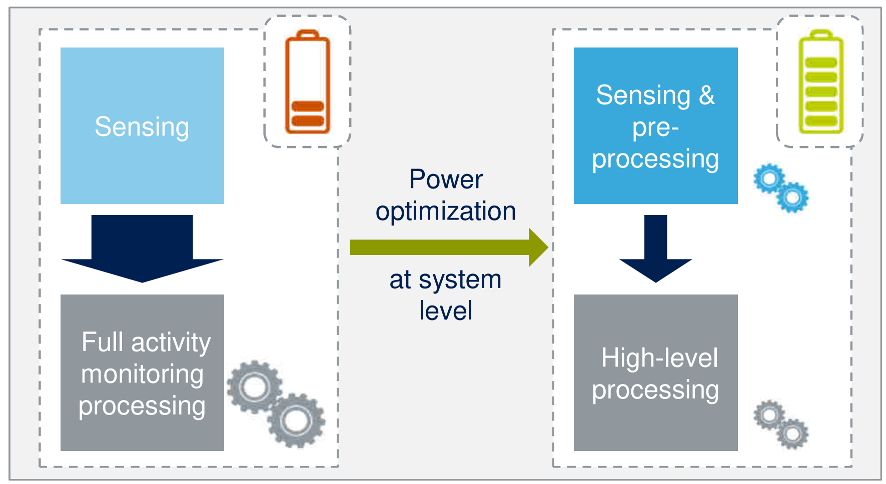
Artificial Intelligence in IoT



Data processing inside the sensor:	Data processing inside the STM32:	Data processing inside the Cloud:
+ Local processing + Real time analysis + Reduced cost of bandwidth + Ultra Low Power + Intrinsic Security = Configurable Logic - Simple computation (Dec. Tree)	+ Local processing + Real time analysis + Reduced cost of bandwidth = Low Power = Improved security = Configurable Logic = Std Computation (Neural Net.)	+ Advanced Computation + Availability of Wide Amount of Data + Continuous Algo Improvement = Remote processing - Data Transfer Latency - High cost of bandwidth - Very High current consumption

LSM6DSOX Smart Sensor

The First IMU Sensor with a Machine Learning Core



LSM6DSOX Improved Performance

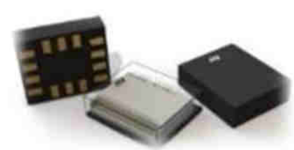
Improved Accuracy, Optimized System Power

High Accuracy
Noise: Gyro 3.8 mdps/√Hz
Accelerometer 70 µg/√Hz

Low Current Consumption
0.55mA HP combo
-15% vs. LSM6DSL/M

New ultra low power Axl:
14uA @100Hz ODR

LSM6DSO/X



2.5x3x0.86 mm

Sensor HUB
& compressed 9kB FIFO

Embedded Pedometer 2.x
WeChat Compliant

OIS Stabilization Core

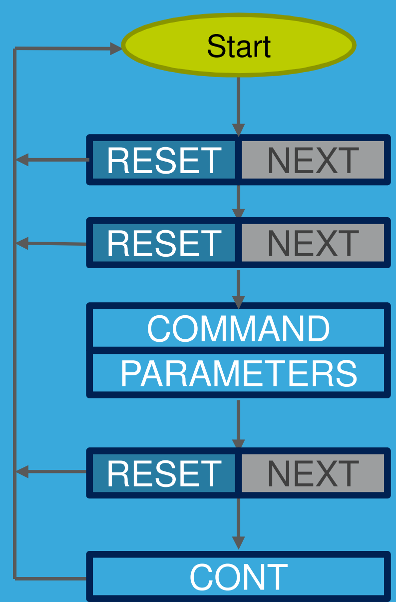
New Standard Protocol
I3C / I2C / SPI

Finite State Machine &
Machine Learning Core

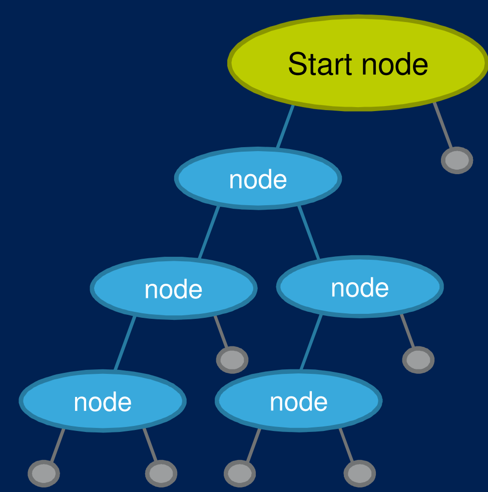
LSM6DSOX Smart Sensor

The first Smart Sensor embedding:

Finite State Machine



Machine Learning Core



FSM and MLC allows sensors to process data with reduced help of a host Microcontroller

Deductive vs. Inductive algorithms

Inertial Algorithms Overview

DEDUCTIVE	INDUCTIVE
Hypotesis	Observation
↓	↓
Rules	Model
i.e. Wake Up	i.e. Activity Rec
Finite State Machine	Machine Learning Processing

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Finite State Machines overview

LSM6DSO/X - Finite State Machine

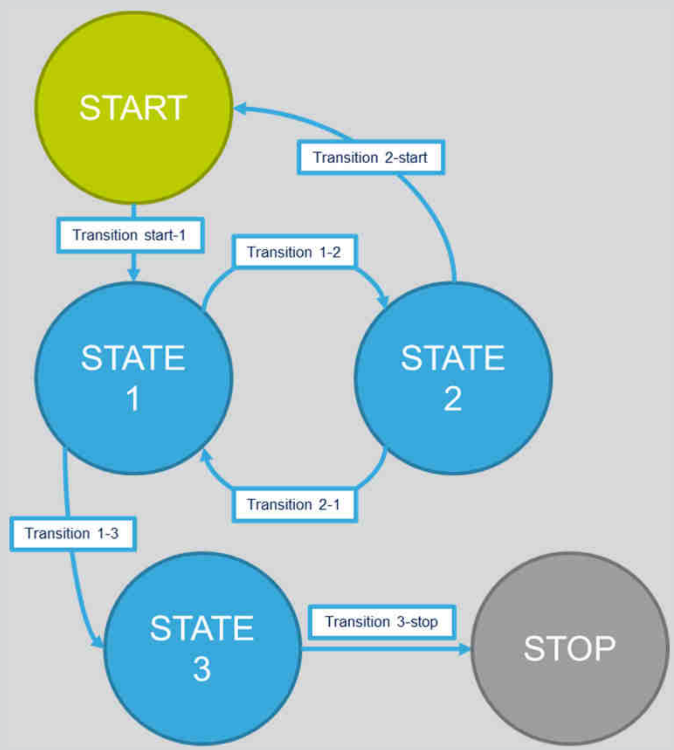
FSM is composed by a series of states, configurable parameters/resources and variables

Possibility to implement up to 16 independent FSM

FSM are executed simultaneously or sequentially

FSM can use data from accelerometer, gyro or an external sensor

FSM outputs:
- Interrupt
- Source information



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Finite State Machine Structure

In LSM6DSOX

Sensors Data
- Accelerometer
- Gyroscope
- External Sensor
- MLC Filtered Data

Data Section
- Fixed Data
- Variable Data

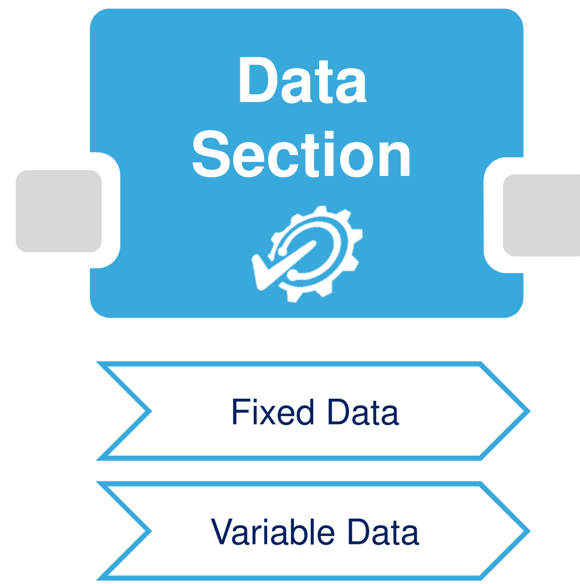
Instructions
- Conditions
- Commands
- Parameters

Finite State Machine Structure

In LSM6DSOX

There are 2 Data Sections in each FSM program:

- The **Fixed Data Section** of the program is used to specify the resources that are needed in the instructions section. Resources examples:
    - Thresholds
    - Timers
    - Masks
    - Hysteresis
    - Decimation factor
- The **Variable Data Section** is used to define all the values for the used resources.



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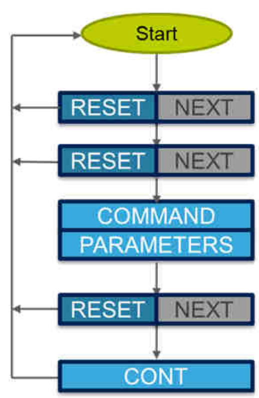
Finite State Machine Structure
In LSM6DSOX

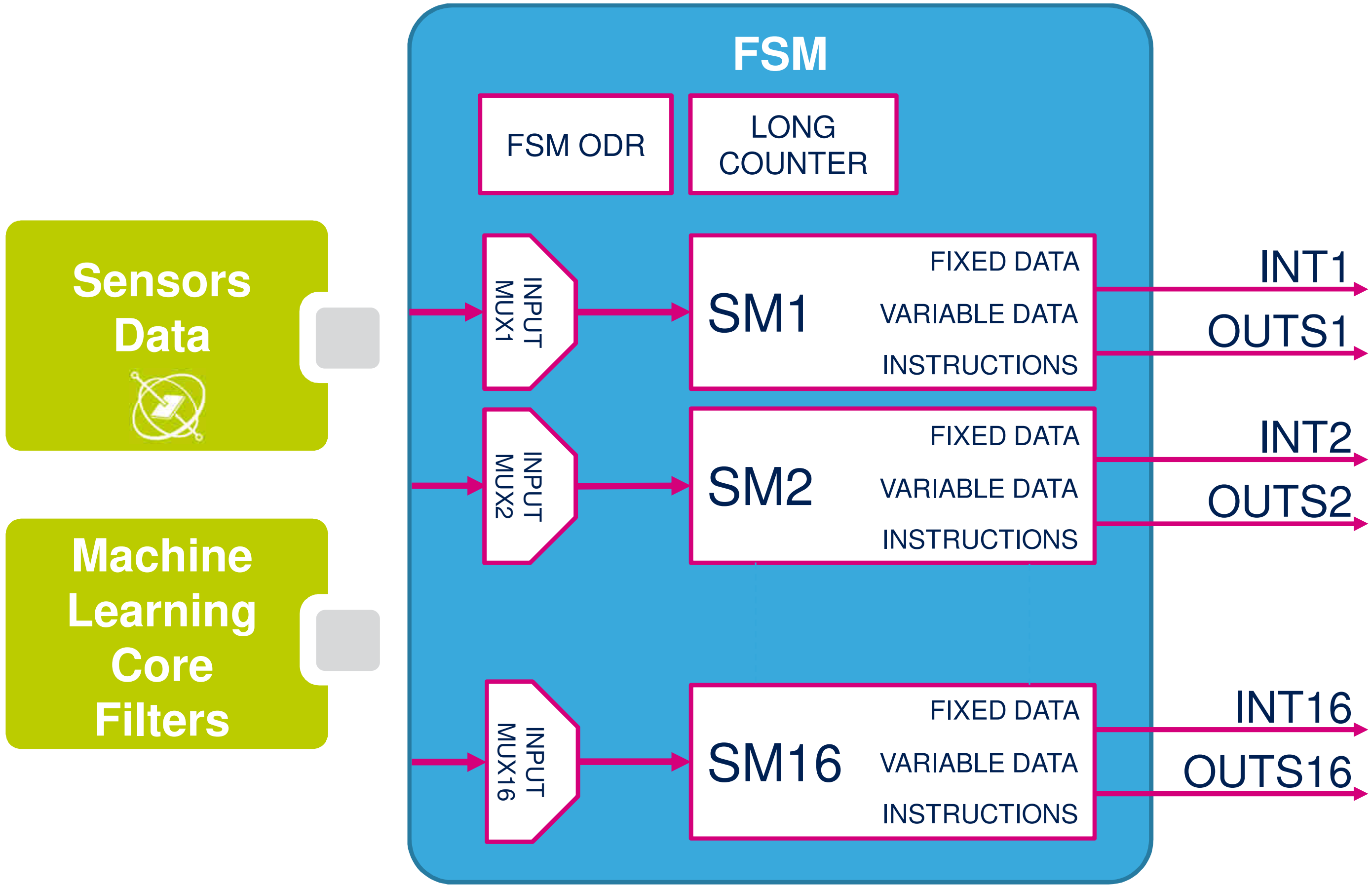
In the Instruction Section the user defines the algorithm by using available commands and conditions:

- **Commands** can be followed by parameters. Once executed the program pointer is set to the next command/condition line that is immediately evaluated.
- **Parameter** are application masks, threshold and timers.
- **Conditions** can be:
  - Reset. If true → pointer set to last Reset Point
  - Next. If true → pointer set to Next Line
  - None → interpreter keeps evaluating the same line when next sample occurs



Finite State Machine Blocks

Summary

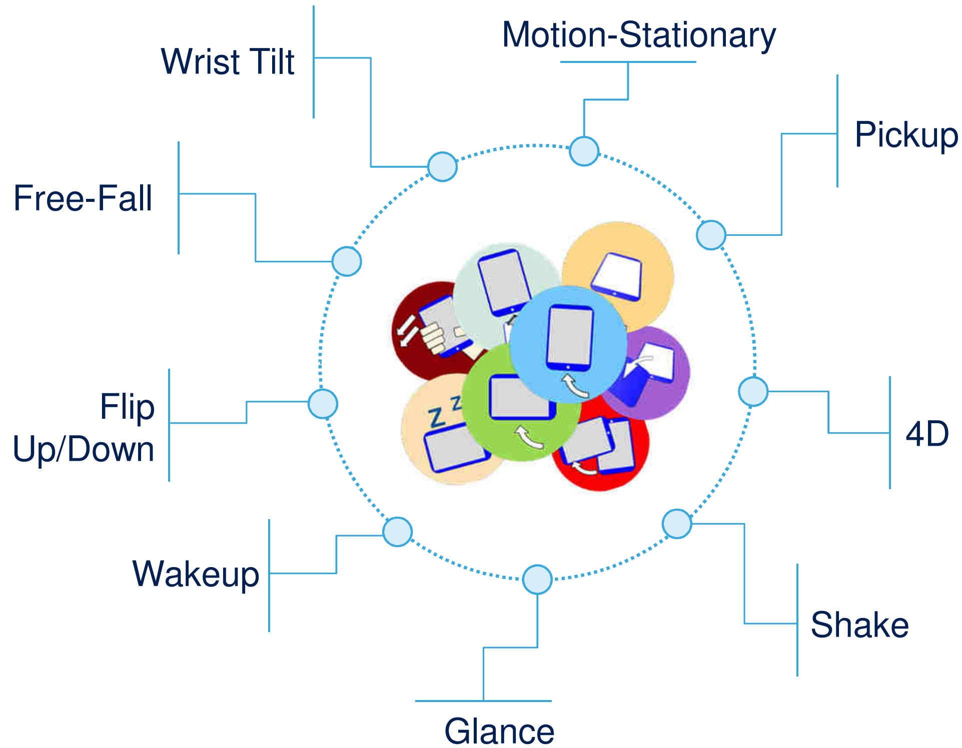


Finite State Machine

Examples of Libraries

Exploiting Finite State Machine capabilities

- High Efficiency (Computation Resources, Power)
- High Customization level
- Library of example gestures available:



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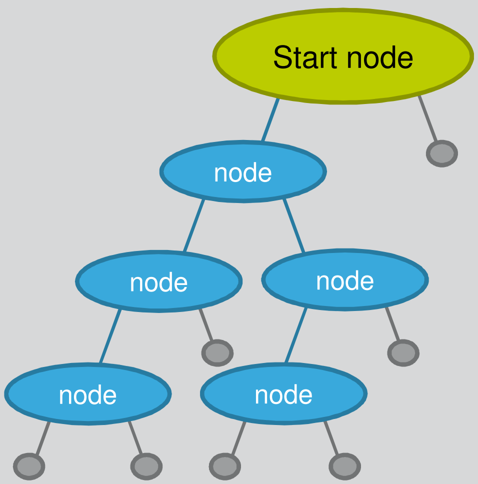
Machine Learning Core overview

LSM6DSOX - Machine Learning Core



MLC is a programmable logic.

LSM6DSOX embeds a Decision Tree Logic composed by a series of configurable nodes.

Each node is characterized by one “if-then-else” condition.

Up to 8 decision trees can be configured to run simultaneously in LMS6DSOX.

Machine Learning Configuration Flow

After the definitinition of the classes to be recognized: running, walking, car,... Capture data …

1

User defines Classes to be recognized

2

Collect data Logs for each class and label data

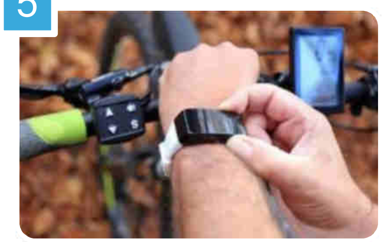
3

Select Features that best characterize the identified classes

4

Machine Learning tools generate program for LSM6DSOX based on Logs and Features

5



Configure the LSM6DSOX and run the application

Machine Learning Core (MLC)

In LSM6DSOX

Sensors Data

- Accelerometer
- Gyroscope
- External Sensor

Computation Block

- Filters
- Digital Pre-defined Features

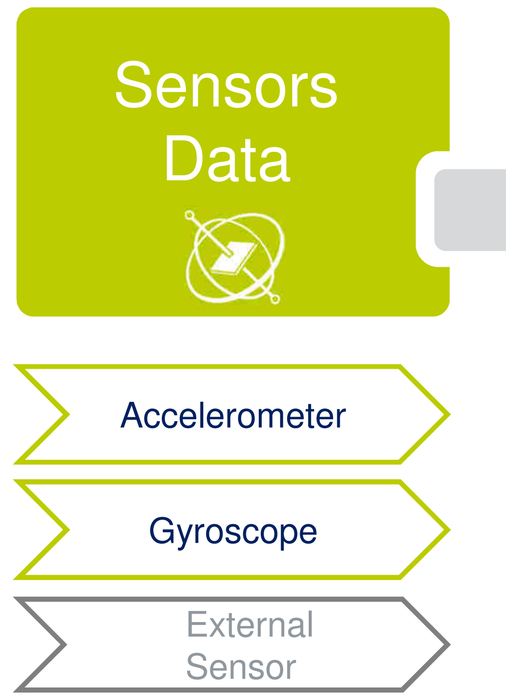
Decision Tree

- Meta-classifier
- Node

Machine Learning Core (MLC)

In LSM6DSOX

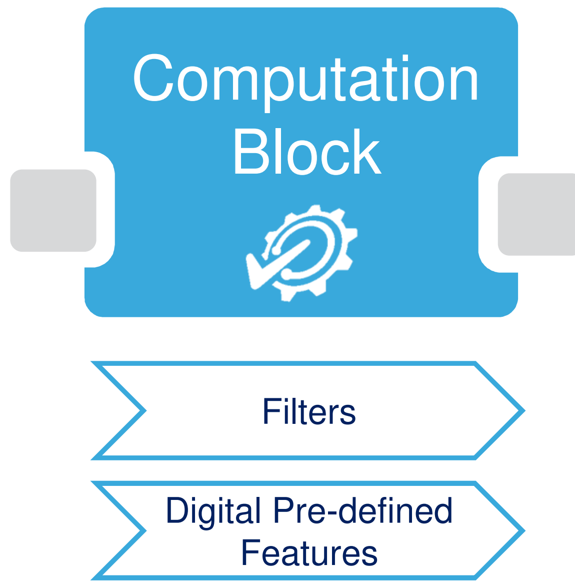
- Wide set of Inputs available:
  - **Accelerometer** → $[a_x\ a_y\ a_z\ ], [a_v], [a^2{}_v]$
  - **Gyroscope** → $[g_x\ g_y\ g_z\ ], [g_v]\ , [g^2{}_v]$
  - **External sensor** → $[m_x\ m_y\ m_z\ ], [m_v], [m^2{}_v] (i.e. magnetometer)$
  - **Magnitude** → $V = \sqrt{X^2 + Y^2 + Z^2}$



Machine Learning Core (MLC)

In LSM6DSOX

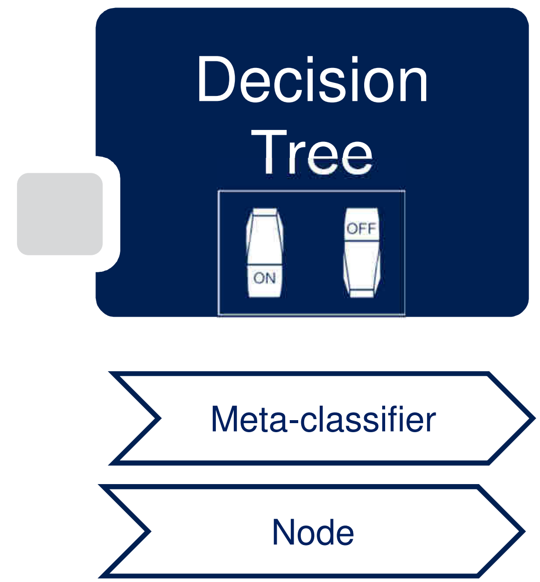
- Sensors data can be filtered with a 2nd order IIR **Filter**.
- **Features** are statistical parameter calculated from:
  - Input Data
  - Filtered Input Data
- Examples of features are: Mean, Variance, Energy, Peak to Peak, …

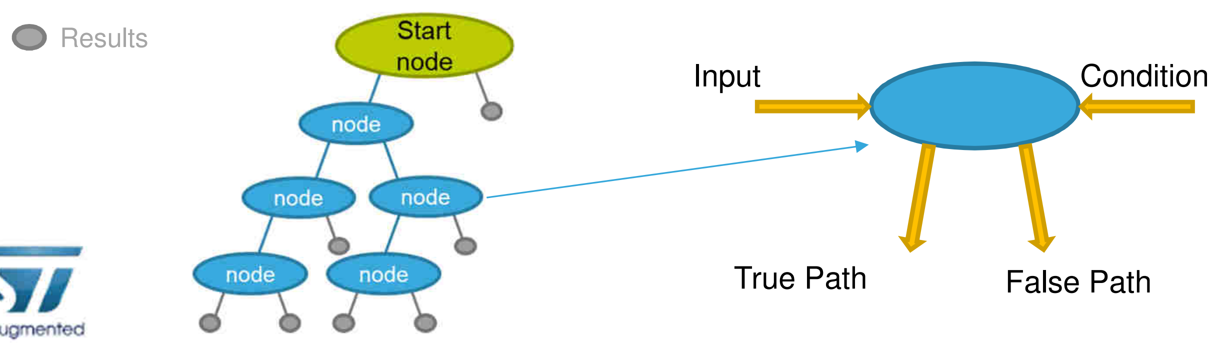


Machine Learning Core (MLC)

In LSM6DSOX

- The **Decision Tree** is a predictive model built from training data. The outputs of the computation blocks are the inputs of the decision tree.
- Each **Node** is characterized by one «if-then-else» condition. Some examples of conditions:
  - Mean on Acc_X < 0.5 g
  - Variance on Gyro_Z < 200 dps
- Decision tree can either generate a result at every sample or filter the results with a **Meta-classifier**, to have a more robust output.



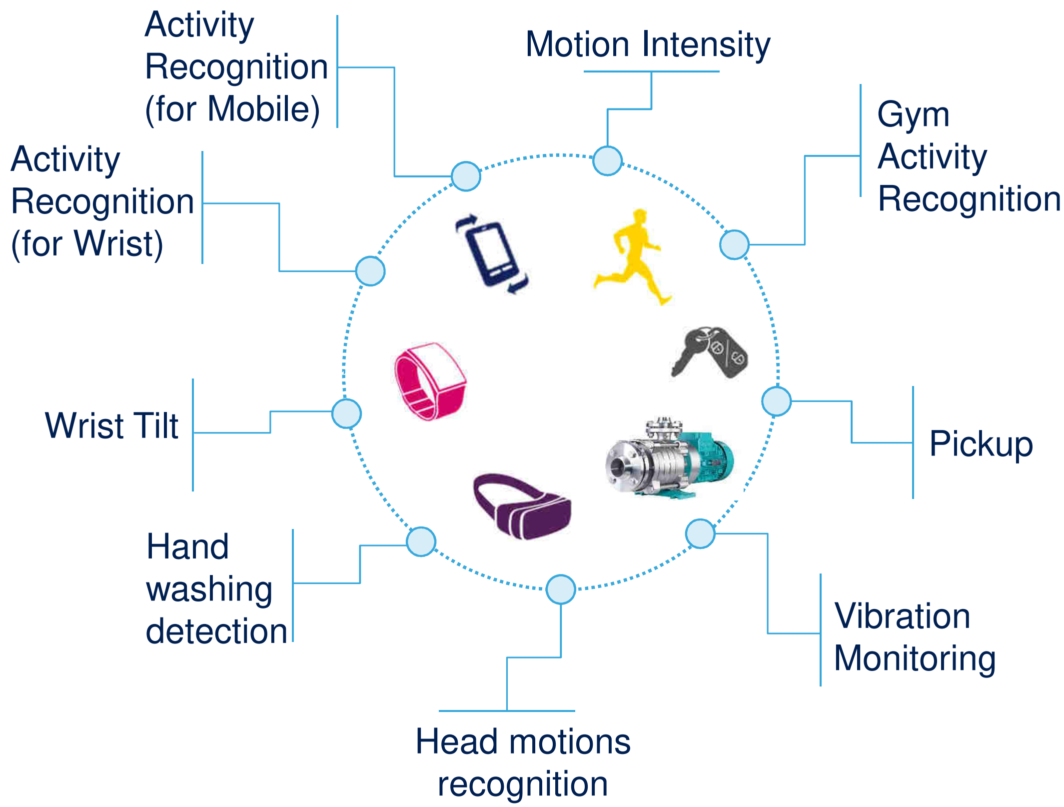


Machine Learning Core

Examples of Libraries

Exploiting Machine Learning Core capabilities

- High Efficiency (Computation Resources, Power)
- High Customization level
- Higher Complexity than FSM
- Example Libraries available:



Solutions Comparison

LS6DSO/X Power Consumption

Application Case examples

LSM6DSO / X

2.5x3x0.86 mm

LSM6DSOX Lowest Current Consumption

FSM and MLC are incredibly efficient in current consumption needs:

+ 3 µA for each Finite State Machine

+ 1-15 µA Machine Learning Core

as low power features to recognize customizable conditions and generate interrupts.

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Computational Current Consumption

Applications has been developed on Machine Learning Core

Algorithm	Sensors used	ODR	Number of decision trees	Number of nodes	MLC additional Current consumption
Vibration Monitoring	A	26 Hz	1	2	1 uA
Motion Intensity	A	12.5 Hz	1	7	1 uA
6D position recognition	A	26 Hz	1	8	2 uA
Activity Recognition for mobile	A	26 Hz	1	126	4 uA

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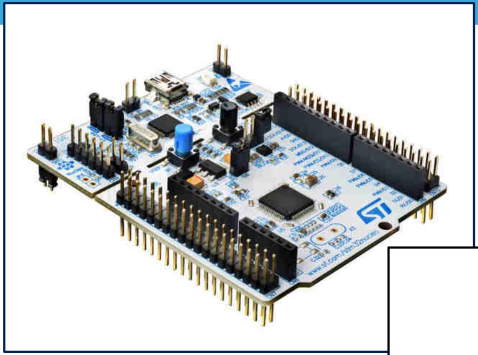
Application Case

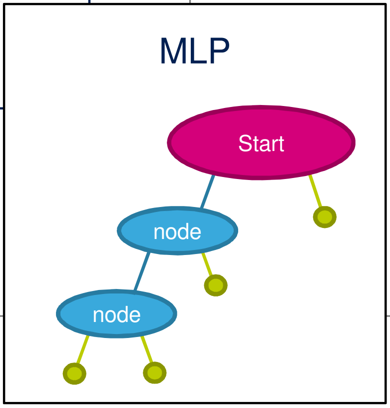
Same application has been developed on a low power microcontroller and on Motion Learning Processing

Activity Recognition Algorithm Classes

- Stationary
- Walking
- Fast Walking
- Jogging

…





Additional Current Consumption Required to Run the Application

Running on:	[µA]
Cortex-M3 STM32L152RE@32MHz	240
MLC on LSM6DSOX	7

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LSMDSOX Performance

Confusion Matrix of Activity Recognition in LSM6DSOX

Detected as ->	Stationary	Walking	Fast Walking	Jogging
Stationary	99.1%	0.9%	0.0%	0.0%
Walking	0.0%	99.4%	0.2%	0.0%
Fast Walking	0.0%	3.7%	95.9%	0.2%
Jogging	0.0%	0.6%	0.7%	98.5%

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Tools

ST MEMS sensor evaluation kit

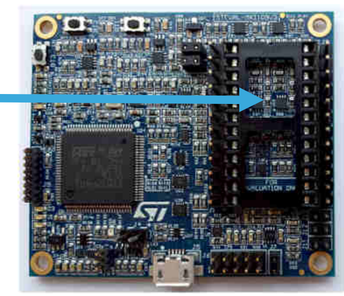
Professional Unico software Tool and ProfiMEMS

HW board

Sensor Adapter

STEVAL-MKI196V1

STEVAL-MKI109V3

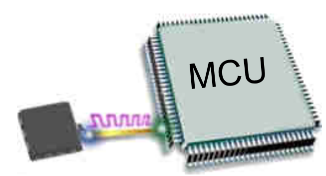


Software tool

Device Configuration

Runtime verification

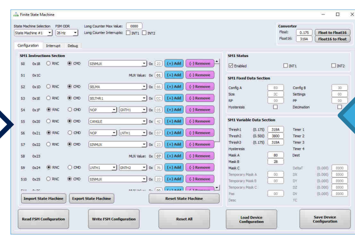
CONFIGURATION .UCF file



ST Unico GUI software

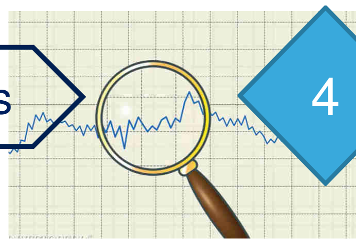
- Unico Lite GUI (or STSW-MEMS034) is an user interface that assists users to graphically and easily:
  - configure registers,
  - see the sensor's behavior on a chart,
  - export settings in a header file to include in the source code of an application.

1 Registers configuration



2 Data Collection

3 Pattern analysis



4 FSM Implementation

5 MLC Configuration

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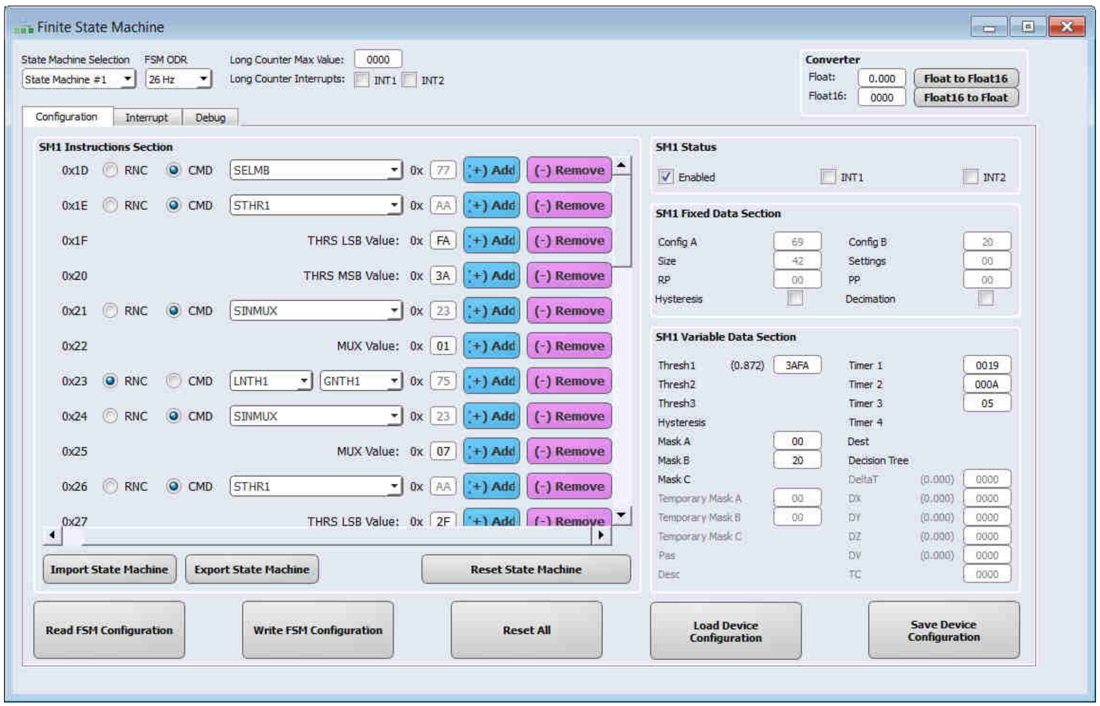
FSM examples

- ST provides FSM examples to start experimenting and test.



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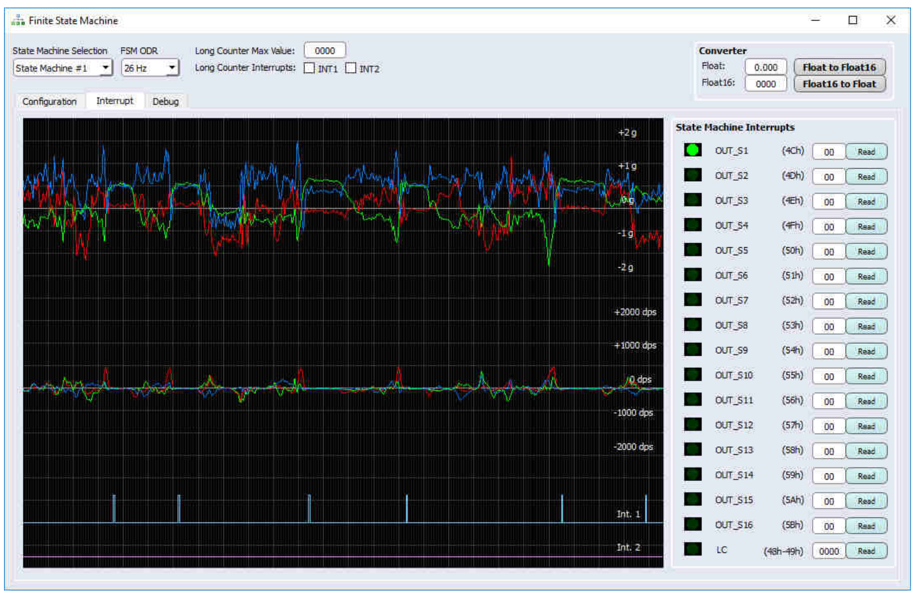
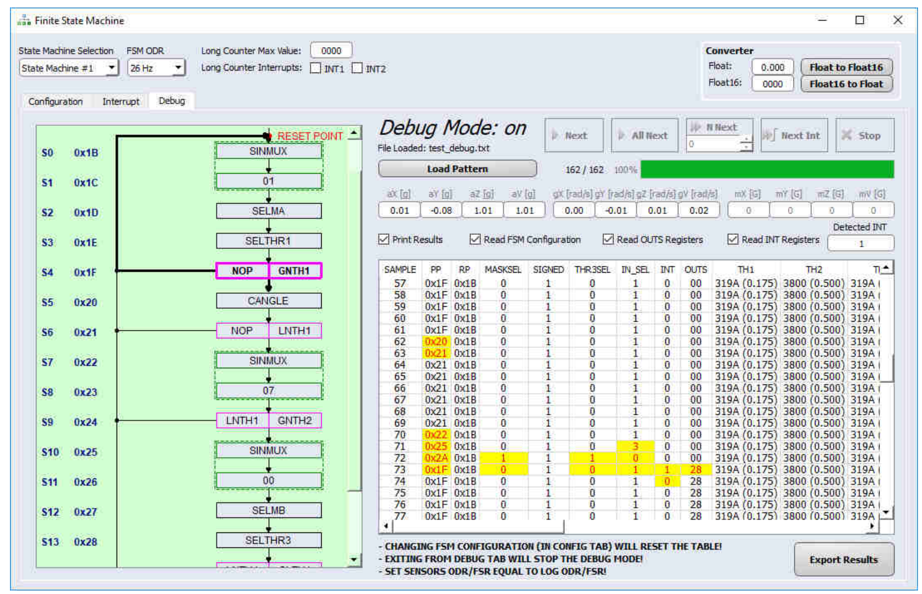
Fine Tuning

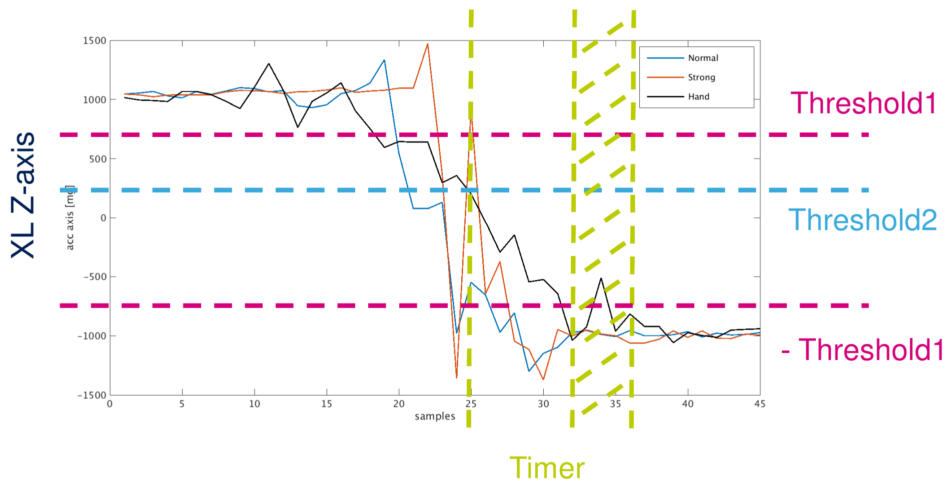
It is possible to debug in real time the FSM behavior playing back previously recorded data.

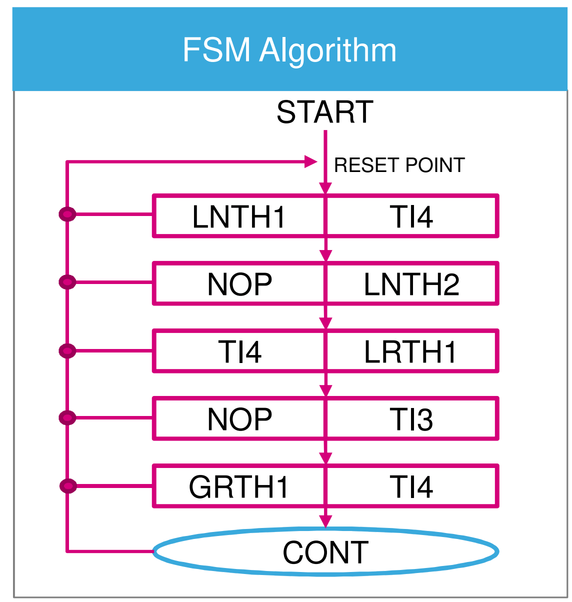




FSM capable of detecting when the user picks up a product

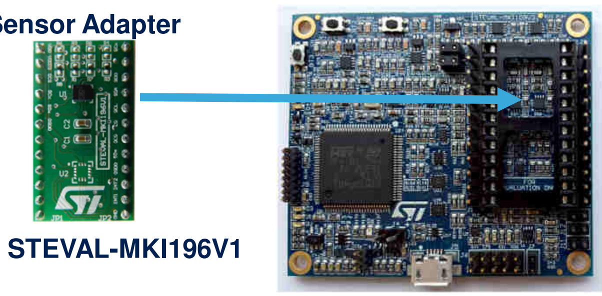
- Option 1: Programmers can load the example, write it onto the sensor, and start experimenting with it right away by changing threshold values or timers, for instance.
- Option 2: You can replay a series of events to see if the FSM would respond appropriately and throw an interrupt at the right moment.





Start Working with ProfiMEMS Board

- The best way to start experimenting and prototyping with the LSM6DSO/X is:
  - STEVAL-MKI196V1 daughter board.
  - STEVAL-MKI109V3 motherboard.



- Users need to plug the sensor board into the main board and connect it to a PC using the onboard USB port.

- Unico v8.0 supports FSM & MLC on Windows, Linux, Mac

Part Number	Software Version	Marketing Status	Supplier	Download
STSW-MKI109W	8.0.0	Active	ST	Get Software

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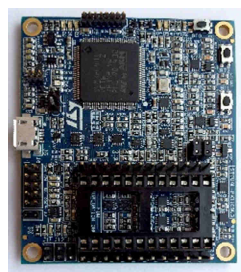
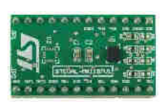
LSM6DSOX

Reference & Support

- LSM6DSOX ST datasheet
  - LSM6DSOX: LSM6DSOX.html
- Application Notes:
  - AN5272 (LSM6DSOX): DM00571818.pdf
  - AN5273 (LSM6DSOX Finite State Machine): DM00572971.pdf
  - AN5259 (LSM6DSOX Machine Learning Core): DM00563460.pdf
- Video Tutorial
  - Getting Started with LSM6DSOX: LSM6DSOX.html
- Boards:
  - Professional MEMS tool board - STEVAL-MKI109V3: mems-motion-sensor-eval-boards/steval-mki109v3.html



  - LSM6DSOX Adapter board - STEVAL-MKI197V1: mems-motion-sensor-eval-boards/steval-mki197v1.html



- Unico GUI package v8.0 - SW package for boards
  - STSW-MKI109W for Windows OS: evaluation-tool-software/stsw-mki109w.html
  - STSW-MKI109L for Linux OS: evaluation-tool-software/stsw-mki109l.html
  - STSW-MKI109M for Mac OS: evaluation-tool-software/stsw-mki109m.html
- MEMS Community
  - Community: community.st.com/s/group/CollaborationGroup
  - Q&A: mems-and-sensors

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Takeaways

- LSM6DSO/X completely transforms what a sensor can process without the help of a host microcontroller (MCU), thanks to the unique Machine Learning Core.
- Exceptional advantage in terms of Power consumption and Flexibility.
- ST is supporting your projects by refence design, dedicated tools and example libaries.

Thank You!

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Thank you

ST stands for

life.augmented

Everywhere microelectronics make a positive contribution to people’s lives, ST is there