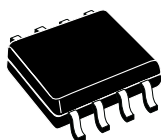


2 A step-down switching regulator for aerospace applications

Datasheet - target specification



HSOP8 exposed pad

Features

- General features
 - 2 A DC output current
 - 4.5 V to 38 V input voltage
 - Output voltage adjustable from 0.6 V
 - Large ambient temperature range: -40 °C to 125 °C
 - 250 kHz switching frequency, programmable up to 1 MHz
 - Internal soft-start and enable
 - Low dropout operation: 100% duty cycle
 - Voltage feed-forward
 - Zero load current operation
 - Overcurrent and thermal protection
 - HSOP8 package
- Aerospace and defense features
 - Suitable for use in aerospace and defense applications
 - Dedicated traceability and part marking
 - Production parts approval documents available
 - Adapted extended life time and obsolescence management
 - Extended product change notification process
 - Designed and manufactured to meet sub-ppm quality goals
 - Advanced mold and frame designs for superior resilience in harsh environments (acceleration, EMI, thermal, humidity)
 - Extended screening capability on request

Applications

- Dedicated to aerospace applications
- Aerospace LED driving

Description

The R7985A is a step-down switching regulator with a 2.5 A (minimum) current limited embedded power MOSFET, so it is able to deliver up to 2 A current to the load depending on the application conditions.

The input voltage can range from 4.5 V to 38 V, while the output voltage can be set starting from 0.6 V to V_{IN} .

Requiring a minimum set of external components, the device includes an internal 250 kHz switching frequency oscillator that can be externally adjusted up to 1 MHz. The large ambient temperature range makes it ideal for aerospace and defense applications.

The HSOP8 package with exposed pad allows the reduction of $R_{th(JA)}$ down to 40 °C/W.

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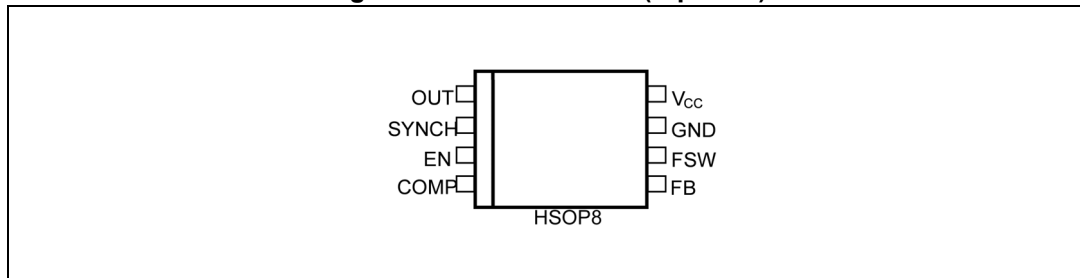
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1 Pin settings

1.1 Pin connection

Figure 1. Pin connection (top view)



1.2 Pin description

Table 1. Pin description

No.	Type	Description
1	OUT	Regulator output.
2	SYNCH	Master/slave synchronization. When it is left floating, a signal with a phase shift of half a period in respect to the power turn-on is present at the pin. When connected to an external signal at a frequency higher than the internal one, the device is synchronized by the external signal, with zero phase shift. Connecting together the SYNCH pins of two devices, the one with the higher frequency works as master and the other as slave; so the two power turn-ons have a phase shift of half a period.
3	EN	A logical signal (active high) enables the device. With EN higher than 1.2 V the device is ON and with EN lower than 0.63 V the device is OFF.
4	COMP	Error amplifier output to be used for loop frequency compensation.
5	FB	Feedback input. Connecting the output voltage directly to this pin the output voltage is regulated at 0.6 V. To have higher regulated voltages an external resistor divider is required from V_{OUT} to the FB pin.
6	FSW	The switching frequency can be increased connecting an external resistor from the FSW pin and ground. If this pin is left floating the device works at its free-running frequency of 250 KHz.
7	GND	Ground.
8	V _{CC}	Unregulated DC input voltage.

2 Maximum ratings

Table 2. Absolute maximum ratings

Symbol	Parameter		Value	Unit
V_{CC}	Input voltage		45	V
OUT	Output DC voltage		-0.3 to V_{CC}	
F_{SW} , COMP, SYNCH	Analog pin		-0.3 to 4	
EN	Enable pin		-0.3 to V_{CC}	
FB	Feedback voltage		-0.3 to 1.5	
P_{TOT}	Power dissipation at $T_A < 60\text{ °C}$	HSOP8	2	W
T_J	Junction temperature range		-40 to 150	°C
T_{stg}	Storage temperature range		-55 to 150	°C

3 Thermal data

Table 3. Thermal data

Symbol	Parameter		Value	Unit
$R_{th(JA)}$	Maximum thermal resistance junction ambient ⁽¹⁾	HSOP8	40	°C/W

1. Package mounted on demonstration board.

4 Electrical characteristics

$T_J = -40\text{ }^{\circ}\text{C}$ to $125\text{ }^{\circ}\text{C}$, $V_{CC} = 12\text{ V}$, unless otherwise specified.

Table 4. Electrical characteristics

Symbol	Parameter	Test conditions	Values			Unit
			Min.	Typ.	Max.	
V _{CC}	Operating input voltage range		4.5		38	V
V _{CCON}	Turn-on V _{CC} threshold				4.5	
V _{CCHYS}	V _{CC} UVLO hysteresis		0.1		0.4	
R _{DS(on)}	MOSFET on-resistance			200	400	mΩ
I _{LIM}	Maximum limiting current		2.5		3.5	A
Oscillator						
F _{SW}	Switching frequency		210	250	275	kHz
V _{FSW}	FSW pin voltage			1.254		V
D	Duty cycle		0		100	%
F _{ADJ}	Adjustable switching frequency	R _{FSW} = 33 kΩ		1000		kHz
Dynamic characteristics						
V _{FB}	Feedback voltage	4.5 V < V _{CC} < 38 V	0.588	0.6	0.612	V
DC characteristics						
I _Q	Quiescent current	Duty cycle = 0, V _{FB} = 0.8 V			2.4	mA
I _{QST-BY}	Total standby quiescent current			20	30	μA
Enable						
V _{EN}	EN threshold voltage	Device OFF level			0.3	V
		Device ON level	1.2			
I _{EN}	EN current	EN = V _{CC}		7.5	10	μA
Soft-start						
T _{SS}	Soft-start duration	FSW pin floating	7.3	8.2	9.8	ms
		F _{SW} = 1 MHz, R _{FSW} = 33 kΩ		2		
Error amplifier						
V _{CH}	High level output voltage	V _{FB} < 0.6 V	3			V
V _{CL}	Low level output voltage	V _{FB} > 0.6 V			0.1	
I _{O SOURCE}	Source COMP pin	V _{FB} = 0.5 V, V _{COMP} = 1 V		19		mA
I _{O SINK}	Sink COMP pin	V _{FB} = 0.7 V, V _{COMP} = 0.75 V		30		mA
G _V	Open loop voltage gain	(1)		100		dB

Table 4. Electrical characteristics (continued)

Symbol	Parameter	Test conditions	Values			Unit
			Min.	Typ.	Max.	
Synchronization function						
V _{S_IN,HI}	High input voltage		2		3.3	V
V _{S_IN,LO}	Low input voltage				1	
t _{S_IN_PW}	Input pulse width	V _{S_IN,HI} = 3 V, V _{S_IN,LO} = 0 V	100			ns
		V _{S_IN,HI} = 2 V, V _{S_IN,LO} = 1 V	300			
I _{SYNCH,LO}	Slave sink current	V _{SYNCH} = 2.9 V		0.7	1	mA
V _{S_OUT,HI}	Master output amplitude	I _{SOURCE} = 4.5 mA	2			V
t _{S_OUT_PW}	Output pulse width	SYNCH floating		110		ns
Protection						
T _{SHDN}	Thermal shutdown			150		°C
	Hysteresis			30		

1. Guaranteed by design.

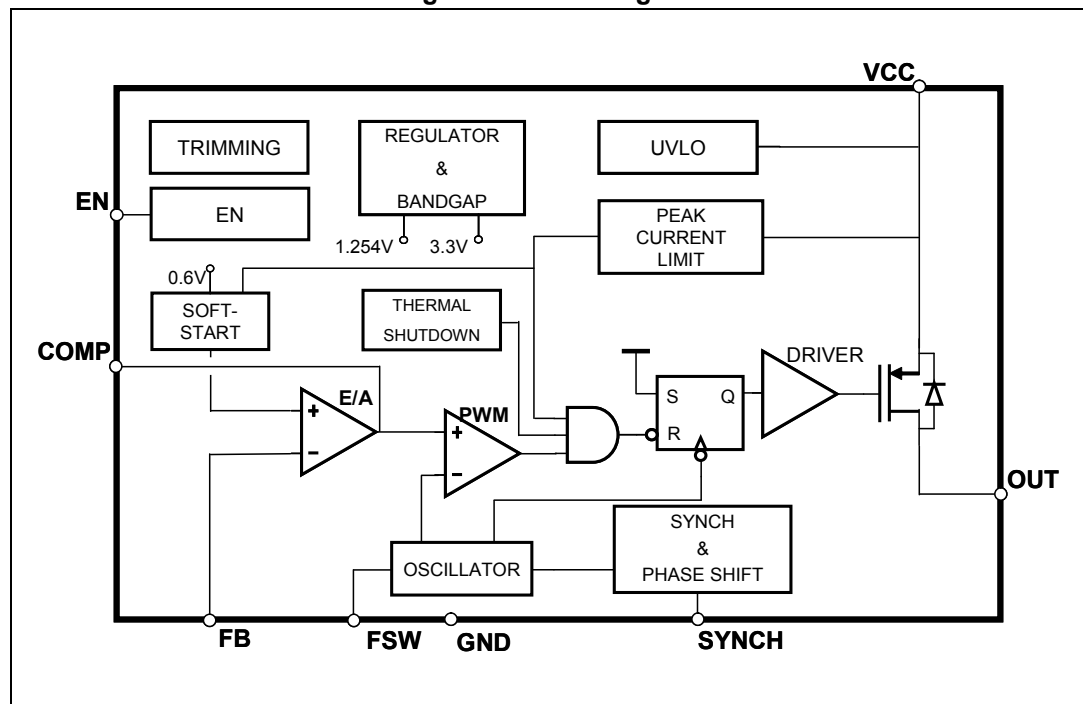
5 Functional description

The R7985A device is based on a “voltage mode”, constant frequency control. The output voltage V_{OUT} is sensed by the feedback pin (FB) compared to an internal reference (0.6 V) providing an error signal that, compared to a fixed frequency sawtooth, controls the ON and OFF time of the power switch.

The main internal blocks are shown in the block diagram in [Figure 2](#). They are:

- A fully integrated oscillator that provides sawtooth to modulate the duty cycle and the synchronization signal. Its switching frequency can be adjusted by an external resistor. The voltage and frequency feed-forward are implemented
- Soft-start circuitry to limit inrush current during the startup phase
- Voltage mode error amplifier
- Pulse width modulator and the relative logic circuitry necessary to drive the internal power switch
- High-side driver for embedded P-channel power MOSFET switch
- Peak current limit sensing block, to handle overload and short-circuit conditions
- A voltage regulator and internal reference. It supplies internal circuitry and provides a fixed internal reference
- A voltage monitor circuitry (UVLO) that checks the input and internal voltages
- A thermal shutdown block, to prevent thermal runaway.

Figure 2. Block diagram



5.1 Oscillator and synchronization

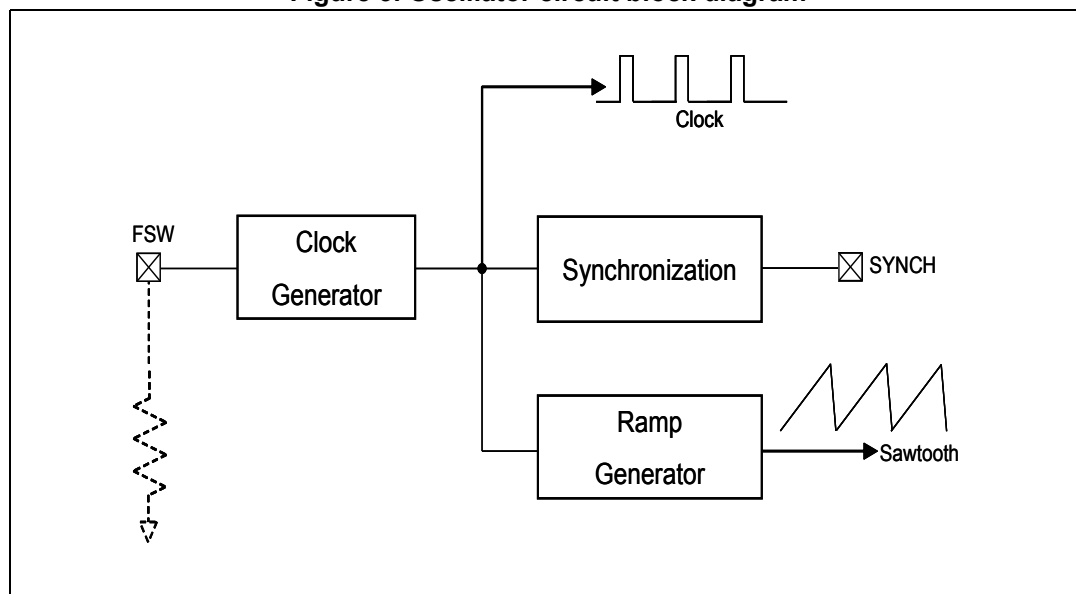
Figure 3 shows the block diagram of the oscillator circuit. The internal oscillator provides a constant frequency clock. Its frequency depends on the resistor externally connected to the FSW pin. If the FSW pin is left floating, the frequency is 250 kHz; it can be increased as shown in *Figure 5* by an external resistor connected to ground.

To improve the line transient performance, keeping the PWM gain constant versus the input voltage, the voltage feed-forward is implemented by changing the slope of the sawtooth according to the input voltage change (see *Figure 4.a*).

The slope of the sawtooth also changes if the oscillator frequency is increased by the external resistor. In this way, a frequency feed-forward is implemented (*Figure 4.b*) in order to keep the PWM gain constant versus the switching frequency (see *Section 6.4 on page 21* for PWM gain expression).

On the SYNCH pin the synchronization signal is generated. This signal has a phase shift of 180° with respect to the clock. This delay is useful when two devices are synchronized connecting the SYNCH pin together. When SYNCH pins are connected, the device with the higher oscillator frequency works as master, so the slave device switches at the frequency of the master but with a delay of half a period. This minimizes the RMS current flowing through the input capacitor (see the L5988D datasheet).

Figure 3. Oscillator circuit block diagram



The device can be synchronized to work at a higher frequency feeding an external clock signal. The synchronization changes the sawtooth amplitude, changing the PWM gain (*Figure 4.c*). This change must be taken into account when the loop stability is studied. To minimize the change of the PWM gain, the free-running frequency should be set (with a resistor on the FSW pin) only slightly lower than the external clock frequency. This pre-adjusting of the frequency changes the sawtooth slope in order to render negligible the truncation of sawtooth, due to the external synchronization.

Figure 4. Sawtooth: voltage and frequency feed-forward; external synchronization

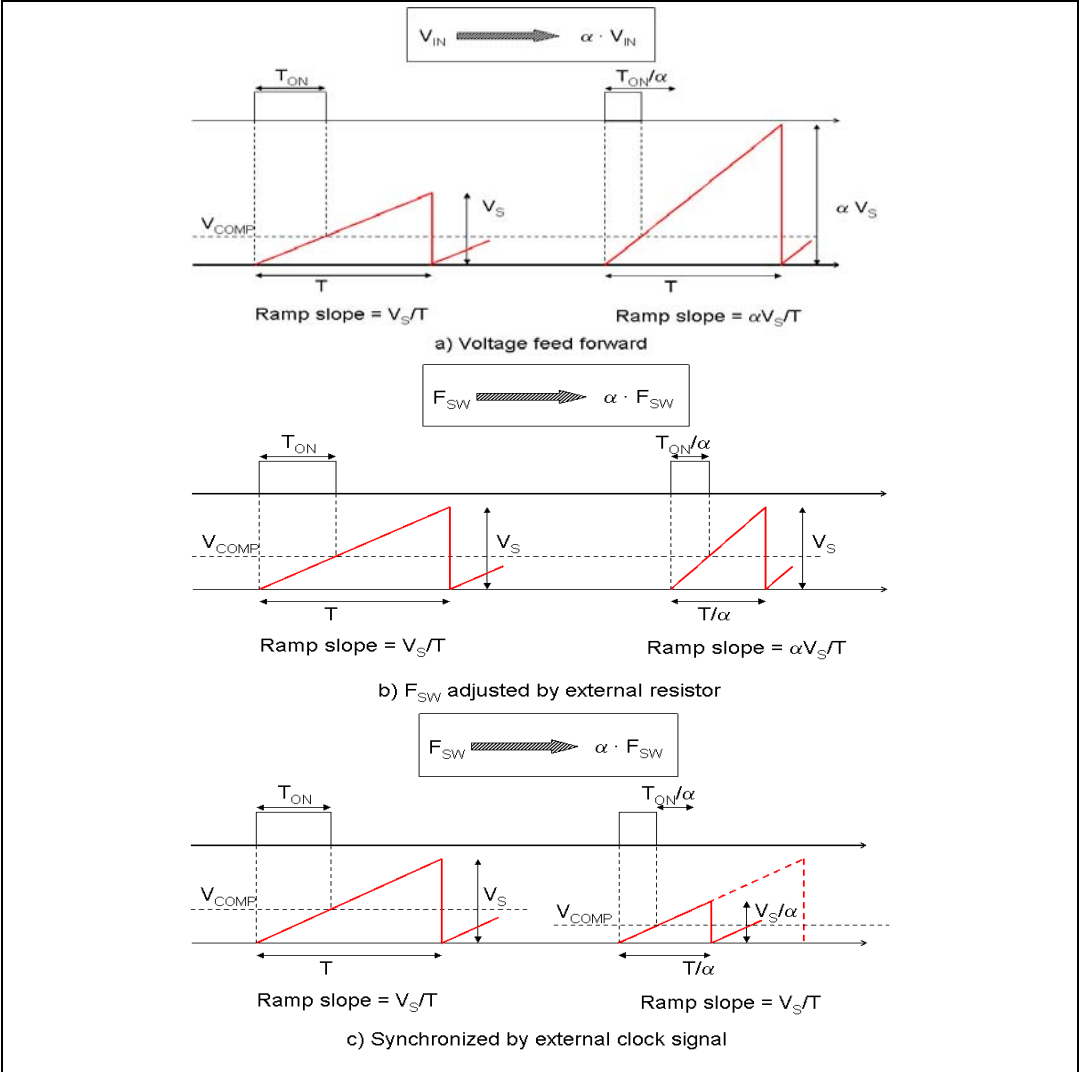
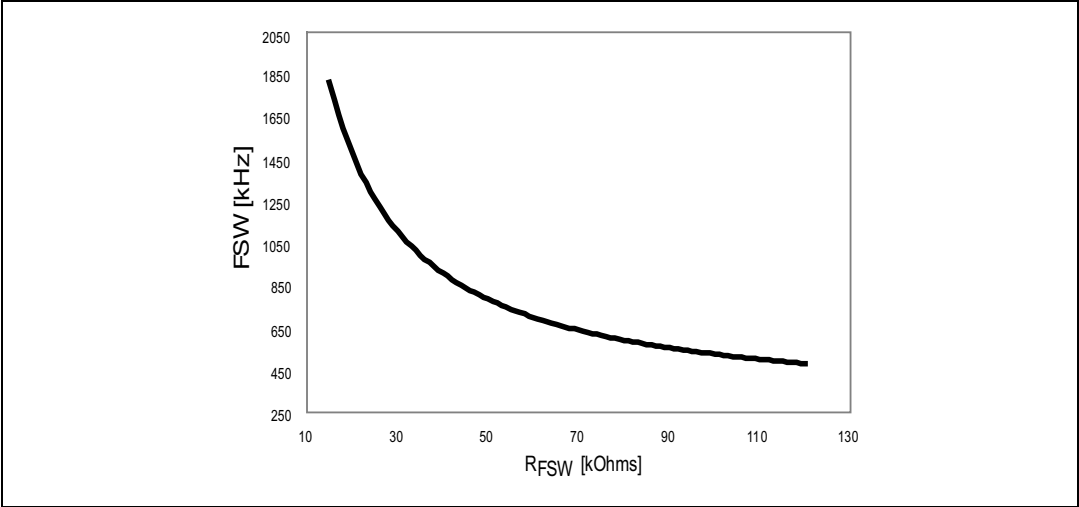


Figure 5. Oscillator frequency vs. the FSW pin resistor



where:

Equation 1

$$R_{FSW} = \frac{28.5 \cdot 10^9}{F_{SW} - 250 \cdot 10^3} - 3.23 \cdot 10^3$$

F_{SW} is desired switching frequency.

5.2 Soft-start

Soft-start is essential to assure the correct and safe startup of the step-down converter. It avoids inrush current surge and makes the output voltage increase monotonically.

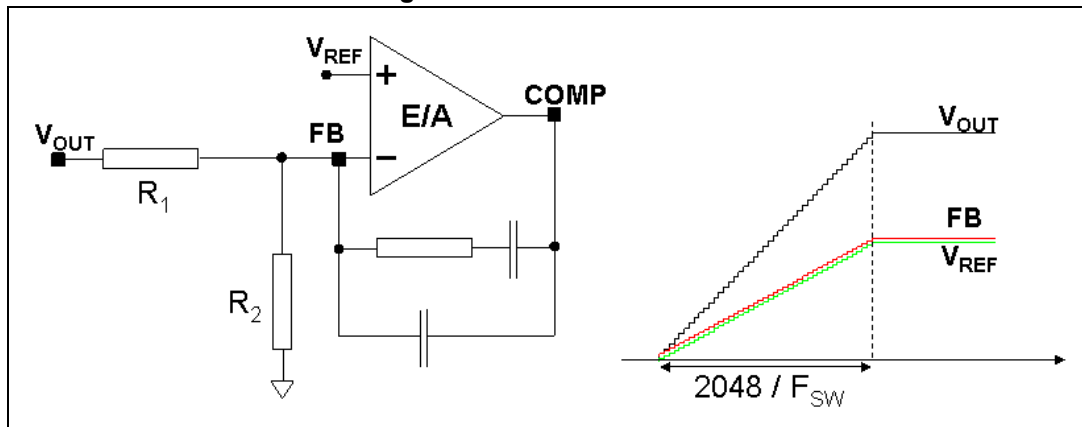
The soft-start is performed by a staircase ramp on the non inverting input (V_{REF}) of the error amplifier. So the output voltage slew rate is:

Equation 2

$$SR_{OUT} = SR_{VREF} \cdot \left(1 + \frac{R1}{R2}\right)$$

where SR_{VREF} is the slew rate of the non inverting input, while $R1$ and $R2$ is the resistor divider to regulate the output voltage (see [Figure 6](#)). The soft-start staircase consists of 64 steps of 9.5 mV each, from 0 V to 0.6 V. The time base of one step is of 32 clock cycles. So the soft-start time and then the output voltage slew rate depend on the switching frequency.

Figure 6. Soft-start scheme



Soft-start time results:

Equation 3

$$SS_{TIME} = \frac{32 \cdot 64}{F_{SW}}$$

For example, with a switching frequency of 250 kHz, the SS_{TIME} is 8 ms.

5.3 Error amplifier and compensation

The error amplifier (E/A) provides the error signal to be compared with the sawtooth to perform the pulse width modulation. Its non inverting input is internally connected to a 0.6 V voltage reference, while its inverting input (FB) and output (COMP) are externally available for feedback and frequency compensation. In this device the error amplifier is a voltage mode operational amplifier, so with high DC gain and low output impedance.

The uncompensated error amplifier characteristics are shown in [Table 5](#).

Table 5. Uncompensated error amplifier characteristics

Parameter	Value
Low frequency gain	100 dB
GBWP	4.5 MHz
Slew rate	7 V/ μ s
Output voltage swing	0 to 3.3 V
Maximum source/sink current	17 mA/25 mA

In continuous conduction mode (CCM), the transfer function of the power section has two poles due to the LC filter and one zero due to the ESR of the output capacitor. Different kinds of compensation networks can be used depending on the ESR value of the output capacitor. In case the zero introduced by the output capacitor helps to compensate the double pole of the LC filter, a Type II compensation network can be used. Otherwise, a Type III compensation network must be used (see [Section 6.4 on page 21](#) for details of the compensation network selection).

The methodology to compensate the loop is to introduce zeroes to obtain a safe phase margin.

5.4 Overcurrent protection

The R7985A implements the overcurrent protection sensing current flowing through the power MOSFET. Due to the noise created by the switching activity of the power MOSFET, the current sensing is disabled during the initial phase of the conduction time. This avoids an erroneous detection of a fault condition. This interval is generally known as “masking time” or “blanking time”. The masking time is about 200 ns.

If the overcurrent limit is reached, the power MOSFET is turned off, implementing the pulse-by-pulse overcurrent protection. Under an overcurrent condition, the device can skip turn-on pulses in order to keep the output current constant and equal to the current limit. If, at the end of the “masking time”, the current is higher than the overcurrent threshold, the power MOSFET is turned off and one pulse is skipped. If, at the following switching-on, when the “masking time” ends, the current is still higher than the overcurrent threshold, the device skips two pulses. This mechanism is repeated and the device can skip up to seven pulses. While, if at the end of the “masking time” the current is lower than the over current threshold, the number of skipped cycles is decreased by one unit (see [Figure 7](#)).

So the overcurrent/short-circuit protection acts by switching off the power MOSFET and reducing the switching frequency down to one eighth of the default switching frequency, in order to keep constant the output current around the current limit.

This kind of overcurrent protection is effective if the output current is limited. To prevent the current from diverging, the current ripple in the inductor during the ON-time must not be higher than the current ripple during the OFF-time. That is:

Equation 4

$$\frac{V_{IN} - V_{OUT} - R_{DS(on)} \cdot I_{OUT} - DCR \cdot I_{OUT}}{L \cdot F_{SW}} \cdot D = \frac{V_{OUT} + V_F + R_{DS(on)} \cdot I_{OUT} + DCR \cdot I_{OUT}}{L \cdot F_{SW}} \cdot (1 - D)$$

If the output voltage is shorted, $V_{OUT} \cong 0$, $I_{OUT} = I_{LIM}$, $D/F_{SW} = T_{ON_MIN}$, $(1-D)/F_{SW} \cong 1/F_{SW}$. So from the above equation the maximum switching frequency that guarantees to limit the current results:

Equation 5

$$F_{SW}^* = \frac{(V_F + DCR \cdot I_{LIM})}{(V_{IN} - (R_{DS(on)} + DCR) \cdot I_{LIM})} \cdot \frac{1}{T_{ON_MIN}}$$

With $R_{DS(on)} = 300 \text{ m}\Omega$, $DCR = 0.08 \text{ }\Omega$, the worst condition is with $V_{IN} = 38 \text{ V}$, $I_{LIM} = 2.5 \text{ A}$; the maximum frequency to keep the output current limited during the short-circuit results 74 kHz.

Based on the pulse-by-pulse mechanism, that reduces the switching frequency down to one eighth, the maximum F_{SW} , adjusted by the FSW pin, that assures a full effective output current limitation is $74 \text{ kHz} \cdot 8 = 592 \text{ kHz}$.

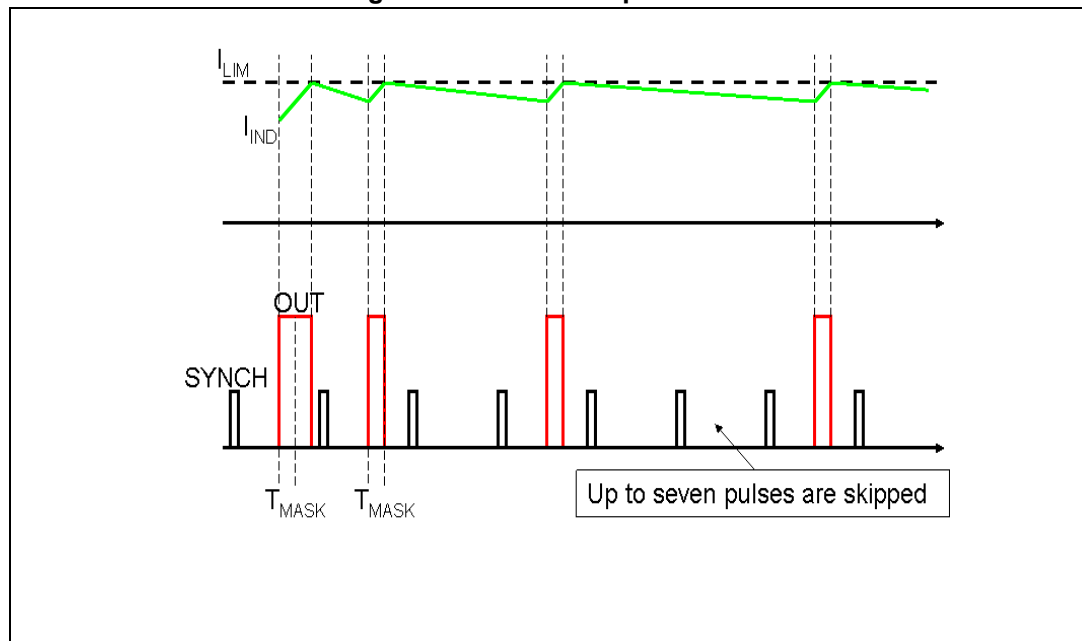
If, with $V_{IN} = 38 \text{ V}$, the switching frequency is set higher than 592 kHz, during short-circuit condition the system finds a different equilibrium with higher current. For example, with $F_{SW} = 700 \text{ kHz}$ and the output shorted to ground, the output current is limited around:

Equation 6

$$I_{OUT} = \frac{V_{IN} \cdot F_{SW}^* - V_F / T_{ON_MIN}}{(DCR / T_{ON_MIN}) + (R_{DS(on)} + DCR) \cdot F_{SW}^*} = 3.68 \text{ A}$$

where F_{SW}^* is 700 kHz divided by eight.

Figure 7. Overcurrent protection



5.5 Enable function

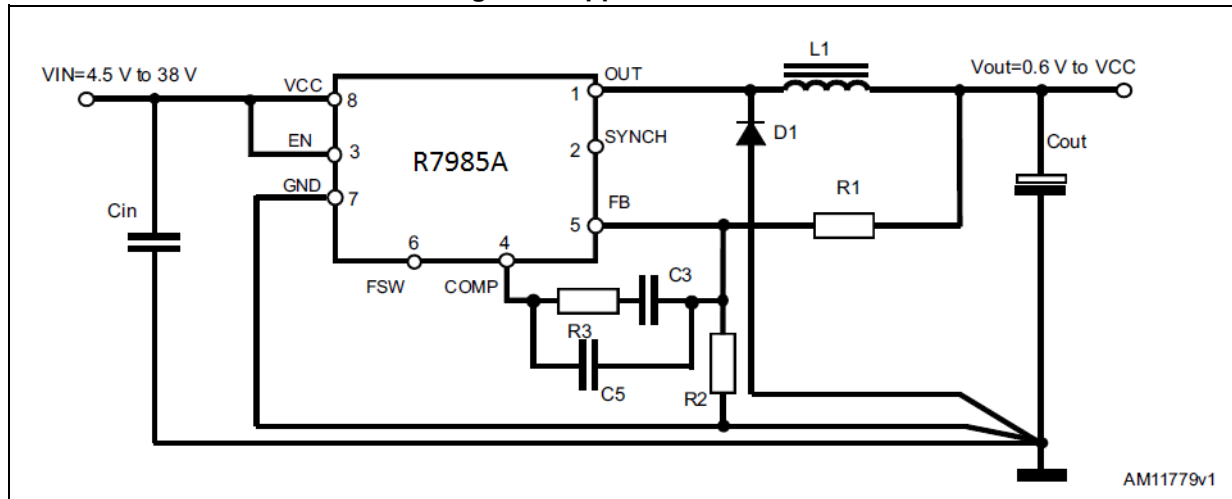
The enable feature allows the device to be put into standby mode. With the EN pin lower than 0.3 V, the device is disabled and the power consumption is reduced to less than 30 μ A. With the EN pin lower than 1.2 V, the device is enabled. If the EN pin is left floating, an internal pull-down ensures that the voltage at the pin reaches the inhibit threshold and the device is disabled. The pin is also V_{CC} compatible.

5.6 Hysteretic thermal shutdown

The thermal shutdown block generates a signal that turns off the power stage if the junction temperature goes above 150 °C. Once the junction temperature goes back to about 120 °C, the device restarts in normal operation. The sensing element is very close to the PDMOS area, so ensuring an accurate and fast temperature detection.

6 Application information

Figure 8. Application circuit



6.1 Input capacitor selection

The capacitor connected to the input must be capable of supporting the maximum input operating voltage and the maximum RMS input current required by the device. The input capacitor is subject to a pulsed current, the RMS value of which is dissipated over its ESR, affecting the overall system efficiency.

So the input capacitor must have an RMS current rating higher than the maximum RMS input current and an ESR value compliant with the expected efficiency.

The maximum RMS input current flowing through the capacitor can be calculated as:

Equation 7

$$I_{\text{RMS}} = I_{\text{O}} \cdot \sqrt{D - \frac{2 \cdot D^2}{\eta} + \frac{D^2}{\eta^2}}$$

where I_{O} is the maximum DC output current, D is the duty cycle, η is the efficiency. Considering $\eta = 1$, this function has a maximum at $D = 0.5$ and it is equal to $I_{\text{O}}/2$.

In a specific application the range of possible duty cycles must be considered in order to find out the maximum RMS input current. The maximum and minimum duty cycles can be calculated as:

Equation 8

$$D_{\text{MAX}} = \frac{V_{\text{OUT}} + V_{\text{F}}}{V_{\text{INMIN}} - V_{\text{SW}}}$$

and

Equation 9

$$D_{\text{MIN}} = \frac{V_{\text{OUT}} + V_F}{V_{\text{INMAX}} - V_{\text{SW}}}$$

where V_F is the forward voltage on the freewheeling diode and V_{SW} is voltage drop across the internal PDMOS.

The peak-to-peak voltage across the input capacitor can be calculated as:

Equation 10

$$V_{\text{PP}} = \frac{I_O}{C_{\text{IN}} \cdot F_{\text{SW}}} \cdot \left[\left(1 - \frac{D}{\eta}\right) \cdot D + \frac{D}{\eta} \cdot (1 - D) \right] + \text{ESR} \cdot I_O$$

where ESR is the equivalent series resistance of the capacitor.

Given the physical dimension, ceramic capacitors can well meet the requirements of the input filter sustaining a higher input RMS current than electrolytic/tantalum types.

In this case, the equation of C_{IN} as a function of the target V_{PP} can be written as follows:

Equation 11

$$C_{\text{IN}} = \frac{I_O}{V_{\text{PP}} \cdot F_{\text{SW}}} \cdot \left[\left(1 - \frac{D}{\eta}\right) \cdot D + \frac{D}{\eta} \cdot (1 - D) \right]$$

neglecting the small ESR of ceramic capacitors.

Considering $\eta = 1$, this function has its maximum in $D = 0.5$, therefore, given the maximum peak-to-peak input voltage ($V_{\text{PP_MAX}}$), the minimum input capacitor ($C_{\text{IN_MIN}}$) value is:

Equation 12

$$C_{\text{IN_MIN}} = \frac{I_O}{2 \cdot V_{\text{PP_MAX}} \cdot F_{\text{SW}}}$$

Typically, C_{IN} is dimensioned to keep the maximum peak-to-peak voltage in the order of 1% of V_{INMAX} .

In [Table 6](#), some multi-layer ceramic capacitors suitable for this device are reported.

Table 6. Input MLCC capacitors

Manufacturer	Series	Cap value (μF)	Rated voltage (V)
Taiyo Yuden	UMK325BJ106MM-T	10	50
	GMK325BJ106MN-T	10	35
muRata	GRM32ER71H475K	4.7	50

A ceramic bypass capacitor, as close to the VCC and GND pins as possible, so that additional parasitic ESR and ESL are minimized, is suggested in order to prevent instability on the output voltage due to noise. The value of the bypass capacitor can go from 100 nF to 1 μF.

6.2 Inductor selection

The inductance value fixes the current ripple flowing through the output capacitor. So the minimum inductance value in order to have the expected current ripple must be selected. The rule to fix the current ripple value is to have a ripple at 20% - 40% of the output current.

In continuous current mode (CCM), the inductance value can be calculated by the following equation:

Equation 13

$$\Delta I_L = \frac{V_{IN} - V_{OUT}}{L} \cdot T_{ON} = \frac{V_{OUT} + V_F}{L} \cdot T_{OFF}$$

where T_{ON} is the conduction time of the internal high-side switch and T_{OFF} is the conduction time of the external diode [in CCM, $F_{SW} = 1/(T_{ON} + T_{OFF})$]. The maximum current ripple, at fixed V_{OUT} , is obtained at maximum T_{OFF} , that is at minimum duty cycle (see [Section 6.1](#) to calculate minimum duty). So by fixing $\Delta I_L = 20\%$ to 30% of the maximum output current, the minimum inductance value can be calculated:

Equation 14

$$L_{MIN} = \frac{V_{OUT} + V_F}{\Delta I_{MAX}} \cdot \frac{1 - D_{MIN}}{F_{SW}}$$

where F_{SW} is the switching frequency, $1/(T_{ON} + T_{OFF})$.

For example, for $V_{OUT} = 5\text{ V}$, $V_{IN} = 24\text{ V}$, $I_O = 2\text{ A}$ and $F_{SW} = 250\text{ kHz}$, the minimum inductance value to have $\Delta I_L = 30\%$ of I_O is about $28\text{ }\mu\text{H}$.

The peak current through the inductor is given by:

Equation 15

$$I_{L,PK} = I_O + \frac{\Delta I_L}{2}$$

So if the inductor value decreases, then the peak current (that must be lower than the minimum current limit of the device) increases. According to the maximum DC output current for this product family (2 A), the higher the inductor value, the higher the average output current that can be delivered, without triggering the overcurrent protection.

In [Table 7](#) some inductor part numbers are listed.

Table 7. Inductors

Manufacturer	Series	Inductor value (μH)	Saturation current (A)
Coilcraft	MSS1038	3.8 to 10	3.9 to 6.5
	MSS1048	12 to 22	3.84 to 5.34
Würth	PD Type L	8.2 to 15	3.75 to 6.25
	PD Type M	2.2 to 4.7	4 to 6
SUMIDA	CDRH6D226/HP	1.5 to 3.3	3.6 to 5.2
	CDR10D48MN	6.6 to 12	4.1 to 5.7

6.3 Output capacitor selection

The current in the capacitor has a triangular waveform which generates a voltage ripple across it. This ripple is due to the capacitive component (charge or discharge of the output capacitor) and the resistive component (due to the voltage drop across its ESR). So the output capacitor must be selected in order to have a voltage ripple compliant with the application requirements.

The amount of the voltage ripple can be calculated starting from the current ripple obtained by the inductor selection.

Equation 16

$$\Delta V_{OUT} = ESR \cdot \Delta I_{MAX} + \frac{\Delta I_{MAX}}{8 \cdot C_{OUT} \cdot f_{SW}}$$

Usually the resistive component of the ripple is much higher than the capacitive one, if the output capacitor adopted is not a multi-layer ceramic capacitor (MLCC) with very low ESR value.

The output capacitor is important also for loop stability: it fixes the double LC filter pole and the zero due to its ESR. In [Section 6.4](#), how to consider its effect in the system stability is illustrated.

For example, with $V_{OUT} = 5\text{ V}$, $V_{IN} = 24\text{ V}$, $\Delta I_L = 0.9\text{ A}$ (resulting by the inductor value), in order to have a $\Delta V_{OUT} = 0.01 \cdot V_{OUT}$, if the multi-layer ceramic capacitors are adopted, $10\text{ }\mu\text{F}$ are needed and the ESR effect on the output voltage ripple can be neglected. In case of not-negligible ESR (electrolytic or tantalum capacitors), the capacitor is chosen taking into account its ESR value. So, in the case of $330\text{ }\mu\text{F}$ with $ESR = 70\text{ m}\Omega$, the resistive component of the drop dominates and the voltage ripple is 43 mV .

The output capacitor is also important to sustain the output voltage when a load transient with high slew rate is required by the load. When the load transient slew rate exceeds the system bandwidth the output capacitor provides the current to the load. So if the high slew rate load transient is required by the application, the output capacitor and system bandwidth must be chosen in order to sustain the load transient.

In [Table 8](#) below some capacitor series are listed.

Table 8. Output capacitors

Manufacturer	Series	Cap value (μF)	Rated voltage (V)	ESR ($\text{m}\Omega$)
muRata	GRM32	22 to 100	6.3 to 25	< 5
	GRM31	10 to 47	6.3 to 25	< 5
PANASONIC	ECJ	10 to 22	6.3	< 5
	EEFCD	10 to 68	6.3	15 to 55
SANYO	TPA/B/C	100 to 470	4 to 16	40 to 80
TDK	C3225	22 to 100	6.3	< 5

6.4 Compensation network

The compensation network must assure stability and good dynamic performance. The loop of the R7985A is based on the voltage mode control. The error amplifier is a voltage operational amplifier with high bandwidth. So by selecting the compensation network the E/A is considered as ideal, that is, its bandwidth is much larger than the system one.

The transfer functions of the PWM modulator and the output LC filter are studied (see [Figure 10](#)). The transfer function of the PWM modulator, from the error amplifier output (COMP pin) to the OUT pin, results:

Equation 17

$$G_{PW0} = \frac{V_{IN}}{V_s}$$

where V_s is the sawtooth amplitude. As seen in [Section 5.1 on page 11](#), the voltage feed-forward generates a sawtooth amplitude directly proportional to the input voltage, that is:

Equation 18

$$V_s = K \cdot V_{IN}$$

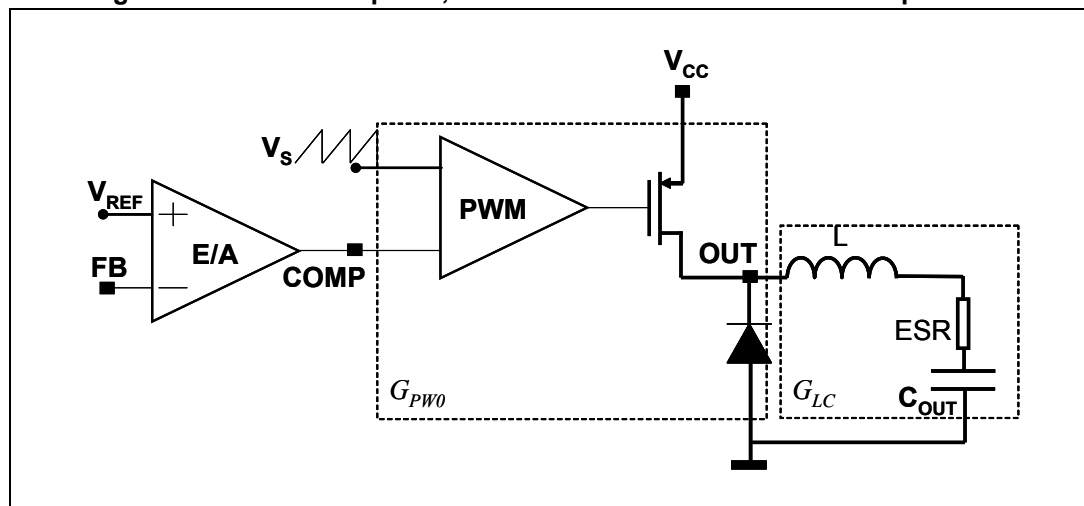
In this way the PWM modulator gain results constant and equal to:

Equation 19

$$G_{PW0} = \frac{V_{IN}}{V_s} = \frac{1}{K} = 18$$

The synchronization of the device with an external clock provided through the SYNCH pin can modify the PWM modulator gain (see [Section 5.1 on page 11](#) to understand how this gain changes and how to keep it constant in spite of the external synchronization).

Figure 9. The error amplifier, the PWM modulator and the LC output filter



The transfer function on the LC filter is given by:

Equation 20

$$G_{LC}(s) = \frac{1 + \frac{s}{2\pi \cdot f_{zESR}}}{1 + \frac{s}{2\pi \cdot Q \cdot f_{LC}} + \left(\frac{s}{2\pi \cdot f_{LC}}\right)^2}$$

where:

Equation 21

$$f_{LC} = \frac{1}{2\pi \cdot \sqrt{L \cdot C_{OUT}} \cdot \sqrt{1 + \frac{ESR}{R_{OUT}}}}, \quad f_{zESR} = \frac{1}{2\pi \cdot ESR \cdot C_{OUT}}$$

Equation 22

$$Q = \frac{\sqrt{R_{OUT} \cdot L \cdot C_{OUT} \cdot (R_{OUT} + ESR)}}{L + C_{OUT} \cdot R_{OUT} \cdot ESR}, \quad R_{OUT} = \frac{V_{OUT}}{I_{OUT}}$$

As seen in [Section 5.3 on page 14](#), two different kinds of network can compensate the loop. In the two following paragraphs the guidelines to select the Type II and Type III compensation network are illustrated.

6.4.1 Type III compensation network

The methodology to stabilize the loop consists in placing two zeroes to compensate the effect of the LC double pole, thereby increasing phase margin; then to place one pole in the origin to minimize the DC error on the regulated output voltage; finally to place other poles far from the zero dB frequency.

If the equivalent series resistance (ESR) of the output capacitor introduces a zero with a frequency higher than the desired bandwidth (that is: $2\pi \cdot ESR \cdot C_{OUT} < 1 / BW$), the Type III compensation network is needed. Multi-layer ceramic capacitors (MLCC) have very low ESR ($< 1 \text{ m}\Omega$), with very high frequency zero, so a Type III network is adopted to compensate the loop.

In [Figure 10](#), the Type III compensation network is shown. This network introduces two zeroes (f_{Z1} , f_{Z2}) and three poles (f_{P0} , f_{P1} , f_{P2}). They are expressed as:

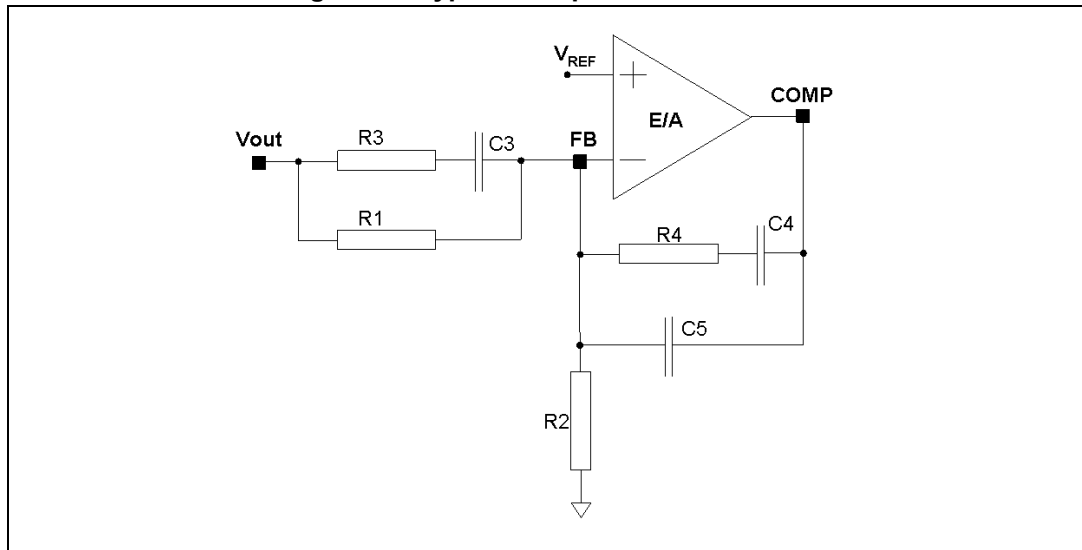
Equation 23

$$f_{Z1} = \frac{1}{2\pi \cdot C_3 \cdot (R_1 + R_3)}, \quad f_{Z2} = \frac{1}{2\pi \cdot R_4 \cdot C_4}$$

Equation 24

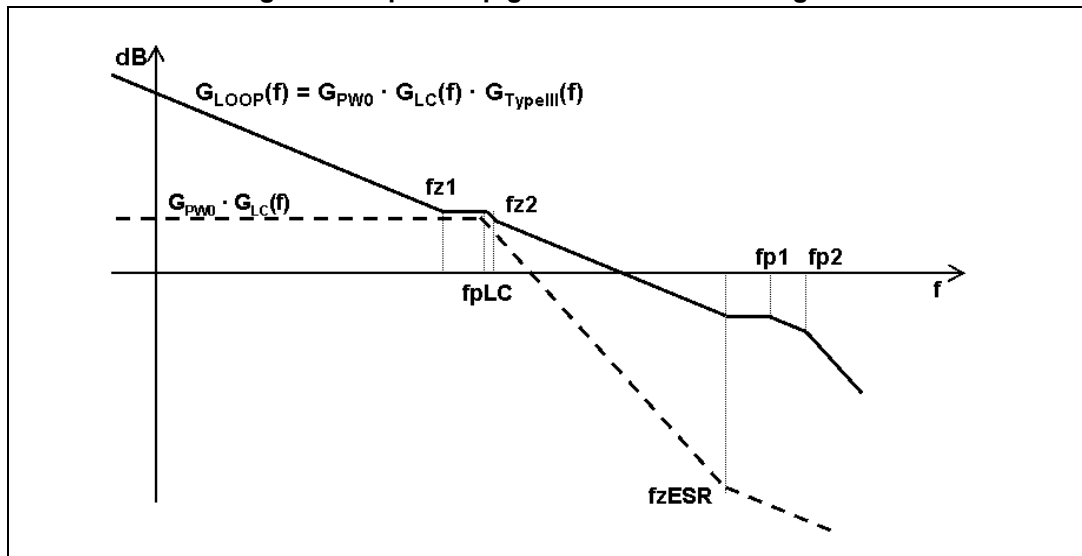
$$f_{P0} = 0, \quad f_{P1} = \frac{1}{2\pi \cdot R_3 \cdot C_3}, \quad f_{P2} = \frac{1}{2\pi \cdot R_4 \cdot \frac{C_4 \cdot C_5}{C_4 + C_5}}$$

Figure 10. Type III compensation network



In [Figure 11](#) the Bode diagram of the PWM and LC filter transfer function [$G_{PW0} \cdot G_{LC}(f)$] and the open loop gain [$G_{LOOP}(f) = G_{PW0} \cdot G_{LC}(f) \cdot G_{TYPEIII}(f)$] are drawn.

Figure 11. Open loop gain: module Bode diagram



The guidelines for positioning the poles and the zeroes and for calculating the component values can be summarized as follows:

1. Choose a value for R_1 , usually between 1 k Ω and 5 k Ω .
2. Choose a gain (R_4/R_1) in order to have the required bandwidth (BW), that means:

Equation 25

$$R_4 = \frac{BW}{f_{LC}} \cdot K \cdot R_1$$

where K is the feed-forward constant and $1/K$ is equal to 18.

3. Calculate C_4 by placing the zero at 50% of the output filter double pole frequency (f_{LC}):

Equation 26

$$C_4 = \frac{1}{\pi \cdot R_4 \cdot f_{LC}}$$

4. Calculate C_5 by placing the second pole at four times the system bandwidth (BW):

Equation 27

$$C_5 = \frac{C_4}{2\pi \cdot R_4 \cdot C_4 \cdot 4 \cdot BW - 1}$$

5. Set also the first pole at four times the system bandwidth and also the second zero at the output filter double pole:

Equation 28

$$R_3 = \frac{R_1}{\frac{4 \cdot BW}{f_{LC}} - 1}, \quad C_3 = \frac{1}{2\pi \cdot R_3 \cdot 4 \cdot BW}$$

The suggested maximum system bandwidth is equal to the switching frequency divided by 3.5 ($F_{SW}/3.5$), so lower than 100 kHz if the F_{SW} is set higher than 500 kHz.

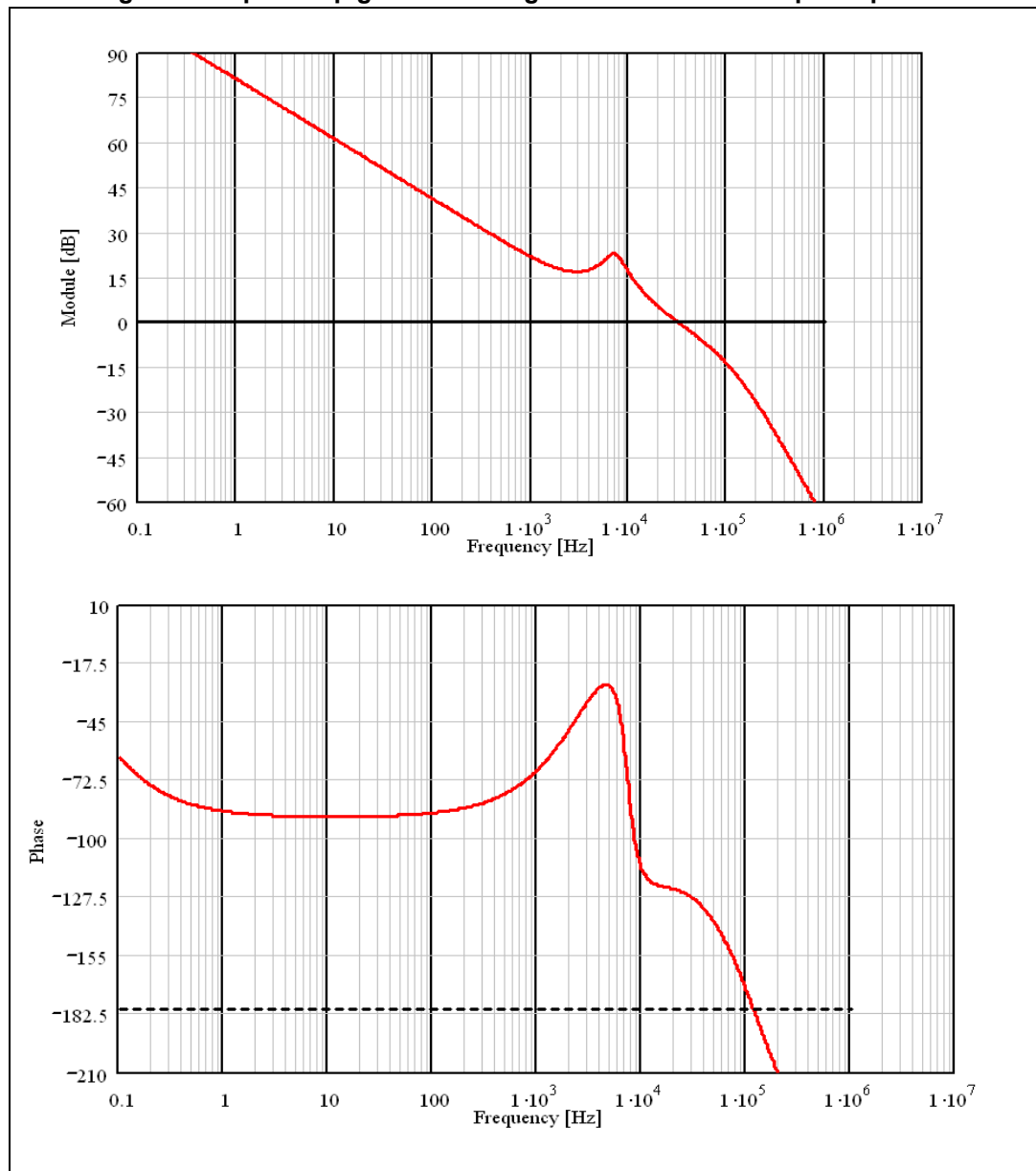
For example, with $V_{OUT} = 5$ V, $V_{IN} = 24$ V, $I_O = 2$ A, $L = 22$ μ H, $C_{OUT} = 22$ μ F, and $ESR < 1$ m Ω , the Type III compensation network is:

Equation 29

$$R_1 = 4.99\text{k}\Omega, \quad R_2 = 680\Omega, \quad R_3 = 270\Omega, \quad R_4 = 1.1\text{k}\Omega, \quad C_3 = 4.7\text{nF}, \quad C_4 = 47\text{nF}, \quad C_5 = 1\text{pF}$$

In [Figure 12](#) the module and phase of the open loop gain is shown. The bandwidth is about 32 kHz and the phase margin is 51°.

Figure 12. Open loop gain Bode diagram with ceramic output capacitor

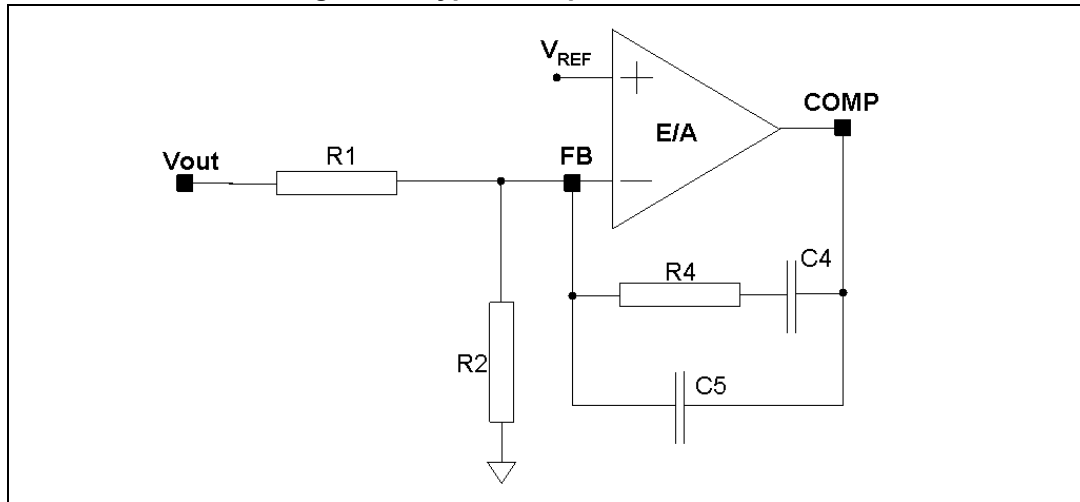


6.4.2 Type II compensation network

If the equivalent series resistance (ESR) of the output capacitor introduces a zero with a frequency lower than the desired bandwidth (that is: $2\pi \cdot \text{ESR} \cdot C_{\text{OUT}} > 1 / \text{BW}$), this zero helps stabilize the loop. Electrolytic capacitors show not-negligible ESR ($> 30 \text{ m}\Omega$), so with this kind of output capacitor the Type II network combined with the zero of the ESR allows the stabilizing of the loop.

In [Figure 13](#) the Type II network is shown.

Figure 13. Type II compensation network



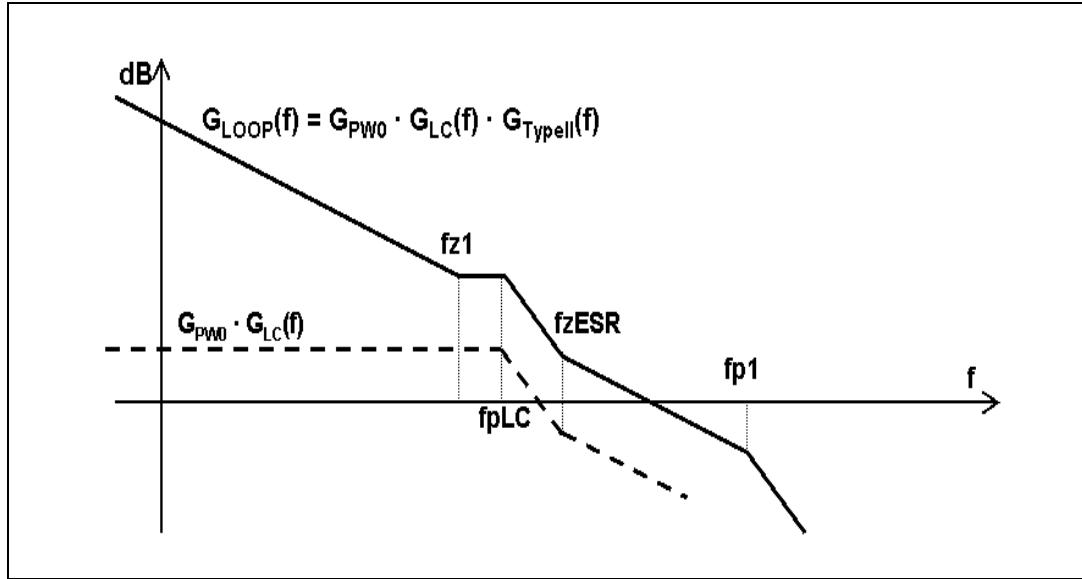
The singularities of the network are:

Equation 30

$$f_{z1} = \frac{1}{2\pi \cdot R_4 \cdot C_4}, \quad f_{p0} = 0, \quad f_{p1} = \frac{1}{2\pi \cdot R_4 \cdot \frac{C_4 \cdot C_5}{C_4 + C_5}}$$

In [Figure 14](#) the Bode diagram of the PWM and LC filter transfer function [$G_{PW0} \cdot G_{LC}(f)$] and the open loop gain [$G_{LOOP}(f) = G_{PW0} \cdot G_{LC}(f) \cdot G_{TYPEII}(f)$] are drawn.

Figure 14. Open loop gain: module Bode diagram



The guidelines for positioning the poles and the zeroes and for calculating the component values can be summarized as follows:

1. Choose a value for R_1 , usually between 1 k Ω and 5 k Ω , in order to have values of C_4 and C_5 not comparable with parasitic capacitance of the board.
2. Choose a gain (R_4/R_1) in order to have the required bandwidth (BW), that means:

Equation 31

$$R_4 = \left(\frac{f_{ESR}}{f_{LC}} \right)^2 \cdot \frac{BW}{f_{ESR}} \cdot \frac{V_S}{V_{IN}} \cdot R_1$$

where f_{ESR} is the ESR zero:

Equation 32

$$f_{ESR} = \frac{1}{2\pi \cdot ESR \cdot C_{OUT}}$$

and V_S is the sawtooth amplitude. The voltage feed-forward keeps the ratio V_S/V_{IN} constant.

3. Calculate C_4 by placing the zero one decade below the output filter double pole:

Equation 33

$$C_4 = \frac{10}{2\pi \cdot R_4 \cdot f_{LC}}$$

4. Then calculate C_3 in order to place the second pole at four times the system bandwidth (BW):

Equation 34

$$C_5 = \frac{C_4}{2\pi \cdot R_4 \cdot C_4 \cdot 4 \cdot BW - 1}$$

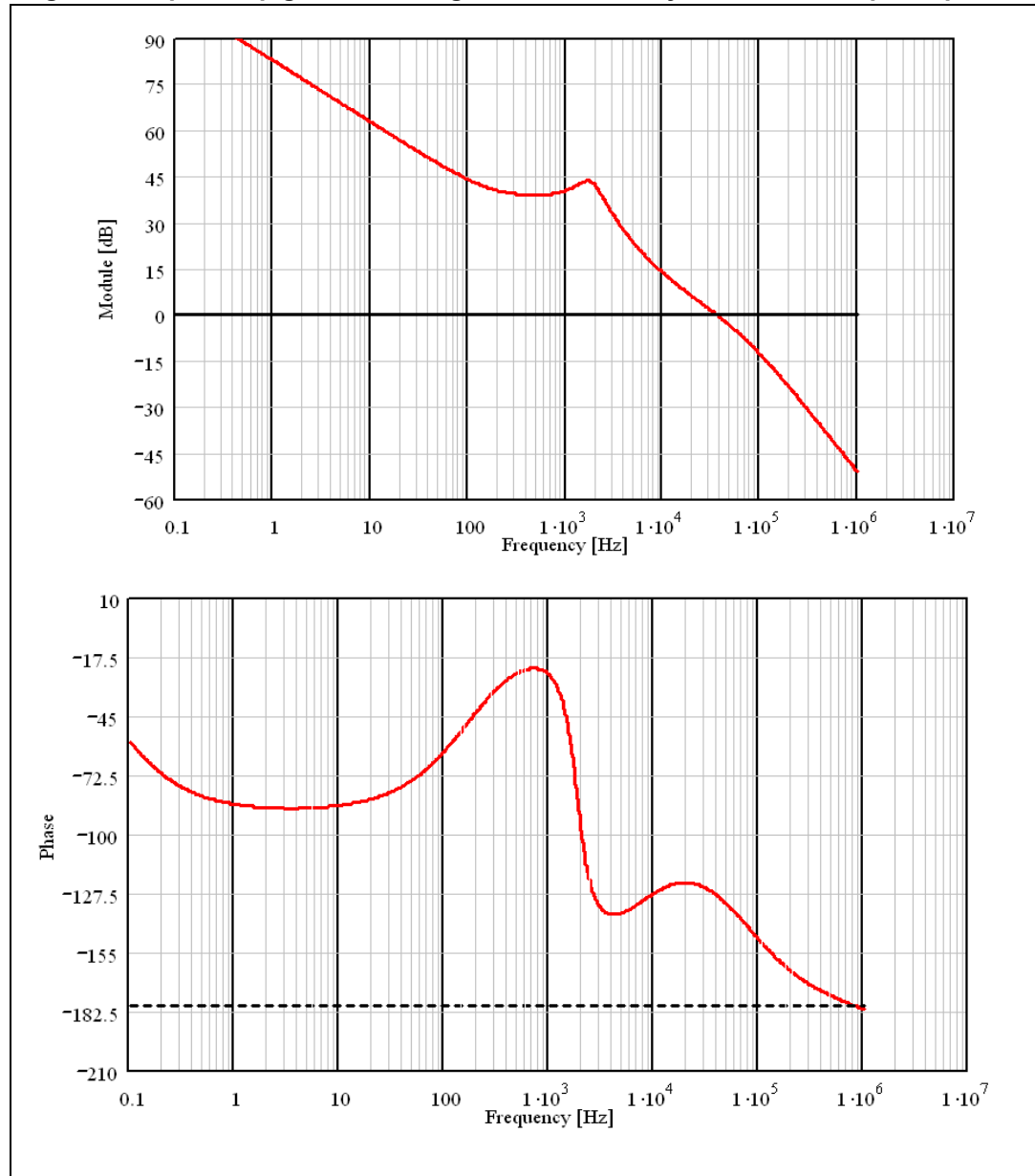
For example, with $V_{OUT} = 5\text{ V}$, $V_{IN} = 24\text{ V}$, $I_O = 2\text{ A}$, $L = 22\text{ }\mu\text{H}$, $C_{OUT} = 330\text{ }\mu\text{F}$, and $\text{ESR} = 70\text{ m}\Omega$, the Type II compensation network is:

Equation 35

$$R_1 = 1.1\text{ k}\Omega, \quad R_2 = 150\text{ }\Omega, \quad R_4 = 4.99\text{ k}\Omega, \quad C_4 = 180\text{ nF}, \quad C_5 = 180\text{ pF}$$

In [Figure 15](#) the module and phase of the open loop gain is shown. The bandwidth is about 36 kHz and the phase margin is 53 °.

Figure 15. Open loop gain Bode diagram with electrolytic/tantalum output capacitor



6.5 Thermal considerations

The thermal design is important to prevent the thermal shutdown of the device if the junction temperature goes above 150 °C. The three different sources of losses within the device are:

- a) conduction losses due to the not-negligible $R_{DS(on)}$ of the power switch; these are equal to:

Equation 36

$$P_{ON} = R_{DS(on)} \cdot (I_{OUT})^2 \cdot D$$

where D is the duty cycle of the application and the maximum $R_{DS(on)}$ overtemperature is 220 mΩ. Note that the duty cycle is theoretically given by the ratio between V_{OUT} and V_{IN} , but actually it is quite higher to compensate the losses of the regulator. So the conduction losses increase compared with the ideal case.

- b) switching losses due to power MOSFET turn-on and turn-off; these can be calculated as:

Equation 37

$$P_{SW} = V_{IN} \cdot I_{OUT} \cdot \frac{(T_{RISE} + T_{FALL})}{2} \cdot F_{SW} = V_{IN} \cdot I_{OUT} \cdot T_{SW} \cdot F_{SW}$$

where T_{RISE} and T_{FALL} are the overlap times of the voltage across the power switch (V_{DS}) and the current flowing into it during turn-on and turn-off phases, as shown in [Figure 16](#). T_{SW} is the equivalent switching time. For this device the typical value for the equivalent switching time is 40 ns.

- c) Quiescent current losses, calculated as:

Equation 38

$$P_Q = V_{IN} \cdot I_Q$$

where I_Q is the quiescent current ($I_Q = 2.4$ mA).

The junction temperature T_J can be calculated as:

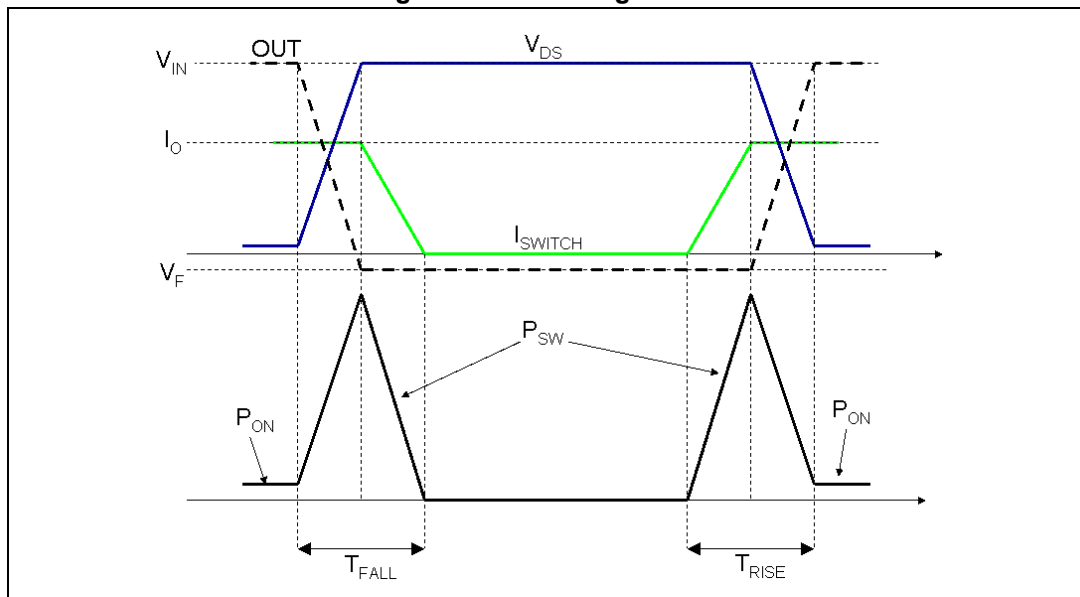
Equation 39

$$T_J = T_A + R_{thJA} \cdot P_{TOT}$$

where T_A is the ambient temperature and P_{TOT} is the sum of the power losses just seen.

$R_{th(JA)}$ is the equivalent thermal resistance junction to ambient of the device; it can be calculated as the parallel of many paths of heat conduction from the junction to the ambient. For this device the path through the exposed pad is the one conducting the largest amount of heat. The $R_{th(JA)}$ measured on the demonstration board described in the following paragraph is about 40 °C/W for the HSOP8 package.

Figure 16. Switching losses



6.6 Layout considerations

The PC board layout of the switching DC/DC regulator is very important to minimize the noise injected in high impedance nodes and interference generated by the high switching current loops.

In a step-down converter, the input loop (including the input capacitor, the power MOSFET and the freewheeling diode) is the most critical one. This is due to the fact that the high value pulsed current is flowing through it. In order to minimize the EMI, this loop must be as short as possible.

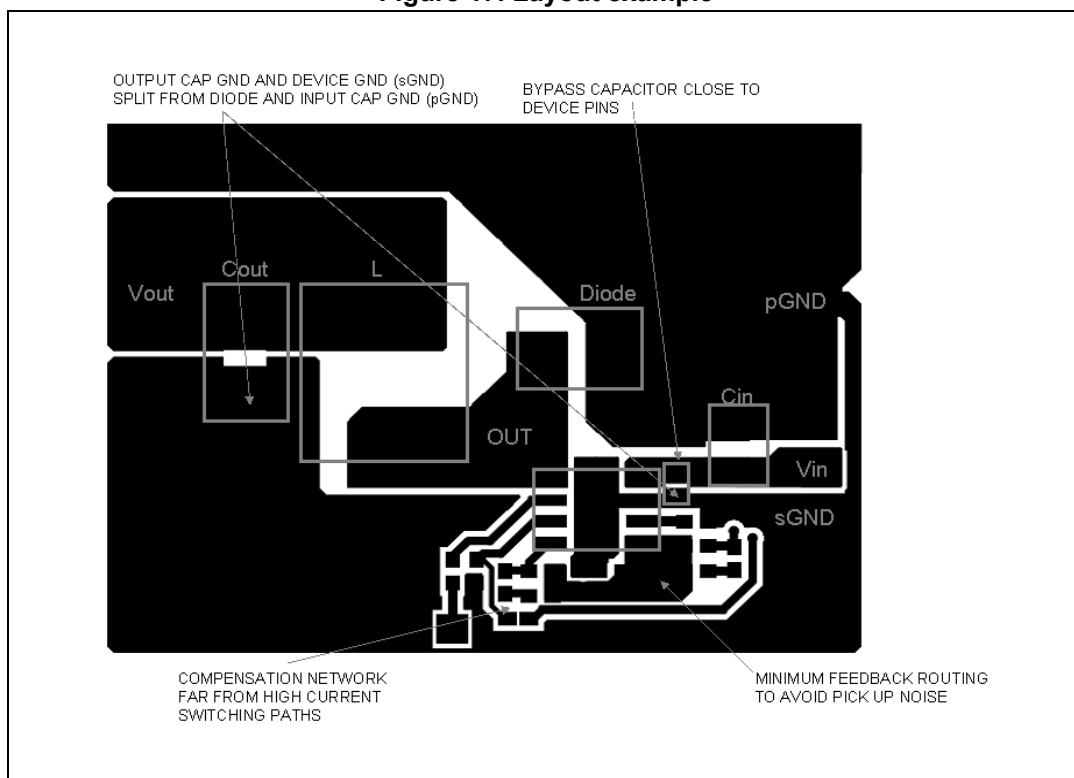
The feedback pin (FB) connection to the external resistor divider is a high impedance node, so the interference can be minimized by placing the routing of the feedback node as far as possible from the high current paths. To reduce the pick-up noise, the resistor divider must be placed very close to the device.

To filter the high frequency noise, a small bypass capacitor (220 nF - 1 μ F) can be added as close as possible to the input voltage pin of the device.

Thanks to the exposed pad of the device, the ground plane helps to reduce the thermal resistance junction to ambient; so a large ground plane enhances the thermal performance of the converter allowing high power conversion.

In [Figure 17](#) a layout example is shown.

Figure 17. Layout example



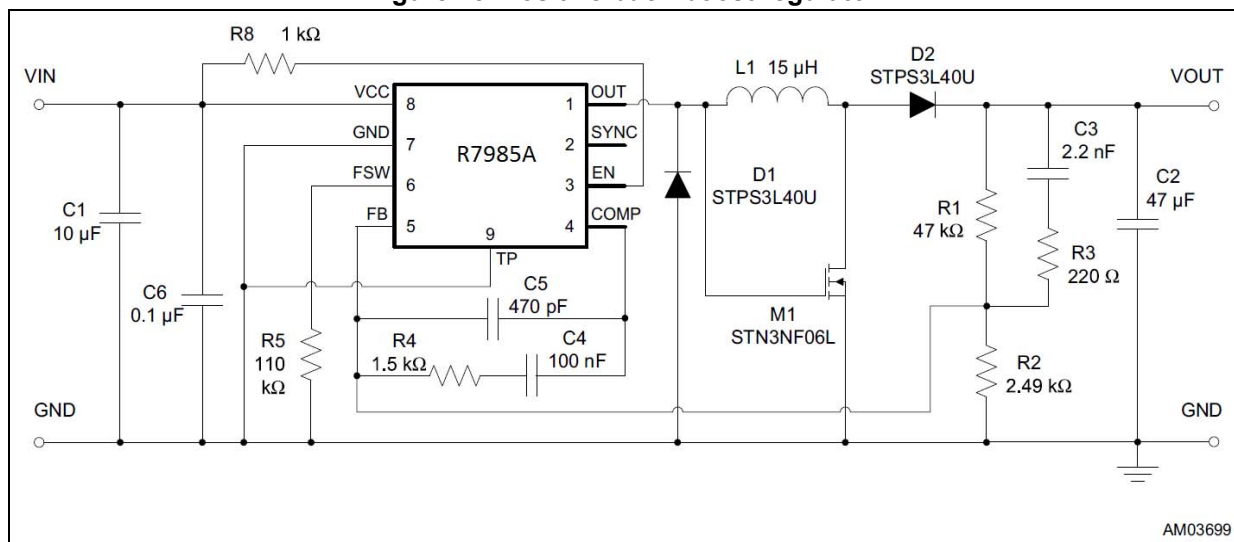
7 Application ideas

7.1 Positive buck-boost

The R7985A can implement the step-up/down converter with a positive output voltage.

[Figure 18](#) shows the schematic: one power MOSFET and one Schottky diode are added to the standard buck topology to provide a 12 V output voltage with input voltage from 4.5 V to 38 V.

Figure 18. Positive buck-boost regulator



The relationship between input and output voltage is:

Equation 40

$$V_{OUT} = V_{IN} \cdot \frac{D}{1-D}$$

so the duty cycle is:

Equation 41

$$D = \frac{V_{OUT}}{V_{OUT} + V_{IN}}$$

The output voltage isn't limited by the maximum operating voltage of the device (38 V), because the output voltage is sensed only through the resistor divider. The external power MOSFET maximum drain to source voltage, must be higher than output voltage; the maximum gate to source voltage must be higher than the input voltage (in [Figure 18](#), if V_{IN} is higher than 16 V, the gate must be protected through a Zener diode and resistor).

The current flowing through the internal power MOSFET is transferred to the load only during the OFF time, so according to the maximum DC switch current (2.0 A), the maximum output current for the buck boost topology can be calculated from [Equation 42](#).

Equation 42

$$I_{SW} = \frac{I_{OUT}}{1-D} < 2 \text{ A}$$

where I_{SW} is the average current in the embedded power MOSFET in the ON time.

To chose the right value of the inductor and to manage transient output current, which, for a short time, can exceed the maximum output current calculated by [Equation 42](#), also the peak current in the power MOSFET must be calculated. The peak current, shown in [Equation 43](#), must be lower than the minimum current limit (2.5 A).

Equation 43

$$I_{SW,PK} = \frac{I_{OUT}}{1-D} \cdot \left[1 + \frac{r}{2} \right] < 3.7 \text{ A}$$

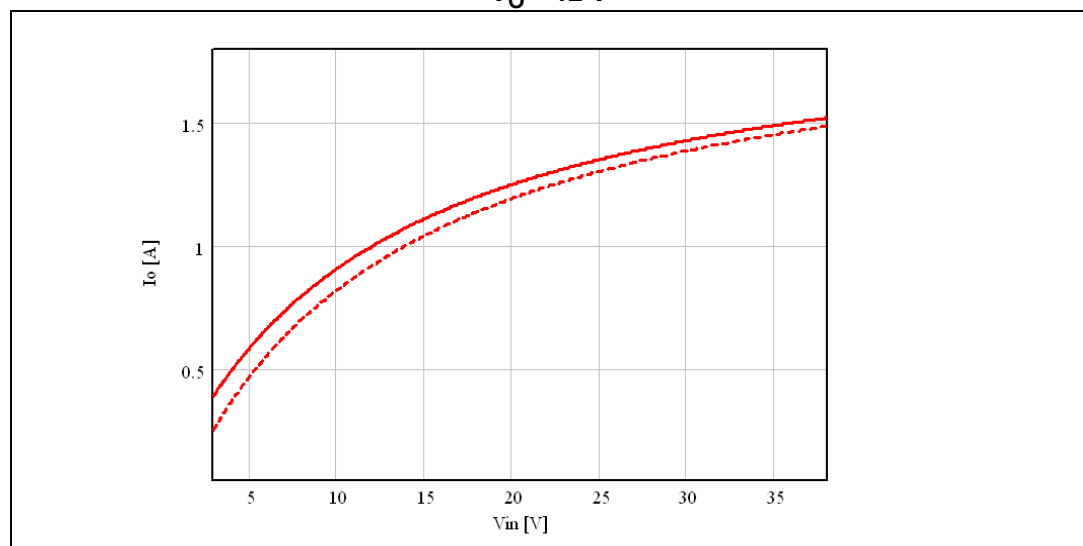
where r is defined as the ratio between the inductor current ripple and the inductor DC current.

Therefore, in the buck boost topology the maximum output current depends on the application conditions (firstly input and output voltage, secondly switching frequency and inductor value).

In [Figure 19](#) the maximum output current for the above configuration is depicted, varying the input voltage from 4.5 V to 38 V.

The dashed line considers a more accurate estimation of the duty cycles given [Equation 44](#), where power losses across diodes, the external power MOSFET, and the internal power MOSFET are taken into account.

**Figure 19. Maximum output current according to max. DC switch current (2.0 A):
 $V_O = 12 \text{ V}$**



Equation 44

$$D = \frac{V_{OUT} + 2 \cdot V_D}{V_{IN} - V_{SW} - V_{SWE} + V_{OUT} + 2 \cdot V_D}$$

where V_D is the voltage drop across the diodes, V_{SW} and V_{SWE} across the internal and external power MOSFET.

7.2 Inverting buck-boost

The R7985A device can implement the step-up/down converter with a negative output voltage.

[Figure 18](#) shows the schematic to regulate -5 V: no further external components are added to the standard buck topology.

The relationship between input and output voltage is:

Equation 45

$$V_{OUT} = -V_{IN} \cdot \frac{D}{1-D}$$

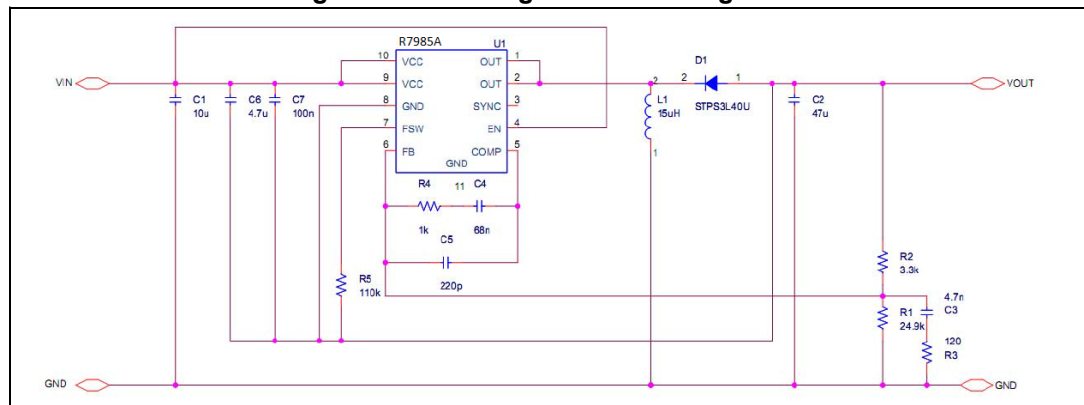
so the duty cycle is:

Equation 46

$$D = \frac{V_{OUT}}{V_{OUT} - V_{IN}}$$

As in the positive one, in the inverting buck-boost the current flowing through the power MOSFET is transferred to the load only during the OFF time. So according to the maximum DC switch current (2.0 A), the maximum output current can be calculated from [Equation 42](#), where the duty cycle is given by [Equation 46](#).

Figure 20. Inverting buck-boost regulator



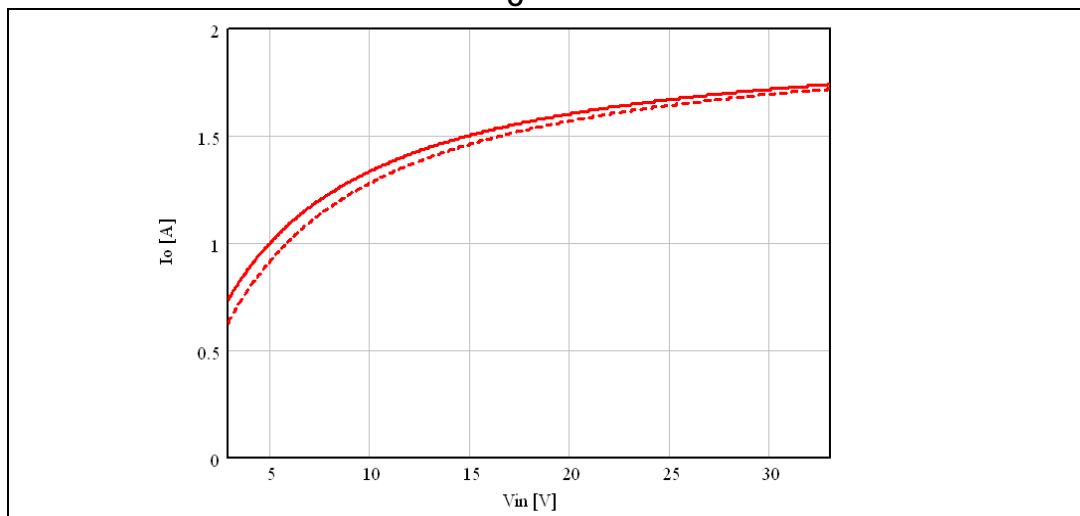
The GND pin of the device is connected to the output voltage so, given the output voltage, the input voltage range is limited by the maximum voltage the device can withstand across VCC and GND (38 V). Therefore, if the output is -5 V, the input voltage can range from 4.5 V to 33 V.

As in the positive buck-boost, the maximum output current according to application conditions is shown in [Figure 21](#). The dashed line considers a more accurate estimation of the duty cycles given by [Equation 47](#), where power losses across diodes and the internal power MOSFET are taken into account.

Equation 47

$$D = \frac{V_{OUT} - V_D}{-V_{IN} - V_{SW} + V_{OUT} - V_D}$$

**Figure 21. Maximum output current according to switch max. peak current (2.0 A):
 $V_O = -5\text{ V}$**



8 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

Figure 22. HSOP8 package outline

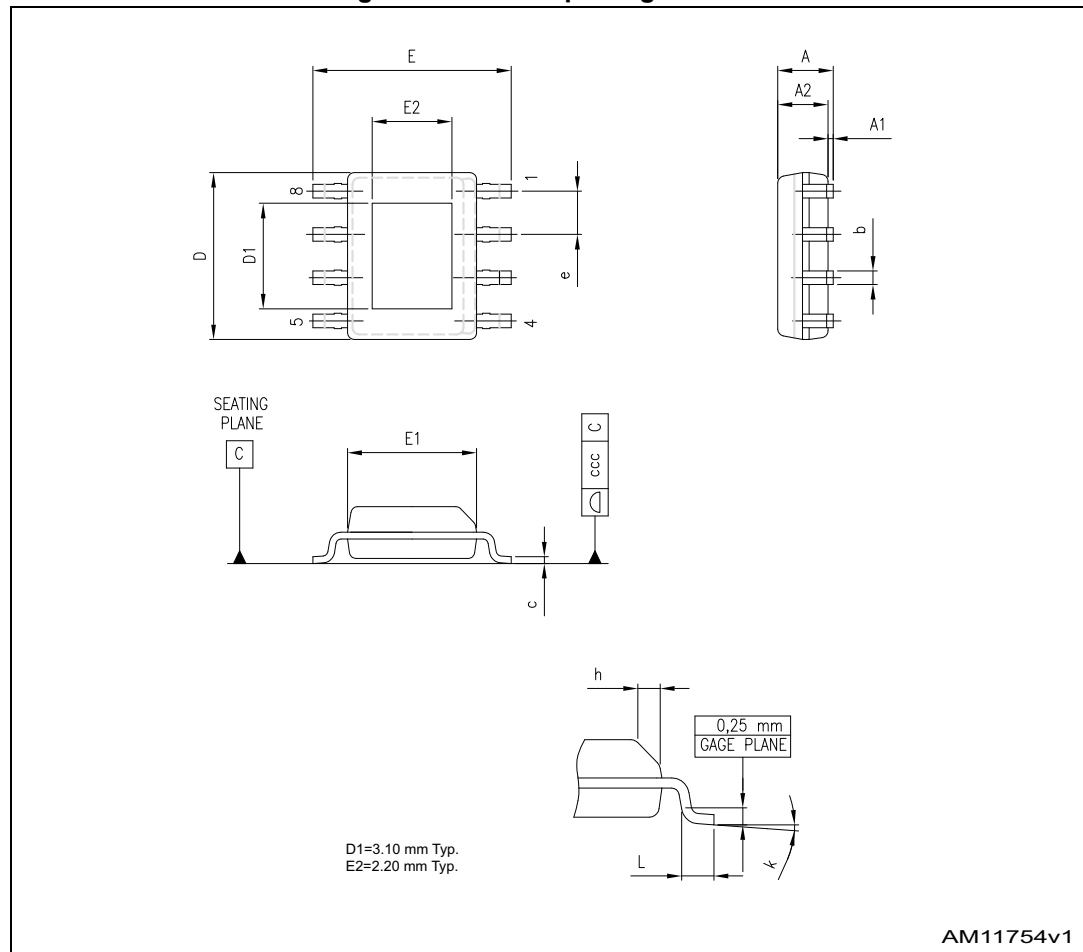


Table 9. HSOP8 package mechanical data

Symbol	Dimensions (mm)		
	Min.	Typ.	Max.
A			1.70
A1	0.00		0.150
A2	1.25		
b	0.31		0.51
c	0.17		0.25
D	4.80	4.90	5.00
E	5.80	6.00	6.20
E1	3.80	3.90	4.00
e		1.27	
h	0.25		0.50
L	0.40		1.27
k	0.00		8.00
ccc			0.10

9 Ordering information

Table 10. Ordering information

Order code	Package	Packaging
R7985A	HSOP8	Tube
R7985ATR	HSOP8	Tape and reel

10 **Revision history**

Table 11. Document revision history

Date	Revision	Changes
06-Oct-2014	1	Initial release.



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