Features

- High voltage rail up to 1700 V
- Driver current capability: 4 A sink/source @25°C
- dV/dt transient immunity ±100 V/ns in full temperature range
- Overall input-output propagation delay: 75 ns
- Separate sink and source option for easy gate driving configuration
- 4 A Miller CLAMP dedicated pin option
- UVLO function
- Gate driving voltage up to 26 V
- 3.3 V, 5 V TTL/CMOS inputs with hysteresis
- Temperature shut-down protection
- Standby function
- Narrow body SO8

Application

- Motor driver for home appliances, factory automation, industrial drives and fans.
- 600/1200 V inverters
- Battery chargers
- Induction heating
- Welding
- UPS
- Power supply units
- DC-DC converters
- Power Factor Correction

Description

The STGAP2S is a single gate driver which provides galvanic isolation between the gate driving channel and the low voltage control and interface circuitry.

The gate driver is characterized by 4 A capability and rail-to-rail outputs, making the device also suitable for mid and high power applications such as power conversion and motor driver inverters in industrial applications. The device is available in two different configurations. The configuration with separated output pins allows to independently optimize turn-on and turn-off by using dedicated gate resistors. The configuration featuring single output pin and Miller CLAMP function prevents gate spikes during fast commutations in half-bridge topologies. Both configurations provide high flexibility and bill of material reduction for external components.

The device integrates UVLO and thermal shutdown protection functions to facilitate the design of highly reliable systems. Dual input pins allow the selection of signal polarity control and implementation of HW interlocking protection to avoid cross-conduction in case of controller malfunction. The input to output propagation delay is less than 75 ns, which delivers high PWM control accuracy. A standby mode is available to reduce idle power consumption.
1 Block diagram

Figure 1. Block diagram - separated outputs option

Figure 2. Block diagram - single output and Miller clamp option
2 Pin description and connection diagram

Figure 3. Pin connection (top view), separated outputs option

Figure 4. Pin connection (top view), single output and Miller clamp option

Table 1. Pin description

<table>
<thead>
<tr>
<th>Pin no.</th>
<th>Pin name</th>
<th>Type</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Figure 3</td>
<td>Figure 4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>VDD</td>
<td>Power supply</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>IN+</td>
<td>Logic input</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>IN-</td>
<td>Logic input</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>GND</td>
<td>Power supply</td>
</tr>
<tr>
<td>5</td>
<td>5</td>
<td>VH</td>
<td>Power supply</td>
</tr>
<tr>
<td>-</td>
<td>6</td>
<td>GOUT</td>
<td>Analog output</td>
</tr>
<tr>
<td>-</td>
<td>7</td>
<td>CLAMP</td>
<td>Analog output</td>
</tr>
<tr>
<td>6</td>
<td>-</td>
<td>GON</td>
<td>Analog output</td>
</tr>
<tr>
<td>7</td>
<td>-</td>
<td>GOFF</td>
<td>Analog output</td>
</tr>
<tr>
<td>8</td>
<td>8</td>
<td>GNDISO</td>
<td>Power supply</td>
</tr>
</tbody>
</table>
3 Electrical data

3.1 Absolute maximum ratings

Table 2. Absolute maximum ratings

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test condition</th>
<th>Min.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VDD</td>
<td>Logic supply voltage vs. GND</td>
<td></td>
<td>-0.3</td>
<td>6.5</td>
<td>V</td>
</tr>
<tr>
<td>VLOGIC</td>
<td>Logic pins voltage vs. GND</td>
<td></td>
<td>-0.3</td>
<td>6.5</td>
<td>V</td>
</tr>
<tr>
<td>VH</td>
<td>Positive supply voltage (VH vs. GNDISO)</td>
<td></td>
<td>-0.3</td>
<td>28</td>
<td>V</td>
</tr>
<tr>
<td>VOUT</td>
<td>Voltage on gate driver outputs (GON, GOFF, CLAMP vs. GNDISO)</td>
<td></td>
<td>-0.3</td>
<td>VH +0.3</td>
<td>V</td>
</tr>
<tr>
<td>VISO-OP</td>
<td>Input to output isolation voltage (GND vs. GNDISO)</td>
<td>DC or peak</td>
<td>-1700</td>
<td>+1700</td>
<td>V</td>
</tr>
<tr>
<td>TJ</td>
<td>Junction temperature</td>
<td></td>
<td>-40</td>
<td>150</td>
<td>°C</td>
</tr>
<tr>
<td>TS</td>
<td>Storage temperature</td>
<td></td>
<td>-50</td>
<td>150</td>
<td>°C</td>
</tr>
<tr>
<td>PDin</td>
<td>Power dissipation input chip</td>
<td>TA =25 °C</td>
<td>-</td>
<td>10</td>
<td>mW</td>
</tr>
<tr>
<td>PDout</td>
<td>Power dissipation output chip</td>
<td>TA =25 °C</td>
<td>-</td>
<td>850</td>
<td>mW</td>
</tr>
<tr>
<td>ESD</td>
<td>HBM (human body model)</td>
<td></td>
<td>-</td>
<td>2</td>
<td>kV</td>
</tr>
</tbody>
</table>

3.2 Thermal data

Table 3. Thermal data

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Package</th>
<th>Value</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rθ(JA)</td>
<td>Thermal resistance junction to ambient</td>
<td>SO-8</td>
<td>123</td>
<td>°C/W</td>
</tr>
</tbody>
</table>

3.3 Recommended operating conditions

Table 4. Recommended operating conditions

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test conditions</th>
<th>Min.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VDD</td>
<td>Logic supply voltage vs. GND</td>
<td>-</td>
<td>3.1</td>
<td>5.5</td>
<td>V</td>
</tr>
<tr>
<td>VLOGIC</td>
<td>Logic pins voltage vs. GND</td>
<td>-</td>
<td>0</td>
<td>5.5</td>
<td>V</td>
</tr>
<tr>
<td>VH</td>
<td>Positive supply voltage (VH vs. GNDISO)</td>
<td>-</td>
<td>9.6</td>
<td>26</td>
<td>V</td>
</tr>
<tr>
<td>FSW</td>
<td>Maximum switching frequency (1)</td>
<td>-</td>
<td>-</td>
<td>1</td>
<td>MHz</td>
</tr>
<tr>
<td>IOUT</td>
<td>Output pulse width (GOUT, GON-GOFF)</td>
<td>-</td>
<td>100</td>
<td>-</td>
<td>ns</td>
</tr>
<tr>
<td>TJ</td>
<td>Operating junction temperature</td>
<td>-</td>
<td>-40</td>
<td>125</td>
<td>°C</td>
</tr>
</tbody>
</table>

1. Actual limit depends on power dissipation and TJ.
## 4 Electrical characteristics

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Pin</th>
<th>Parameter</th>
<th>Test conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_{\text{Don}}$</td>
<td>IN+, IN-</td>
<td>Input to output propagation delay ON</td>
<td>-</td>
<td>50</td>
<td>75</td>
<td>90</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{\text{Doff}}$</td>
<td>IN+, IN-</td>
<td>Input to output propagation delay OFF</td>
<td>-</td>
<td>50</td>
<td>75</td>
<td>90</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{\text{r}}$</td>
<td>-</td>
<td>Rise time</td>
<td>$C_L = 4.7 \text{ nF}, 10%$ to $90%$</td>
<td>-</td>
<td>30</td>
<td>-</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{\text{f}}$</td>
<td>-</td>
<td>Fall time</td>
<td>$C_L = 4.7 \text{ nF}, 90%$ to $10%$</td>
<td>-</td>
<td>30</td>
<td>-</td>
<td>ns</td>
</tr>
<tr>
<td>PWD</td>
<td>-</td>
<td>Pulse width distortion $</td>
<td>t_{\text{Don}} - t_{\text{Doff}}</td>
<td>$</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>$t_{\text{degilitch}}$</td>
<td>IN+, IN-</td>
<td>Inputs deglitch filter</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>20</td>
<td>40</td>
</tr>
<tr>
<td>CMTI</td>
<td>-</td>
<td>Common-mode transient immunity, $</td>
<td>dV_{\text{ ISO}}/dt</td>
<td>$</td>
<td>$V_{\text{ CM}} = 1500 \text{ V}$, see Figure 13</td>
<td>100</td>
<td>-</td>
</tr>
</tbody>
</table>

### Supply voltage

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Pin</th>
<th>Parameter</th>
<th>Test conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{\text{H}_{\text{on}}}$</td>
<td>-</td>
<td>VH UVLO turn-on threshold</td>
<td>-</td>
<td>8.6</td>
<td>9.1</td>
<td>9.6</td>
<td>V</td>
</tr>
<tr>
<td>$V_{\text{H}_{\text{off}}}$</td>
<td>-</td>
<td>VH UVLO turn-off threshold</td>
<td>-</td>
<td>7.9</td>
<td>8.4</td>
<td>8.9</td>
<td>V</td>
</tr>
<tr>
<td>$V_{\text{H}_{\text{hyst}}}$</td>
<td>-</td>
<td>VH UVLO hysteresis</td>
<td>-</td>
<td>0.60</td>
<td>0.75</td>
<td>0.95</td>
<td>V</td>
</tr>
<tr>
<td>$I_{\text{QH}}$</td>
<td>-</td>
<td>VH quiescent supply current</td>
<td>$V_{\text{ H}} = 7 \text{ V}$</td>
<td>-</td>
<td>1.3</td>
<td>1.8</td>
<td>mA</td>
</tr>
<tr>
<td>$I_{\text{QH}_{\text{SBY}}}$</td>
<td>-</td>
<td>Standby VH quiescent supply current</td>
<td>Standby mode</td>
<td>400</td>
<td>550</td>
<td></td>
<td>μA</td>
</tr>
<tr>
<td>SafeClp</td>
<td>-</td>
<td>GOFF active clamp</td>
<td>$I_{\text{GOFF}} = 0.2 \text{ A}$; $V_{\text{ H}}$ floating</td>
<td>-</td>
<td>2</td>
<td>2.3</td>
<td>V</td>
</tr>
<tr>
<td>$I_{\text{QDD}}$</td>
<td>-</td>
<td>VDD quiescent supply current</td>
<td>-</td>
<td>1</td>
<td>1.3</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>$I_{\text{QDD}_{\text{SBY}}}$</td>
<td>-</td>
<td>Standby VDD quiescent supply current</td>
<td>Standby mode</td>
<td>40</td>
<td>65</td>
<td></td>
<td>μA</td>
</tr>
</tbody>
</table>

### Logic inputs

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Pin</th>
<th>Parameter</th>
<th>Test conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{\text{IL}}$</td>
<td>IN+, IN-</td>
<td>Low level logic threshold voltage</td>
<td>-</td>
<td>0.29 · $V_{\text{ DDD}}$</td>
<td>0.37 · $V_{\text{ DDD}}$</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$V_{\text{IH}}$</td>
<td>IN+, IN-</td>
<td>High level logic threshold voltage</td>
<td>-</td>
<td>0.62 · $V_{\text{ DDD}}$</td>
<td>0.70 · $V_{\text{ DDD}}$</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$I_{\text{INH}}$</td>
<td>IN+, IN-</td>
<td>INx logic “1” input bias current</td>
<td>$\text{INx} = 5 \text{ V}$</td>
<td>33</td>
<td>50</td>
<td>77</td>
<td>μA</td>
</tr>
<tr>
<td>$I_{\text{INI}}$</td>
<td>IN+, IN-</td>
<td>INx logic “0” input bias current</td>
<td>$\text{INx} = \text{GND}$</td>
<td>-</td>
<td>-</td>
<td>1</td>
<td>μA</td>
</tr>
<tr>
<td>$R_{\text{pd}}$</td>
<td>IN+, IN-</td>
<td>Inputs pull-down resistors</td>
<td>$\text{INx} = 5 \text{ V}$</td>
<td>65</td>
<td>100</td>
<td>150</td>
<td>kΩ</td>
</tr>
</tbody>
</table>

### Driver buffer section

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Pin</th>
<th>Parameter</th>
<th>Test conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{\text{GON}}$</td>
<td>-</td>
<td>Source short-circuit current</td>
<td>$T_{\text{J}} = 25 \text{ °C}$</td>
<td>-</td>
<td>4</td>
<td>-</td>
<td>A</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Source short-circuit current</td>
<td>$T_{\text{J}} = 40 + \pm 125 \text{ °C}$</td>
<td>3</td>
<td>-</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td>$V_{\text{GONH}}$</td>
<td>-</td>
<td>Source output high level voltage</td>
<td>$I_{\text{GON}} = 100 \text{ mA}$</td>
<td>$V_{\text{ H}} = 0.15$</td>
<td>$V_{\text{ H}} = 0.125$</td>
<td>-</td>
<td>V</td>
</tr>
</tbody>
</table>
### Electrical characteristics

#### DS12541-Rev 2

**Table 6. Isolation related package specifications**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Value</th>
<th>Unit</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clearance (Minimum External Air Gap)</td>
<td>CLR</td>
<td>4</td>
<td>mm</td>
<td>Measured from input terminals to output terminals, shortest distance through air</td>
</tr>
<tr>
<td>Creepage (*) (Minimum External Tracking)</td>
<td>CPG</td>
<td>4</td>
<td>mm</td>
<td>Measured from input terminals to output terminals, shortest distance path along body</td>
</tr>
<tr>
<td>Comparative Tracking Index (Tracking Resistance)</td>
<td>CTI</td>
<td>≥ 400</td>
<td>V</td>
<td>DIN IEC 112/VDE 0303 Part 1</td>
</tr>
<tr>
<td>Isolation Group</td>
<td></td>
<td>II</td>
<td></td>
<td>Material Group (DIN VDE 0110, 1/89, Table 1)</td>
</tr>
</tbody>
</table>

---

### Symbol, Pin, Parameter, Test conditions

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Pin</th>
<th>Parameter</th>
<th>Test conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>R&lt;sub&gt;GON&lt;/sub&gt;</td>
<td>-</td>
<td>Source R&lt;sub&gt;DS_ON&lt;/sub&gt;</td>
<td>I&lt;sub&gt;GON&lt;/sub&gt; = 100 mA</td>
<td>-</td>
<td>1.125</td>
<td>1.5</td>
<td>Ω</td>
</tr>
<tr>
<td>I&lt;sub&gt;GOFF&lt;/sub&gt;</td>
<td>-</td>
<td>Sink short-circuit current</td>
<td>T&lt;sub&gt;J&lt;/sub&gt; = 25 °C</td>
<td>-</td>
<td>4</td>
<td>-</td>
<td>A</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>T&lt;sub&gt;J&lt;/sub&gt; = -40 + 125 °C&lt;sup&gt;(1)&lt;/sup&gt;</td>
<td>3</td>
<td>-</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td>V&lt;sub&gt;GOFF&lt;/sub&gt;L</td>
<td>-</td>
<td>Sink output low level voltage</td>
<td>I&lt;sub&gt;GOFF&lt;/sub&gt; = 100 mA</td>
<td>-</td>
<td>96</td>
<td>120</td>
<td>mV</td>
</tr>
<tr>
<td>R&lt;sub&gt;GOFF&lt;/sub&gt;</td>
<td>-</td>
<td>Sink R&lt;sub&gt;DS_ON&lt;/sub&gt;</td>
<td>I&lt;sub&gt;GOFF&lt;/sub&gt; = 100 mA</td>
<td>-</td>
<td>0.96</td>
<td>1.2</td>
<td>Ω</td>
</tr>
</tbody>
</table>

#### Miller Clamp function (STGAP2SC only)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Value</th>
<th>Unit</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLAMP voltage threshold</td>
<td>V&lt;sub&gt;CLAMP&lt;/sub&gt;&lt;sub&gt;th&lt;/sub&gt;</td>
<td>-</td>
<td>V</td>
<td>V&lt;sub&gt;CLAMP&lt;/sub&gt; vs. GNDISO</td>
</tr>
</tbody>
</table>
| CLAMP short-circuit current | I<sub>CLAMP</sub> | -     | A    | V<sub>CLAMP</sub> = 15 V
T<sub>J</sub> = 25 °C
T<sub>J</sub> = -40 + 125 °C<sup>(1)</sup> |
| CLAMP low level output voltage | V<sub>CLAMP</sub><sub>L</sub> | -     | mV   | I<sub>CLAMP</sub> = 100 mA
T<sub>J</sub> = 25 °C
T<sub>J</sub> = -40 + 125 °C<sup>(1)</sup> |
| CLAMP R<sub>DS_ON</sub> | R<sub>CLAMP</sub> | -     | Ω    | I<sub>CLAMP</sub> = 100 mA                                               |

---

**Overtemperature protection**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Value</th>
<th>Unit</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Shutdown temperature</td>
<td>T&lt;sub&gt;SD&lt;/sub&gt;</td>
<td>-</td>
<td>°C</td>
<td></td>
</tr>
<tr>
<td>Temperature hysteresis</td>
<td>T&lt;sub&gt;Hys&lt;/sub&gt;</td>
<td>-</td>
<td>°C</td>
<td></td>
</tr>
</tbody>
</table>

---

**Standby**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Value</th>
<th>Unit</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standby time</td>
<td>t&lt;sub&gt;STBY&lt;/sub&gt;</td>
<td>See Section 5.3</td>
<td>200</td>
<td>280</td>
</tr>
<tr>
<td>Wake-up time</td>
<td>t&lt;sub&gt;WUP&lt;/sub&gt;</td>
<td>See Section 5.3</td>
<td>10</td>
<td>20</td>
</tr>
<tr>
<td>Wake-up delay</td>
<td>t&lt;sub&gt;awake&lt;/sub&gt;</td>
<td>See Section 5.3</td>
<td>90</td>
<td>140</td>
</tr>
<tr>
<td>Standby filter</td>
<td>t&lt;sub&gt;STBYfilt&lt;/sub&gt;</td>
<td>See Section 5.3</td>
<td>200</td>
<td>280</td>
</tr>
</tbody>
</table>

---

1. Characterization data, not tested in production.
<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Test conditions</th>
<th>Characteristic</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input to Output test voltage</td>
<td>V_PPR</td>
<td>Method a, Type test</td>
<td>V_PPR = 2720, t_m = 10 s</td>
<td>2720</td>
</tr>
<tr>
<td>In accordance with VDE 0884-11</td>
<td></td>
<td>Partial discharge &lt; 5 pC</td>
<td></td>
<td>V_PEAK</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Method b1, 100 % Production test</td>
<td>V_PPR = 3200, t_m = 1 s</td>
<td>3200</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Partial discharge &lt; 5 pC</td>
<td></td>
<td>V_PEAK</td>
</tr>
<tr>
<td>Transient Overvoltage (Highest Allowable Overvoltage)</td>
<td>V_IOTM</td>
<td>t_{ini} = 60 s, Type test</td>
<td></td>
<td>4800</td>
</tr>
<tr>
<td></td>
<td></td>
<td>V_PPR = 3200, t_m = 1 s</td>
<td></td>
<td>V_PEAK</td>
</tr>
<tr>
<td>Maximum Surge Test Voltage</td>
<td>V_IOSM</td>
<td>Type test</td>
<td></td>
<td>4800</td>
</tr>
<tr>
<td>Isolation Resistance</td>
<td>R_IO</td>
<td>V_{IO} = 500 V, Type test</td>
<td></td>
<td>&gt;10^9</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Ω</td>
</tr>
</tbody>
</table>

**Table 8. UL 1577 Tests**

<table>
<thead>
<tr>
<th>Description</th>
<th>Symbol</th>
<th>Characteristic</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Isolation Withstand Voltage, 1 min (Type test)</td>
<td>V_ISO</td>
<td>2828/4000</td>
<td>V_{rms}/P_{EAK}</td>
</tr>
<tr>
<td>Isolation Voltage, 1 sec (100% production)</td>
<td>V_ISOTest</td>
<td>3394/4800</td>
<td>V_{rms}/P_{EAK}</td>
</tr>
</tbody>
</table>
5 Functional description

5.1 Gate driving power supply and UVLO
The STGAP2S is a flexible and compact gate driver with 4 A output current and rail-to-rail outputs. The device allows implementation of either unipolar or bipolar gate driving.

![Figure 5. Power supply configuration for unipolar and bipolar gate driving](image)

Undervoltage protection is available on VH supply pin. A fixed hysteresis sets the turn-off threshold, thus avoiding intermittent operation.

When VH voltage goes below the $V_{H\text{off}}$ threshold, the output buffer goes in "safe state". When VH voltage reaches the $V_{H\text{on}}$ threshold, the device returns to normal operation and sets the output according to actual input pins status.

The VDD and VH supply pins must be properly filtered with local bypass capacitors. The use of capacitors with different values in parallel provides both local storage for impulsive current supply and high-frequency filtering. The best filtering is obtained by using low-ESR SMT ceramic capacitors, which are therefore recommended. A 100 nF ceramic capacitor must be placed as close as possible to each supply pin, and a second bypass capacitor with value in the range between 1 µF and 10 µF should be placed close to it.

5.2 Power up, power down and 'safe state'
The following conditions define the "safe state":

- $GOFF = \text{ON state}$
- $GON = \text{high impedance}$
- $CLAMP = \text{ON state}$ (for STGAP2SC)

Such conditions are maintained at power up of the isolated side ($V_{H} < V_{H\text{on}}$) and during whole device power down phase ($V_{H} < V_{H\text{off}}$), regardless of the value of the input pins.

The device integrates a structure which clamps the driver output to a voltage not higher than SafeClp when VH voltage is not high enough to actively turn the internal GOFF MOSFET on. If VH positive supply pin is floating or not supplied the GOFF pin is therefore clamped to a voltage smaller than SafeClp.

If the supply voltage VDD of the control section of the device is not supplied, the output is put in safestate, and remains in such condition until the VDD voltage returns within operative conditions.

After power-up of both isolated and low voltage side the device output state depends on the input pins’ status.
5.3 **Control inputs**

The device is controlled through the IN+ and IN- logic inputs, in accordance to the truth table described in Table 9.

<table>
<thead>
<tr>
<th>Input pins</th>
<th>Output pins</th>
</tr>
</thead>
<tbody>
<tr>
<td>IN+</td>
<td>IN-</td>
</tr>
<tr>
<td>L</td>
<td>L</td>
</tr>
<tr>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>L</td>
<td>H</td>
</tr>
<tr>
<td>H</td>
<td>H</td>
</tr>
</tbody>
</table>

Adeglitch filter allow the input pins to ignore signals with duration shorter than $t_{\text{deglish}}$, so preventing noise spikes possibly present in the application from generating unwanted commutations.

5.4 **Miller clamp function**

The Miller clamp function allows the control of the Miller current during the power stage switching in half-bridge configurations. When the external power transistor is in the OFF state, the driver operates to avoid the induced turn-on phenomenon that may occur when the other switch in the same leg is being turned on, due to the $C_{GD}$ capacitance.

During the turn-off period the gate of the external switch is monitored through the CLAMP pin. The CLAMP switch is activated when gate voltage goes below the voltage threshold, $V_{\text{CLAMPth}}$, thus creating a low impedance path between the switch gate and the GNDISO pin.

5.5 **Watchdog**

The isolated HV side has a watchdog function in order to identify when it is not able to communicate with LV side, for example because the VDD of the LV side is not supplied. In this case the output of the driver is forced in “safe state” until communication link is properly established again.

5.6 **Thermal shutdown protection**

The device provides a thermal shutdown protection. When junction temperature reaches the TSD temperature threshold, the device is forced in “safe state”. The device operation is restored as soon as the junction temperature is lower than $T_{\text{SD}} - T_{\text{hys}}$. 
5.7 Standby function

In order to reduce the power consumption of both control interface and gate driving sides the device can be put in standby mode. In standby mode the quiescent current from VDD and VH supply pins is reduced to $I_{QDDSBY}$ and $I_{QHBSBY}$ respectively, and the output remains in 'safe state' (the output is actively forced low).

The way to enter standby is to keep both IN+ and IN- high ("standby" value) for a time longer than $t_{STBY}$. During standby the inputs can change from the "stand-by" value.

To exit stand-by, IN+ and IN- must be put in any combination different from the "standby" value for a time longer than $t_{stbyfilt}$, and then in the "standby" value for a time $t$ such that $t_{WUP} < t < t_{STBY}$.

When the input configuration is changed from the "standby" value the output is enabled and set according to inputs state after a time $t_{awake}$.

**Figure 6. Standby state sequences**

**Sequence to enter stand-by mode**

<table>
<thead>
<tr>
<th>IN+ &amp; IN-</th>
<th>Device status</th>
<th>Output</th>
</tr>
</thead>
<tbody>
<tr>
<td>active</td>
<td>active</td>
<td>active</td>
</tr>
<tr>
<td>stand-by</td>
<td>stand-by</td>
<td>safe-state</td>
</tr>
</tbody>
</table>

**Sequence to exit stand-by mode**

<table>
<thead>
<tr>
<th>IN+ &amp; IN-</th>
<th>Device status</th>
<th>Output</th>
</tr>
</thead>
<tbody>
<tr>
<td>active</td>
<td>active</td>
<td>active</td>
</tr>
<tr>
<td>stand-by</td>
<td>stand-by</td>
<td>safe-state</td>
</tr>
</tbody>
</table>

$\text{STGAP2S}$
6 Typical application diagram

Figure 7. Typical application diagram - separated outputs

Figure 8. Typical application diagram - separated outputs and negative gate driving
Figure 9. Typical application diagram - Miller clamp

Figure 10. Typical application diagram - Miller clamp and negative gate driving
7 Layout

7.1 Layout guidelines and considerations

In order to optimize the PCB layout, following considerations should be taken into account:

• SMT ceramic capacitors (or different types of low-ESR and low-ESL capacitors) must be placed close to each supply rail pins. A 100 nF capacitor must be placed between VDD and GND and between VH and GNDISO, as close as possible to device pins, in order to filter high-frequency noise and spikes. In order to provide local storage for pulsed current a second capacitor with value in the range between 1 µF and 10 µF should also be placed close to the supply pins.

• As a good practice it is suggested to add filtering capacitors close to logic inputs of the device (IN+, IN-), in particular for fast switching or noisy applications.

• The power transistors must be placed as close as possible to the gate driver, so to minimize the gate loop area and inductance that might bring to noise or ringing.

• To avoid degradation of the isolation between the primary and secondary side of the driver, there should not be any trace or conductive area below the driver.

• If the system has multiple layers, it is recommended to connect the VH and GNDISO pins to internal ground or power planes through multiple vias of adequate size. These vias should be located close to the IC pins to maximize thermal conductivity.

7.2 Layout example

An example of STGAP2SC Half-Bridge PCB layout with main signals highlighted by different colors is shown in Figure 11. It is recommended to follow this example for proper positioning and connection of filtering capacitors.

Figure 11. Layer traces and copper
Figure 12. Timings definition

Figure 13. CMTI test circuit
In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

9.1 SO-8 package information
### Table 10: SO-8 package mechanical data

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<tr>
<th>Dim.</th>
<th>mm</th>
<th>Notes</th>
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<td></td>
<td>Min.</td>
<td>Typ.</td>
</tr>
<tr>
<td>A</td>
<td>1.35</td>
<td></td>
</tr>
<tr>
<td>A1</td>
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<td></td>
</tr>
<tr>
<td>b</td>
<td>0.35</td>
<td></td>
</tr>
<tr>
<td>c</td>
<td>0.19</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>4.8</td>
<td></td>
</tr>
<tr>
<td>E1</td>
<td>3.8</td>
<td>3.9</td>
</tr>
<tr>
<td>E</td>
<td>5.8</td>
<td>6</td>
</tr>
<tr>
<td>e</td>
<td></td>
<td>1.27 BSC</td>
</tr>
<tr>
<td>L</td>
<td>0.4</td>
<td></td>
</tr>
<tr>
<td>h</td>
<td>0.25</td>
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</tr>
<tr>
<td>Θ</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>Θ1</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>aaa</td>
<td></td>
<td>0.25</td>
</tr>
<tr>
<td>bbb</td>
<td></td>
<td>0.25</td>
</tr>
<tr>
<td>ccc</td>
<td></td>
<td>0.1</td>
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</tbody>
</table>
Figure 15. SO-8 suggested land pattern
### Table 11. Device summary

<table>
<thead>
<tr>
<th>Order code</th>
<th>Output configuration</th>
<th>Package marking</th>
<th>Package</th>
<th>Packaging</th>
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<tbody>
<tr>
<td>STGAP2SM</td>
<td>GON-GOFF</td>
<td>GAP2S2</td>
<td>SO-8</td>
<td>Tube</td>
</tr>
<tr>
<td>STGAP2SMTR</td>
<td>GON-GOFF</td>
<td>GAP2S2</td>
<td>SO-8</td>
<td>Tape and reel</td>
</tr>
<tr>
<td>STGAP2SCM</td>
<td>GOUT-CLAMP</td>
<td>GAP2SC2</td>
<td>SO-8</td>
<td>Tube</td>
</tr>
<tr>
<td>STGAP2SCMTR</td>
<td>GOUT-CLAMP</td>
<td>GAP2SC2</td>
<td>SO-8</td>
<td>Tape and reel</td>
</tr>
</tbody>
</table>
Revision history

Table 12. Document revision history

<table>
<thead>
<tr>
<th>Date</th>
<th>Version</th>
<th>Changes</th>
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<tr>
<td>06-Jun-2018</td>
<td>1</td>
<td>Initial release.</td>
</tr>
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</table>
| 16-Jul-2021| 2       | Updated Table 4, Table 5, Table 10 and Section 7  
|           |         | Added Table 6, Table 7 and Table 8           |
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</tr>
<tr>
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<td>Pin connection (top view), single output and Miller clamp option</td>
<td>3</td>
</tr>
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<td>Typical application diagram - Miller clamp and negative gate driving</td>
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