

# AN1572 Application note

Power-down time-stamp function in serial real-time clocks (RTCs)

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## Introduction

## Power-down time stamp and the Halt bit

Many serial RTC devices from STMicroelectronics include a feature known as power-down time stamp. One register bit, Halt (HT), controls this feature. It is important that users understand three things about the HT bit in order to ensure correct operation of these devices.

- 1. Upon power-up, prior to writing any of the clock/calendar registers that is, prior to writing any address in the range 00h to 07h the user must first clear the HT bit by writing it to 0 (in bit 6 of address 0Ch).
- 2. Writing to addresses 00h to 07h (upon power-up) without first clearing the HT bit will result in the counters being overwritten, thus corrupting the time/date.
- 3. Before the HT bit is cleared, reads of the device will return the time of power-down (or, in the case of the M41T82/83/93, the time of the last read or write prior to power-down).

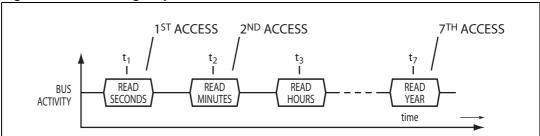
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## Address auto-increment and clock data coherency

When reading and writing the time/date, users should always use the address auto-increment feature of the serial interface. This ensures that the data is transferred coherently between the user and the counters. The time/date values read from the counters will all come from the same instant in time (or be written to the counters at the same instant in time). This does not apply to the non clock registers (eg, Flags or Watchdog registers), only to the clock/calendar registers at addresses 00h to 07h.

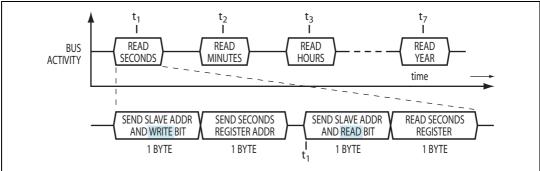
For example, without using auto-increment, the user must read the time using multiple accesses. On the first access, the seconds are read. Then, on the next transfer, the minutes are read. This continues until all the date and time values have been read as shown in the timing diagram below.

Figure 1. I<sup>2</sup>C timing sequence



These transfers, in more detail, are depicted below. To read the seconds, two 2-byte transfers occur in sequence. First, the processor sends the slave address and write bit followed by the register address (01h). Then the slave address is sent again, with the read bit, followed by a read of the seconds register. To read the minutes, this same sequence is repeated, but with a different register address (02h).

Figure 2. Detailed I<sup>2</sup>C timing sequence

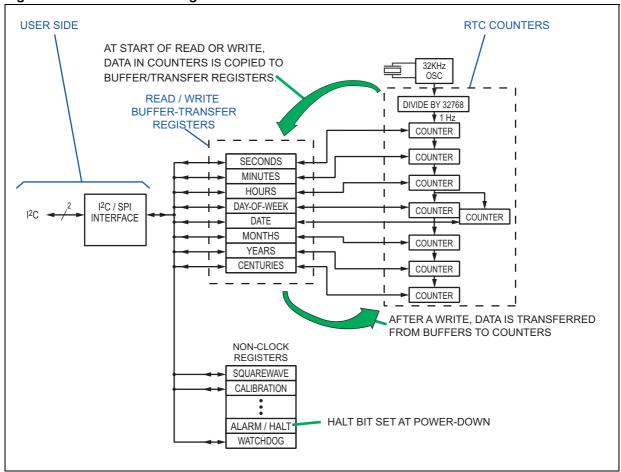


In reading the time this way, each byte comes from a different time. The seconds are from time  $t_1$ , the minutes are from time  $t_2$ , and so forth. That is, the seconds, minutes, hours, and so forth, are each read at a different instant in time. They are not coherent; they are not from the same instant in time.

Example: the user begins reading at 23:59:59  $(t_1)$ , and reads 59 as the seconds, then reads 59 minutes (at  $t_2$ ). Before the hours are read, the RTC increments such that the new time is 00:00:00. So the hours are read (at time  $t_3$ ) as 00 and not 23. Thus the time, when reassembled, will appear to be 00:59:59. It is incorrect by one hour. Thus, it is better to read all the time/date registers during the same transfer so that they come from the same instant in time. That way, the time read will be coherent.

## **Buffer/transfer registers**

Figure 3. Buffer/transfer registers



With a serial RTC, the user accesses the device via its serial interface, either I<sup>2</sup>C or SPI. Inside the RTC, the serial interface does not directly access the counters. Instead, a set of buffer/transfer registers sit between the serial interface and the counters. Reads and writes by the user will transfer data into and out of the buffer/transfer registers.

At the start of any  $I^2C$  (or SPI) transfer, the device copies the counters into the buffer/transfer register. Thus, when the user is reading the time/date, a fresh copy has been placed in the registers. More importantly, because all the counters are simultaneously copied into the registers, the time/date found in them is coherent - the seconds, minutes, hours, etc, all come from the same instant in time.

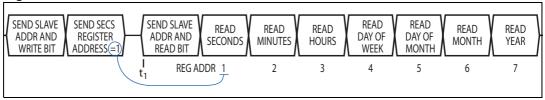
The buffer/transfer registers ensure coherency and that none of the counter values are incremented while the data is being transferred.

#### Address auto-increment

The address auto-increment feature of the serial interface allows the user to specify the first register address to be transferred, then, after each data byte is transferred, it automatically increments the address pointer to the next register. Thus, if the user attempts to read (or write) more than one byte during a transfer, the register address pointer will automatically point to the correct address for each successive byte transferred.

In the example below, the register address pointer is initialized to the seconds register address (1). During the subsequent read, the seconds value is transferred first, then the address pointer is incremented and the minutes are transferred next, and so forth, until all of the time/date registers have been transferred. This is done as one continuous serial bus transfer.

Figure 4. I<sup>2</sup>C address auto-increment feature



Using this feature, all the bytes in the buffer transfer registers are copied from the counters at time  $t_1$ , and then shifted out as a coherent date/time value.

Thus, the combination of buffer/transfer registers and address auto-increment enable reading and writing of the time/date to occur coherently no matter where in time the transfer occurs. Even if the counters increment during the transfer, the value shifted in or out is from the buffer/transfer registers and is not affected by the counters incrementing.

#### Writes

At the start of every transfer, read or write, the counters are copied to the buffer/transfer registers (that is, if the Halt bit is 0). Thus, when write data begins shifting into the buffer/transfer registers, it is overwriting a fresh copy of the time/date. At the end of the write cycle, all the buffer/transfer registers are copied back into the counters. If only one byte of the time/date is changed, then the corresponding counter is loaded with the new value while all the other counters are loaded with the same values they had milliseconds earlier at the start of the serial transfer.

That is, while only one byte was written by the user, all the counters were updated from the buffer/transfer registers. One counter received the newly written value while the other counters received the same values which had been copied from them milliseconds earlier at the start of the transfer. In short, the counter values were copied to the buffer/transfer registers, modified, and then copied back into the counters.

## Halt bit

Whenever the Halt bit (HT, bit 6 of address 0Ch) is a 1, the device halts the automatic copying of the counters to the buffer/transfer registers at the start of a read or write access. Thus, if the user writes the HT bit to 1, the buffer transfer registers will be frozen with the time/date that the HT was written. Subsequent reads of the date/time will continue returning the same value. Hence, with HT=1, at the start of a read/write sequence, the counters are not copied into the buffer/transfer registers. They remain frozen with the time at which HT was written to 1.

The HT bit is set to 1 automatically at power-down, when  $V_{CC}$  fails and the RTC switches to backup mode (except as noted below in  $\frac{M41T82}{83}$ ).

## Power-down time stamp

For most RTCs with battery switchover, the time/date counters are copied into the buffer/transfer registers at power-down. Thus, the time of power-down is frozen in the buffer/transfer registers. In applications where the duration of power outages needs to be known once power returns, the application can read the time of power-down and compare that to the current time to determine how long the device was in backup mode.

## M41T82 / 83 / 93

The M41T82/83/93 RTCs do not save the time/date at power-down. Thus, when  $V_{CC}$  fails and their HT bits are set, the buffer/transfer registers will contain the time of the last access prior to power-down rather than the actual time of power-down.

Applications needing to know the duration of an outage can work around this by implementing periodic reads of the RTC. For example, if the software is configured to read the RTC once per minute, upon power-down, the buffer/transfer registers will contain a time/date value within one minute of the actual time of power-down. Applications requiring more resolution can read the RTC more frequently.

#### Writes with the HT bit set

Whenever a write occurs to any of the RTC date/time register addresses (00h to 07h), all eight registers are copied back into the RTC counters. Regardless of whether one byte is written or several, all eight bytes are copied back into the counters. This only applies to the date/time addresses 00h to 07h.

If the HT bit is set, then the buffer/transfer registers contain the time of power-down (or the time of the last access for the M41T82/83/93). If a write occurs to any of these eight addresses, then the time of power-down (or last access) will be copied back into the counters. This has the effect of making the RTC appear to have stopped running at power-down.

Users should always clear the HT bit prior to writing any of the date/time registers (00h to 07h) to prevent corruption of this nature.

## Stop bit (ST)

If the oscillator has been determined to have stopped, it is recommended that users set and then clear the oscillator stop bit (ST, bit 7 of address 1). This causes additional current to be briefly injected into the oscillator to help get it running. We recommend using this *kick-start* feature only when the oscillator is not running such as when the OF bit (oscillator fail status bit) is set or when the device is being powered up for the first time.

If, upon power-up from backup mode, it is determined the device needs kick-starting, the user should first clear the HT bit before setting the ST bit. Because the ST bit is part of the seconds register, a write of the ST bit will result in the buffer/transfer registers being copied to the counters. And if the HT bit is still set from power-down, the buffer/transfer registers will contain the time of power-down. Thus kick-starting the device with HT set will result in overwriting the date/time counters.

Furthermore, the user is reminded that the ST bit, being part of the seconds register, must be packed with the seconds value. That is, the user must implement a read-modify-write sequence on the seconds register when toggling the ST bit.



## Recommended power-up sequence

The following flowchart shows one way of accessing the RTC after power-up which avoids any issues with the HT bit.

Power-up from backup

Optional: Read time/date
(time of power-down).

Clear HT bit

Optional: Read time/date
(present time).
off\_duration = present\_time time\_of-power-down

Clear any flags (read flags register,
where applicable)

Optional: Re-initialize watchdog
(where applicable)

Optional: Re-enable / Re-initialize
timer (where applicable)

Figure 5. Recommended power-up sequence

## **Revision history**

Table 1. Document revision history

Date	Revision	Changes
Jun-2004	1	Initial release.
02-May-2012	2	Document completely rewritten; updated title.

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