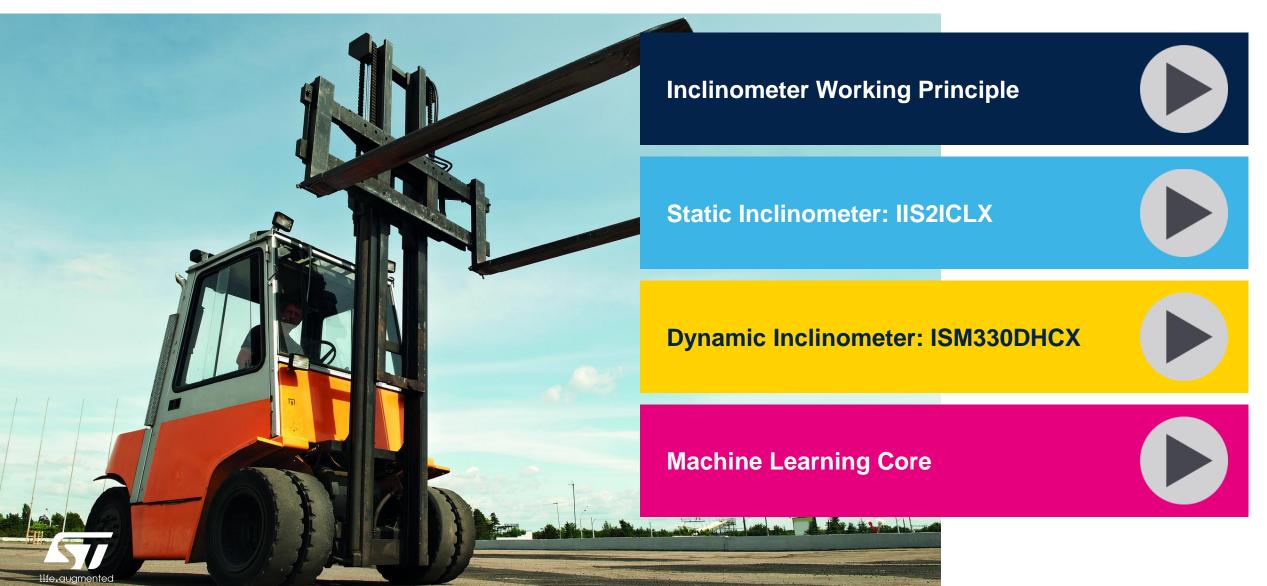


# Static and dynamic inclinometers for Industrial IoT applications





### Tilt measurement with an accelerometer

- Tilt measurement with an accelerometer is based on projection of the Gravity vector on its sensing axes
- An accelerometer does not measure only the gravitational acceleration, but any acceleration caused for example by:
  - Constant acceleration of the device
  - Centripetal acceleration due to a rotation of the device
  - Vibrations, for example due to a running machine or engine nearby
- Such accelerations cannot be easily differentiated from gravitational acceleration and can introduce measurement errors
- Therefore, accurate results require static or quasi-static conditions







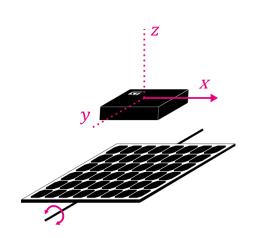




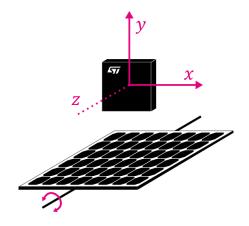
## Industrial application examples

#### **Inclinometer application examples** with possible sensor placements:

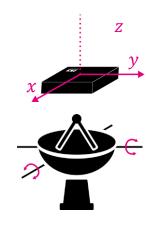
- 1. Tilt sensing of a solar panel that is rotated around a single axis
- 2. Dual-axis tilt sensing of an antenna



1-axis inclinometer



**2-axis** inclinometer vertical placement



**2-axis** inclinometer horizontal placement









## Static inclinometers in industrial applications

Antenna Leveling



Antenna pointing, platform leveling and stabilization

Robotics and IIoT



Robotics and Industrial automation

Inclinometers for industrial vehicles



High accuracy inclinometers for industrial vehicles, forklift, construction machines

Equipment Installation & monitoring



Installation and monitoring of equipment, tracker for solar panels

Leveling Instruments



Precise leveling instruments

Structural Health Monitoring



Building and infrastructure condition monitoring (inclination and low frequency vibration)











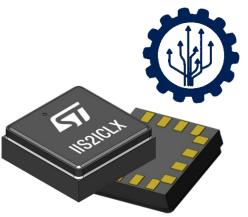


# IIS2ICLX High-accuracy 2-axis digital inclinometer

## High-accuracy, high-resolution, low-power, 2-axis digital inclinometer with embedded Machine Learning Core



- 2-axis, digital inclinometer, low power
- Top notch performance: resolution, accuracy, stability over temperature and time
  - Accuracy better than 0.5° over full temp. range and over time
- Programmable Bandwidth (-3dB) up to 260Hz
- Ultra-low noise (15  $\mu$ g/ $\sqrt{Hz}$ )
- Offset change vs Temp <0.075 mg/°C</li>
- Programmable Machine Learning Core & Finite State Machine to integrate Al algorithms and reduce power consumption at system level
- Extended operating temperature range: from -40 to +105 °C
- No Calibration required ST is testing and calibrating at Final Test
- ST Advantage: Accuracy, Resolution, High Stability & Repeatability



Ceramic Cavity LGA 5x5x1.7 16L









### Development tools for the IIS2ICLX



PC Application
Unico-GUI



Professional MEMS motherboard STEVAL-MKI109V3



PC Application and Software package

<u>Unicleo-GUI</u>

X-CUBE-MEMS1



**DIL24 adapter board**STEVAL-MKI209V1K (IIS2ICLX)









DIL24 adapter board STEVAL-MKI209V1K (IIS2ICLX)







STM32 NUCLEO & Industrial Sensor expansion board e.g., NUCLE-F401RE X-NUCLEO-IKS02A1









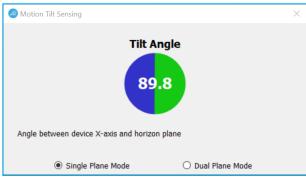


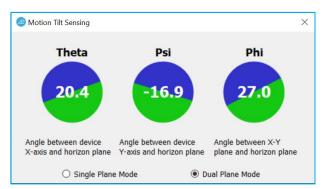
## Tilt Measurement Library for IIS2ICLX MotionTL2

- MotionTL2 is a dedicated library for 2-axis accelerometers that provides real-time information about tilt angles of the user device in single or dual plane mode
- The MotionTL2 sensor fusion library features:
  - Calculation of angles according to the desired mode
  - Configuration of knobs to mitigate vibration noise
- The MotionTL2 library is part of the X-CUBE-MEMS1 software package
  - Sample implementation is available for the <u>STEVAL-MKI209V1K</u> (DIL24 adapter board with the IIS2ICLX)
  - The implementation utilizes also MotionAC2 for calibration
- Available for ARM Cortex-M0+, M3, M4 and M7 architectures
- User Manual: UM2775













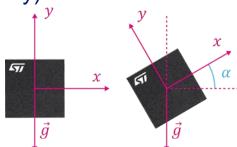




### Tilt Measurement Library for 2-axis AXLs Measurement modes

### Single plane mode

- Single plane mode provides the angle of X axis with respect the horizontal plane
- The reference position is when the X axis is in horizontal plane and Y axis is pointing up (towards the sky)

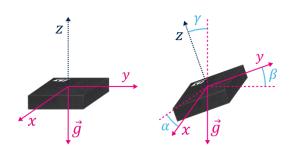


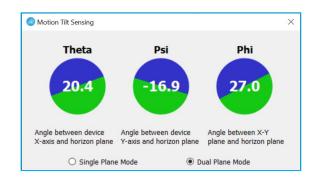
Range: [-180°, +180°]

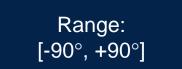


#### **Dual plane mode**

- This mode provides angles between the horizontal plane, X-axis ( $\alpha$ ) and Y-axis ( $\beta$ ), and angle between vertical axis and gravity vector  $(\gamma)$
- The reference position is when the X and Y axis are in the horizontal plane

















## Dynamic inclinometers in industrial applications

Industrial Vehicles



Inclinometers for industrial vehicles.
Mining, cranes

Robotics



Robotics

Autonomous Vehicles



Inclinometers for autonomous vehicles

Equipment Installation & monitoring



Antenna pointing and stabilization, platform leveling and stabilization











## 6-axis IMU with Machine Learning Core

## **Best-in-class accuracy 6-axis IMU with Machine Learning Core**



#### High Accuracy, Stability and linearity over temperature and time

- Gyro Offset vs T ±0.005 dps/°C (typ)
- Gyro Bias Instability 3°/hr (typ)
- Rate Noise Density 5 mdps/√Hz (typ)
- Axel Noise Density 60 μg/√Hz (typ) ODR up to 6.6kHz

#### **Programmability & digital features**

- Programmable Machine Learning Core & Finite State Machines to integrate Al algorithms
- 9 kB Embedded FIFO
- Sensor Hub

#### Configurability

- Angular rate range: from ±125dps up to ±4000 dps
- Axel Full Scale: from ±2g up to ±16g
- Low power and high performance modes

Extended operating temperature range from -40 to +105 °C





LGA 14L 2.5x3x0.86 mm

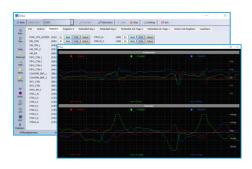








### Development tools for the ISM330DHCX



**PC Application Unico-GUI** 



**Professional MEMS** motherboard STEVAL-MKI109V3

#### ISM330DHCX's DIL24 adapter boards



STEVAL-MKI207V1







STEVAL-MKI210V1K











STM32 NUCLEO & **Industrial Sensor** expansion board e.g., NUCLEO-F401RE X-NUCLEO-IKS02A1











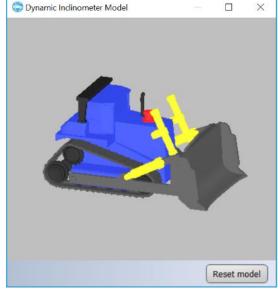


## Dynamic Inclinometer Library for ISM330DHCX MotionDI

- MotionDI is a library that provides real-time motion sensor fusion and tilt information - accurate estimation of device orientation even in presence of vibrations and motion using Kalman filtering
- The MotionDI sensor fusion library features:
  - Real-time 6-axis motion-sensor data fusion (accelerometer, gyroscope)
  - Computation of rotation vector, quaternions, gravity and linear acceleration data
  - Accelerometer and Gyroscope calibration
- Available for ARM Cortex-M3, M4 and M7 architectures
- Requires 6-axis IMU (ISM330DHCX)
- The MotionDI library is part of the X-CUBE-MEMS1 software package
  - An example implementation is available for following Nucleo boards:

STM32 development board	MEMS & Sensors expansion board
NUCLEO-F401RE	X-NUCLEO-IKS01A2
NUCLEO-L476RG	X-NUCLEO-IKS01A3
NUCLEO-L152RE	X-NUCLEO-IKS02A1







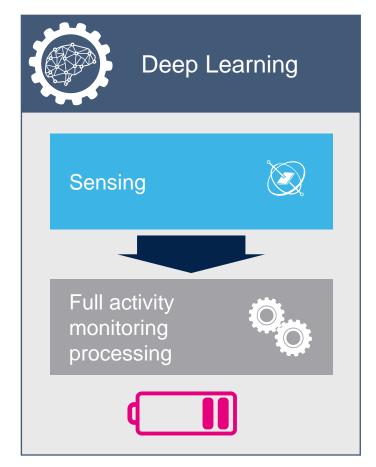




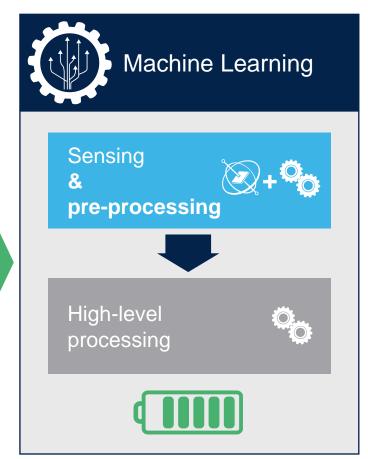


## From low power sensor to low power system

Machine Learning Core (MLC) for real edge computing enables high system flexibility



Power optimization at system level







- Higher computation power
- Lower power consumption
- Cost optimized solution

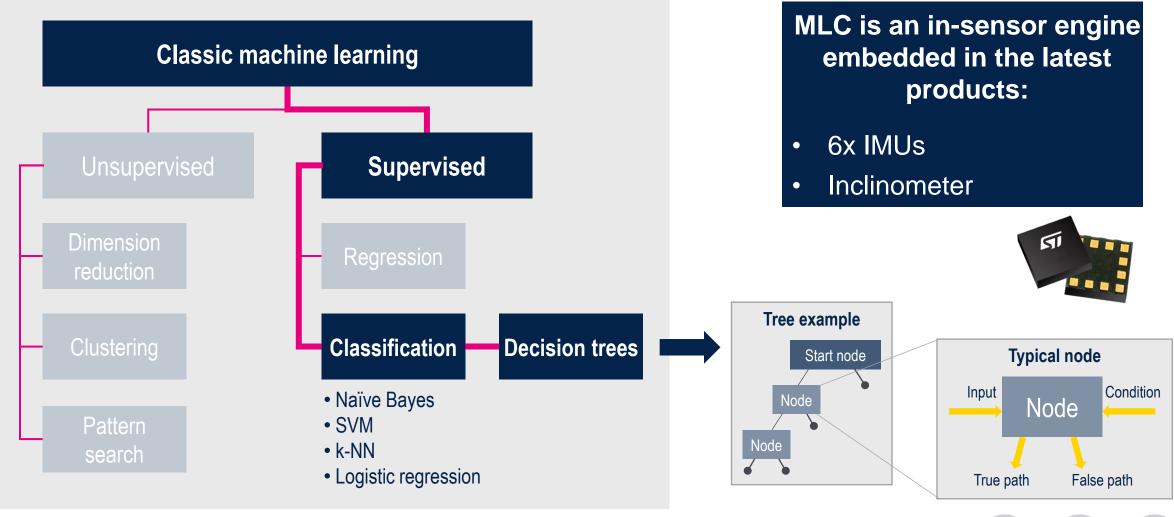
This is the added value!







### Machine Learning embedded in ST sensors











## Explore MLC resources and examples

Machine Learning Core landing page is the reference product resources and ML introduction to users:



https://www.st.com/MLC



 Decision tree examples are available online at the dedicated GitHub project for Machine Learning Core



https://github.com/STMicroelectronics/STMems\_Machine\_Learning\_Core







