TDA7491LP

2 x 5-watt dual BTL class-D audio amplifier

Features
- 5 W + 5 W continuous output power: \( R_L = 8 \Omega \), THD = 10\% at \( V_{CC} = 9 \text{ V} \)
- 5 W + 5 W continuous output power: \( R_L = 4 \Omega \), THD = 10\% at \( V_{CC} = 6.6 \text{ V} \)
- Wide range single supply operation (5 V - 14 V)
- High efficiency (\( \eta = 90\% \))
- Four selectable, fixed gain settings of nominally 20 dB, 26 dB, 30 dB and 32 dB
- Differential inputs minimize common-mode noise
- Filterless operation
- No ‘pop’ at turn-on/off
- Standby and mute features
- Short-circuit protection
- Thermal overload protection
- Externally synchronizable

Description
The TDA7491LP is a dual BTL class-D audio amplifier with single power supply designed for LCD TVs and monitors. Thanks to the high efficiency and exposed-pad-down (EPD) package no separate heatsink is required. Furthermore, the filterless operation allows a reduction in the external component count.

The TDA7491LP is pin-to-pin compatible with the TDA7491P and TDA7491HV.

Table 1. Device summary

<table>
<thead>
<tr>
<th>Order code</th>
<th>Operating temperature</th>
<th>Package</th>
<th>Packaging</th>
</tr>
</thead>
<tbody>
<tr>
<td>TDA7491LP</td>
<td>-40 to 85 °C</td>
<td>PowerSSO-36 EPD</td>
<td>Tube</td>
</tr>
<tr>
<td>TDA7491LP13TR</td>
<td>-40 to 85 °C</td>
<td>PowerSSO-36 EPD</td>
<td>Tape and reel</td>
</tr>
</tbody>
</table>
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1 Device block diagram

Figure 1 shows the block diagram of one of the two identical channels of the TDA7491LP.

Figure 1. Internal block diagram (one channel only)
2 Pin description

2.1 Pin out

Figure 2. Pin connection (top view, PCB view)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUB_GND</td>
<td>1</td>
</tr>
<tr>
<td>OUTPB</td>
<td>2</td>
</tr>
<tr>
<td>OUTPB</td>
<td>3</td>
</tr>
<tr>
<td>PGNDB</td>
<td>4</td>
</tr>
<tr>
<td>PGNDB</td>
<td>5</td>
</tr>
<tr>
<td>PVCCB</td>
<td>6</td>
</tr>
<tr>
<td>PVCCB</td>
<td>7</td>
</tr>
<tr>
<td>OUTNB</td>
<td>8</td>
</tr>
<tr>
<td>OUTNB</td>
<td>9</td>
</tr>
<tr>
<td>OUTNA</td>
<td>10</td>
</tr>
<tr>
<td>OUTNA</td>
<td>11</td>
</tr>
<tr>
<td>PVCCA</td>
<td>12</td>
</tr>
<tr>
<td>PVCCA</td>
<td>13</td>
</tr>
<tr>
<td>PGNDA</td>
<td>14</td>
</tr>
<tr>
<td>PGNDA</td>
<td>15</td>
</tr>
<tr>
<td>OUTPA</td>
<td>16</td>
</tr>
<tr>
<td>OUTPA</td>
<td>17</td>
</tr>
<tr>
<td>PGND</td>
<td>18</td>
</tr>
<tr>
<td>VSS</td>
<td>36</td>
</tr>
<tr>
<td>SVCC</td>
<td>35</td>
</tr>
<tr>
<td>VREF</td>
<td>34</td>
</tr>
<tr>
<td>INNB</td>
<td>33</td>
</tr>
<tr>
<td>INPB</td>
<td>32</td>
</tr>
<tr>
<td>GAIN1</td>
<td>31</td>
</tr>
<tr>
<td>GAIN0</td>
<td>30</td>
</tr>
<tr>
<td>SVR</td>
<td>29</td>
</tr>
<tr>
<td>DIAG</td>
<td>28</td>
</tr>
<tr>
<td>SGND</td>
<td>27</td>
</tr>
<tr>
<td>VDDS</td>
<td>26</td>
</tr>
<tr>
<td>SYNCLK</td>
<td>25</td>
</tr>
<tr>
<td>ROSE</td>
<td>24</td>
</tr>
<tr>
<td>INNA</td>
<td>23</td>
</tr>
<tr>
<td>INPA</td>
<td>22</td>
</tr>
<tr>
<td>MUTE</td>
<td>21</td>
</tr>
<tr>
<td>STBY</td>
<td>20</td>
</tr>
<tr>
<td>VDDPW</td>
<td>19</td>
</tr>
</tbody>
</table>

Exposed pad down: Connect to ground
## 2.2 Pin list

Table 2. Pin description list

<table>
<thead>
<tr>
<th>Number</th>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>SUB_GND</td>
<td>POWER</td>
<td>Connect to the frame</td>
</tr>
<tr>
<td>2,3</td>
<td>OUTPB</td>
<td>OUT</td>
<td>Positive PWM output for right channel</td>
</tr>
<tr>
<td>4,5</td>
<td>PGNDB</td>
<td>POWER</td>
<td>Power stage ground for right channel</td>
</tr>
<tr>
<td>6,7</td>
<td>PVCCB</td>
<td>POWER</td>
<td>Power supply for right channel</td>
</tr>
<tr>
<td>8,9</td>
<td>OUTNB</td>
<td>OUT</td>
<td>Negative PWM output for right channel</td>
</tr>
<tr>
<td>10,11</td>
<td>OUTNA</td>
<td>OUT</td>
<td>Negative PWM output for left channel</td>
</tr>
<tr>
<td>12,13</td>
<td>PVCCA</td>
<td>POWER</td>
<td>Power supply for left channel</td>
</tr>
<tr>
<td>14,15</td>
<td>PGNDA</td>
<td>POWER</td>
<td>Power stage ground for left channel</td>
</tr>
<tr>
<td>16,17</td>
<td>OUTPA</td>
<td>OUT</td>
<td>Positive PWM output for left channel</td>
</tr>
<tr>
<td>18</td>
<td>PGND</td>
<td>POWER</td>
<td>Power stage ground</td>
</tr>
<tr>
<td>19</td>
<td>VDDPW</td>
<td>OUT</td>
<td>3.3-V (nominal) regulator output referred to ground for power stage</td>
</tr>
<tr>
<td>20</td>
<td>STBY</td>
<td>INPUT</td>
<td>Standby mode control</td>
</tr>
<tr>
<td>21</td>
<td>MUTE</td>
<td>INPUT</td>
<td>Mute mode control</td>
</tr>
<tr>
<td>22</td>
<td>INPA</td>
<td>INPUT</td>
<td>Positive differential input of left channel</td>
</tr>
<tr>
<td>23</td>
<td>INNA</td>
<td>INPUT</td>
<td>Negative differential input of left channel</td>
</tr>
<tr>
<td>24</td>
<td>ROSC</td>
<td>OUT</td>
<td>Master oscillator frequency-setting pin</td>
</tr>
<tr>
<td>25</td>
<td>SYNCLK</td>
<td>IN/OUT</td>
<td>Clock in/out for external oscillator</td>
</tr>
<tr>
<td>26</td>
<td>VDDS</td>
<td>OUT</td>
<td>3.3-V (nominal) regulator output referred to ground for signal blocks</td>
</tr>
<tr>
<td>27</td>
<td>SGND</td>
<td>POWER</td>
<td>Signal ground</td>
</tr>
<tr>
<td>28</td>
<td>DIAG</td>
<td>OUT</td>
<td>Open-drain diagnostic output</td>
</tr>
<tr>
<td>29</td>
<td>SVR</td>
<td>OUT</td>
<td>Supply voltage rejection</td>
</tr>
<tr>
<td>30</td>
<td>GAIN0</td>
<td>INPUT</td>
<td>Gain setting input 1</td>
</tr>
<tr>
<td>31</td>
<td>GAIN1</td>
<td>INPUT</td>
<td>Gain setting input 2</td>
</tr>
<tr>
<td>32</td>
<td>INPB</td>
<td>INPUT</td>
<td>Positive differential input of right channel</td>
</tr>
<tr>
<td>33</td>
<td>INNB</td>
<td>INPUT</td>
<td>Negative differential input of right channel</td>
</tr>
<tr>
<td>34</td>
<td>VREF</td>
<td>OUT</td>
<td>Half VDDS (nominal) referred to ground</td>
</tr>
<tr>
<td>35</td>
<td>SVCC</td>
<td>POWER</td>
<td>Signal power supply</td>
</tr>
<tr>
<td>36</td>
<td>VSS</td>
<td>OUT</td>
<td>3.3-V (nominal) regulator output referred to power supply</td>
</tr>
<tr>
<td>-</td>
<td>EP</td>
<td>-</td>
<td>Exposed pad for ground-plane heatsink, to be connected to GND</td>
</tr>
</tbody>
</table>
3 Electrical specifications

3.1 Absolute maximum ratings

Table 3. Absolute maximum ratings

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Value</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{CC}$</td>
<td>DC supply voltage</td>
<td>18</td>
<td>V</td>
</tr>
<tr>
<td>$V_I$</td>
<td>Voltage limits for input pins STBY, MUTE, INNA, INPA, INNB, INPB, GAIN0, GAIN1</td>
<td>-0.3 to 3.6</td>
<td>V</td>
</tr>
<tr>
<td>$T_{op}$</td>
<td>Operating temperature</td>
<td>-40 to 85</td>
<td>°C</td>
</tr>
<tr>
<td>$T_j$</td>
<td>Operating junction temperature</td>
<td>-40 to 150</td>
<td>°C</td>
</tr>
<tr>
<td>$T_{stg}$</td>
<td>Storage temperature</td>
<td>-40 to 150</td>
<td>°C</td>
</tr>
</tbody>
</table>

3.2 Thermal data

Refer also to Section 5.9: Heatsink requirements on page 32.

Table 4. Thermal data

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$R_{thj-case}$</td>
<td>Thermal resistance, junction to case</td>
<td>-</td>
<td>2</td>
<td>3</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{thj-amb}$</td>
<td>Thermal resistance, junction to ambient</td>
<td>-</td>
<td>24</td>
<td>-</td>
<td>°C/W</td>
</tr>
</tbody>
</table>
### Electrical specifications

Unless otherwise stated, the results in *Table 5* below are given for the conditions: $V_{CC} = 9$ V, $R_L$ (load) = $8\Omega$, $R_{OSC} = R_3 = 39$ k$\Omega$, $C_8 = 100$ nF, $f = 1$ kHz, $G_V = 20$ dB, and $T_{amb} = 25^\circ$C.

**Table 5. Electrical specifications**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{CC}$</td>
<td>Supply voltage</td>
<td>-</td>
<td>5</td>
<td>-</td>
<td>14</td>
<td>V</td>
</tr>
<tr>
<td>$I_q$</td>
<td>Total quiescent current</td>
<td>Without LC filter</td>
<td>-</td>
<td>26</td>
<td>35</td>
<td>mA</td>
</tr>
<tr>
<td>$I_{QSTBY}$</td>
<td>Quiescent current in standby</td>
<td>-</td>
<td>-</td>
<td>10</td>
<td>$\mu$A</td>
<td></td>
</tr>
<tr>
<td>$V_{OS}$</td>
<td>Output offset voltage</td>
<td>Play mode</td>
<td>-100</td>
<td>-</td>
<td>100</td>
<td>mV</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Mute mode</td>
<td>-60</td>
<td>-</td>
<td>60</td>
<td>mV</td>
</tr>
<tr>
<td>$I_{OCP}$</td>
<td>Overcurrent protection threshold</td>
<td>$R_L = 0$ $\Omega$</td>
<td>3</td>
<td>-</td>
<td>-</td>
<td>A</td>
</tr>
<tr>
<td>$T_j$</td>
<td>Junction temperature at thermal shutdown</td>
<td>-</td>
<td>-</td>
<td>150</td>
<td>-</td>
<td>°C</td>
</tr>
<tr>
<td>$R_i$</td>
<td>Input resistance</td>
<td>Differential input</td>
<td>54</td>
<td>68</td>
<td>-</td>
<td>k$\Omega$</td>
</tr>
<tr>
<td>$V_{UVP}$</td>
<td>Undervoltage protection threshold</td>
<td>-</td>
<td>-</td>
<td>4.5</td>
<td>-</td>
<td>V</td>
</tr>
<tr>
<td>$R_{dsON}$</td>
<td>Power transistor on resistance</td>
<td>High side</td>
<td>-</td>
<td>0.2</td>
<td>-</td>
<td>$\Omega$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Low side</td>
<td>-</td>
<td>0.2</td>
<td>-</td>
<td>$\Omega$</td>
</tr>
<tr>
<td>$P_o$</td>
<td>Output power</td>
<td>THD = 10%</td>
<td>-</td>
<td>5.0</td>
<td>-</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>THD = 1%</td>
<td>-</td>
<td>4.0</td>
<td>-</td>
<td>W</td>
</tr>
<tr>
<td>$P_o$</td>
<td>Output power</td>
<td>$R_L = 4$ $\Omega$, THD = 10%, $V_{CC} = 6.6$ V</td>
<td>-</td>
<td>5.0</td>
<td>-</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$R_L = 4$ $\Omega$, THD = 1%, $V_{CC} = 6.6$ V</td>
<td>-</td>
<td>4.0</td>
<td>-</td>
<td>W</td>
</tr>
<tr>
<td>$P_D$</td>
<td>Dissipated power</td>
<td>$P_o = 5$ W + 5 W, THD = 10%</td>
<td>-</td>
<td>1.0</td>
<td>-</td>
<td>W</td>
</tr>
<tr>
<td>$\eta$</td>
<td>Efficiency</td>
<td>$P_o = 5$ W + 5 W, $R_L = 8$ $\Omega$, THD = 10%, $V_{CC} = 9$ V</td>
<td>-</td>
<td>90</td>
<td>-</td>
<td>%</td>
</tr>
<tr>
<td>THD</td>
<td>Total harmonic distortion</td>
<td>$P_o = 1$ W</td>
<td>-</td>
<td>0.1</td>
<td>-</td>
<td>%</td>
</tr>
<tr>
<td>$G_V$</td>
<td>Closed loop gain</td>
<td>$GAIN0 = L$, $GAIN1 = L$</td>
<td>18</td>
<td>20</td>
<td>22</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$GAIN0 = L$, $GAIN1 = H$</td>
<td>24</td>
<td>26</td>
<td>28</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$GAIN0 = H$, $GAIN1 = L$</td>
<td>28</td>
<td>30</td>
<td>32</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$GAIN0 = H$, $GAIN1 = H$</td>
<td>30</td>
<td>32</td>
<td>34</td>
<td>dB</td>
</tr>
<tr>
<td>$\Delta G_V$</td>
<td>Gain matching</td>
<td>-</td>
<td>-1</td>
<td>-</td>
<td>1</td>
<td>dB</td>
</tr>
<tr>
<td>CT</td>
<td>Crosstalk</td>
<td>$f = 1$ kHz, $P_o = 1$ W</td>
<td>-</td>
<td>70</td>
<td>-</td>
<td>dB</td>
</tr>
<tr>
<td>eN</td>
<td>Total input noise</td>
<td>A Curve, $G_V = 20$ dB</td>
<td>-</td>
<td>15</td>
<td>-</td>
<td>$\mu$V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$f = 22$ Hz to 22 kHz</td>
<td>-</td>
<td>20</td>
<td>-</td>
<td>$\mu$V</td>
</tr>
</tbody>
</table>
### Table 5. Electrical specifications (continued)

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>SVRR</td>
<td>Supply voltage rejection ratio</td>
<td>$f_r = 100$ Hz, $V_r = 1$ Vpp, $C_{SVR} = 10$ µF</td>
<td>-</td>
<td>50</td>
<td>-</td>
<td>dB</td>
</tr>
<tr>
<td>$T_r$, $T_f$</td>
<td>Rise and fall times</td>
<td>-</td>
<td>40</td>
<td>-</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$f_{SW}$</td>
<td>Switching frequency</td>
<td>Internal oscillator, master mode</td>
<td>290</td>
<td>320</td>
<td>350</td>
<td>kHz</td>
</tr>
<tr>
<td>$f_{SWR}$</td>
<td>Switching frequency range</td>
<td>(1)</td>
<td>250</td>
<td>-</td>
<td>400</td>
<td>kHz</td>
</tr>
<tr>
<td>$V_{inH}$</td>
<td>Digital input high (H)</td>
<td>-</td>
<td>2.3</td>
<td>-</td>
<td>-</td>
<td>V</td>
</tr>
<tr>
<td>$V_{inL}$</td>
<td>Digital input low (L)</td>
<td>-</td>
<td>-</td>
<td>0.8</td>
<td>-</td>
<td>V</td>
</tr>
<tr>
<td>$A_{MUTE}$</td>
<td>Mute attenuation</td>
<td>$V_{MUTE} = \text{low, } V_{STBY} = \text{high}$</td>
<td>-</td>
<td>80</td>
<td>-</td>
<td>dB</td>
</tr>
<tr>
<td>Function mode</td>
<td>Standby, mute and play modes</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$V_{STBY} &lt; 0.5$ V, $V_{MUTE} = X$</td>
<td>Standby</td>
<td>-</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$V_{STBY} &gt; 2.9$ V, $V_{MUTE} &lt; 0.8$ V</td>
<td>Mute</td>
<td>-</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$V_{STBY} &gt; 2.9$ V, $V_{MUTE} &gt; 2.9$ V</td>
<td>Play</td>
<td>-</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1. Refer to Section 5.5: Internal and external clocks on page 27.
4 Characterization curves

The following characterization curves were made using the TDA7491LP demo board. The LC filter for the 4-Ω load uses components of 15 µH and 470 nF and that for the 8-Ω load uses 33 µH and 220 nF.

4.1 With 4-Ω load at \( V_{\text{CC}} = 6.6 \, \text{V} \)

**Figure 3. Output power vs. supply voltage**

<table>
<thead>
<tr>
<th>Test Condition:</th>
</tr>
</thead>
<tbody>
<tr>
<td>( V_{\text{CC}} = 5\text{~}6.6 , \text{V} )</td>
</tr>
<tr>
<td>( R_L = 4 , \text{ohm} )</td>
</tr>
<tr>
<td>( R_{\text{osc}} = 39k , \Omega )</td>
</tr>
<tr>
<td>( C_{\text{osc}} = 100n , \text{F} )</td>
</tr>
<tr>
<td>( f = 1 , \text{kHz} )</td>
</tr>
<tr>
<td>( G_{\text{v}} = 30 , \text{dB} )</td>
</tr>
<tr>
<td>( T_{\text{amb}} = 25^\circ \text{C} )</td>
</tr>
</tbody>
</table>

**Specification Limit:**

Typical:

\( V_s = 6.6 \, \text{V}, \, R_l = 4 \, \text{ohm} \)

\( P_o = 5W \, @ \text{THD} = 10\% \)

\( P_o = 3.7W \, @ \text{THD} = 1\% \)

**Figure 4. THD vs. output power (1 kHz)**

<table>
<thead>
<tr>
<th>Test Condition:</th>
</tr>
</thead>
<tbody>
<tr>
<td>( V_{\text{CC}} = 6.6 , \text{V} )</td>
</tr>
<tr>
<td>( R_L = 4 , \text{ohm} )</td>
</tr>
<tr>
<td>( R_{\text{osc}} = 39k , \Omega )</td>
</tr>
<tr>
<td>( C_{\text{osc}} = 100n , \text{F} )</td>
</tr>
<tr>
<td>( f = 1 , \text{kHz} )</td>
</tr>
<tr>
<td>( G_{\text{v}} = 30 , \text{dB} )</td>
</tr>
<tr>
<td>( T_{\text{amb}} = 25^\circ \text{C} )</td>
</tr>
</tbody>
</table>

**Specification Limit:**

Typical:

\( P_o = 5W \, @ \text{THD} = 10\% \)
Figure 5. THD vs. output power (100 Hz)

Test Condition:
Vcc = 6.6V,
RL = 4 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 100Hz,
Gv = 30dB,
Tamb = 25°C

Specification Limit:
Typical: Po = 5W @ THD = 10%

Figure 6. THD vs. frequency

Test Condition:
Vcc = 6.6V,
RL = 4 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 1kHz,
Gv = 30dB,
Po = 1W,
Tamb = 25°C

Specification Limit:
Typical: THD < 0.5%
Figure 7. Frequency response

**Test Condition:**
- $V_{cc} = 6.6V$,
- $RL = 4$ ohm,
- $R_{osc} = 39k \Omega$, $C_{osc} = 100nF$,
- $f = 1kHz$,
- $G_{v} = 30dB$,
- $P_{o} = 1W$,
- $T_{amb} = 25^\circ C$,
- $C_{in} = 1uF$

**Specification Limit:**
- Max: $\pm 3dB$
- @20Hz to 20kHz

![Amplitude (dB) vs. Frequency (Hz)]

Figure 8. Crosstalk vs. frequency

**Test Condition:**
- $V_{cc} = 6.6V$,
- $RL = 4$ ohm,
- $R_{osc} = 39k \Omega$, $C_{osc} = 100nF$,
- $f = 1kHz$,
- $G_{v} = 30dB$,
- $P_{o} = 1W$,
- $T_{amb} = 25^\circ C$,

**Specification Limit:**
- Typical: $>30dB$ (@ $f = 1kHz$)

![Crosstalk (dB) vs. Frequency (Hz)]
Figure 9. FFT (0 dB)

Test Condition:
Vcc = 6.6V,
RL = 4 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 1kHz,
Gv = 30dB,
P0 = 1W
Tamb = 25°C

Specification Limit:
Typical: >60dB
for the harmonic frequency

Figure 10. FFT (-60 dB)

Test Condition:
Vcc = 6.6V,
RL = 4 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 1kHz,
Gv = 30dB,
P0 = -60dB (@ 1W = 0dB)
Tamb = 25°C

Specification Limit:
Typical: >90dB
for the harmonic frequency
Figure 11. Power supply rejection ratio vs. frequency

Test Condition:
- Vcc = 6.6V,
- RL = 4 ohm,
- Rosc = 39kΩ, Cosp = 100nF,
- Vin = 0,
- Gv = 30dB,
- Tamb = 25°C
- Vr = 500mVrms
- Fr = 100Hz

Figure 12. Power dissipation and efficiency vs. output power

Test Condition:
- Vcc = 6.6V,
- RL = 4 ohm,
- Rosc = 39kΩ, Cosp = 100nF,
- Gv = 30dB,
- Tamb = 25°C
Figure 13. Attenuation vs. voltage on pin MUTE

Test Condition:
Vcc = 6.6V,
RL = 4 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 1kHz,
0dB@f = 1kHz, Po = 1w,
Gv = 30dB,
Tamb = 25°C

Figure 14. Current consumption vs. voltage on pin STBY

Test Condition:
Vcc = 6.6V,
RL = 4 ohm,
Rosc = 39kΩ, Cosc = 100nF,
Vin = 0,
Gv = 30dB,
Tamb = 25°C
Figure 15. Attenuation vs. voltage on pin STBY

Test Condition:
- \( V_{cc} = 6.6V \),
- \( RL = 4 \) ohm,
- \( R_{osc} = 39k\Omega \), \( C_{osc} = 100nF \),
- \( f = 1kHz \),
- \( 0dB@f=1kHz, P_o=1w, G_v = 30dB, \)
- \( T_{amb} = 25°C \)
4.2 With 8-Ω load at $V_{CC} = 9\,\text{V}$

**Figure 16. Output power vs. supply voltage**

![Output power vs. supply voltage graph]

**Test Condition:**
- $V_{CC} = 5$ to $9\,\text{V}$,
- $R_L = 8\,\text{ohm}$,
- $R_{osc} = 39\,\text{kΩ}$, $C_{osc} = 100\,\text{nF}$,
- $f = 1\,\text{kHz}$,
- $G_v = 30\,\text{dB}$,
- $T_{amb} = 25\,^\circ\text{C}$

**Specification Limit:**
- Typical:
  - $V_s = 9\,\text{V}$,
  - $R_L = 8\,\text{ohm}$,
  - $P_o = 5\,\text{W} @ THD = 10\%$,
  - $P_o = 4\,\text{W} @ THD = 1\%$

**Figure 17. THD vs. output power (1 kHz)**

![THD vs. output power graph]

**Test Condition:**
- $V_{CC} = 9\,\text{V}$,
- $R_L = 8\,\text{ohm}$,
- $R_{osc} = 39\,\text{kΩ}$, $C_{osc} = 100\,\text{nF}$,
- $f = 1\,\text{kHz}$,
- $G_v = 30\,\text{dB}$,
- $T_{amb} = 25\,^\circ\text{C}$

**Specification Limit:**
- Typical:
  - $P_o = 5\,\text{W} @ THD = 10\%$
Figure 18. THD vs. output power (100 Hz)

Test Condition:
- Vcc = 9V
- RL = 8 ohm
- Rosc = 39kΩ, Cosc = 100nF
- f = 100Hz
- Gv = 30dB
- Tamb = 25°C

Specification Limit:
- Typical: Po = 5W @ THD = 10%

Figure 19. THD vs. frequency

Test Condition:
- Vcc = 9V
- RL = 8 ohm
- Rosc = 39kΩ, Cosc = 100nF
- f = 1kHz
- Gv = 30dB
- Po = 1W
- Tamb = 25°C

Specification Limit:
- Typical: THD < 0.5%
Figure 20. Frequency response

Test Condition:
Vcc = 9V,
RL = 8 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 1kHz,
Gv = 30dB,
Po = 1W
Tamb = 25°C

Specification Limit:
Max: +/-3dB
@20Hz to 20kHz

Figure 21. Crosstalk vs. frequency

Test Condition:
Vcc = 9V,
RL = 8 ohm,
Rosc = 39kΩ, Cosc = 100nF,
f = 1kHz,
Gv = 30dB,
Po = 1W
Tamb = 25°C

Specification Limit:
Typical: >50dB (@ f = 1kHz)
**Figure 22. FFT (0 dB)**

Test Condition:
- $V_{cc} = 9V$
- $RL = 8\ \text{ohm}$
- $R_{osc} = 39k\ \Omega$, $C_{osc} = 100nF$
- $f = 1kHz$
- $G_{v} = 30dB$
- $P_{o} = 1W$
- $T_{amb} = 25^\circ C$

Specification Limit:
- Typical: $>60dB$
- for the harmonic frequency

**Figure 23. FFT (-60 dB)**

Test Condition:
- $V_{cc} = 9V$
- $RL = 8\ \text{ohm}$
- $R_{osc} = 39k\ \Omega$, $C_{osc} = 100nF$
- $f = 1kHz$
- $G_{v} = 30dB$
- $P_{o} = -60dB$ (@ 1W = 0dB)
- $T_{amb} = 25^\circ C$

Specification Limit:
- Typical: $>90dB$
- for the harmonic frequency
Figure 24. Power supply rejection ratio vs. frequency

Test Condition:
Vcc = 9V,
RL = 8 ohm,
Rosc = 39kΩ, Cosc = 100nF,
Vin = 0,
Gv = 30dB,
Tamb = 25°C

Figure 25. Power dissipation and efficiency vs. output power

Test Condition:
Vcc = 9V,
RL = 8 ohm,
Rosc = 39kΩ, Cosc = 100nF,
Vin = 0,
Gv = 30dB,
Tamb = 25°C
5 Applications information

5.1 Applications circuit

Figure 26. Applications circuit for class-D amplifier

<table>
<thead>
<tr>
<th>LC FILTER COMPONENT</th>
<th>4 ohms</th>
<th>8 ohms</th>
<th>16 ohms</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 µH</td>
<td>22 µH</td>
<td>22 µH</td>
<td>22 µH</td>
</tr>
<tr>
<td>5.6 µH</td>
<td>220 nF</td>
<td>220 nF</td>
<td>220 nF</td>
</tr>
</tbody>
</table>
5.2 Mode selection

The three operating modes, defined below, of the TDA7491LP are set by the two inputs STBY (pin 20) and MUTE (pin 21) as shown in Table 6.

- Standby mode: all circuits are turned off, very low current consumption.
- Mute mode: inputs are connected to ground and the positive and negative PWM outputs are at 50% duty cycle.
- Play mode: the amplifiers are active.

The protection functions of the TDA7491LP are implemented by pulling down the voltages of the STBY and MUTE inputs shown in Figure 27. The input current of the corresponding pins must be limited to 200 µA.

Table 6. Mode settings

<table>
<thead>
<tr>
<th>Mode</th>
<th>Voltage level on pin STBY</th>
<th>Voltage level on pin MUTE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standby</td>
<td>L (1)</td>
<td>X (don’t care)</td>
</tr>
<tr>
<td>Mute</td>
<td>H (1)</td>
<td>L</td>
</tr>
<tr>
<td>Play</td>
<td>H</td>
<td>H</td>
</tr>
</tbody>
</table>

1. Refer to $V_{STBY}$ and $V_{MUTE}$ in Table 5: Electrical specifications on page 10 for the drive levels for L and H.

Figure 27. Standby and mute circuits

Figure 28. Turn-on/off sequence for minimizing speaker “pop”
5.3 Gain setting

The gain of the TDA7491LP is set by the two inputs, GAIN0 (pin 30) and GAIN1 (pin 31). Internally, the gain is set by changing the feedback resistors of the amplifier.

<table>
<thead>
<tr>
<th>Voltage level on pin GAIN0</th>
<th>Voltage level on pin GAIN1</th>
<th>Nominal gain, $G_v$ (dB)</th>
</tr>
</thead>
<tbody>
<tr>
<td>L(1)</td>
<td>H(1)</td>
<td>20</td>
</tr>
<tr>
<td>L</td>
<td>H</td>
<td>26</td>
</tr>
<tr>
<td>H</td>
<td>L</td>
<td>30</td>
</tr>
<tr>
<td>H</td>
<td>H</td>
<td>32</td>
</tr>
</tbody>
</table>

1. Refer to $V_{\text{inL}}$ and $V_{\text{inH}}$ in Table 5: Electrical specifications on page 10 for the drive levels for L and H

5.4 Input resistance and capacitance

The input impedance is set by an internal resistor $R_i = 68 \, \text{k}\Omega$ (typical). An input capacitor ($C_i$) is required to couple the AC input signal.

The equivalent circuit and frequency response of the input components are shown in Figure 29. For $C_i = 220 \, \text{nF}$ the high-pass filter cut-off frequency is below 20 Hz:

$$f_c = \frac{1}{2 \pi R_i C_i}$$

Figure 29. Device input circuit and frequency response
5.5 Internal and external clocks

The clock of the class-D amplifier can be generated internally or can be driven by an external source.

If two or more class-D amplifiers are used in the same system, it is recommended that all devices operate at the same clock frequency. This can be implemented by using one TDA7491LP as master clock, while the other devices are in slave mode, that is, externally clocked. The clock interconnect is via pin SYNCLK of each device. As explained below, SYNCLK is an output in master mode and an input in slave mode.

5.5.1 Master mode (internal clock)

Using the internal oscillator, the output switching frequency, $f_{SW}$, is controlled by the resistor, $R_{OSC}$, connected to pin ROSC:

$$f_{SW} = \frac{10^6}{(16 \cdot R_{OSC} + 182) \cdot 4} \text{kHz}$$

where $R_{OSC}$ is in kΩ.

In master mode, pin SYNCLK is used as a clock output pin, whose frequency is:

$$f_{SYNCLK} = 2 \cdot f_{SW}$$

For master mode to operate correctly then resistor $R_{OSC}$ must be less than 60 kΩ as given below in Table 8.

5.5.2 Slave mode (external clock)

In order to accept an external clock input, pin ROSC must be left open, that is, floating. This forces pin SYNCLK to be internally configured as an input as given in Table 8.

The output switching frequency of the slave devices is:

$$f_{SW} = \frac{f_{SYNCLK}}{2}$$

<table>
<thead>
<tr>
<th>Mode</th>
<th>ROSC</th>
<th>SYNCLK</th>
</tr>
</thead>
<tbody>
<tr>
<td>Master</td>
<td>$R_{OSC} &lt; 60$ kΩ</td>
<td>Output</td>
</tr>
<tr>
<td>Slave</td>
<td>Floating (not connected)</td>
<td>Input</td>
</tr>
</tbody>
</table>

Figure 30. Master and slave connection

![Diagram showing master and slave connection]
5.6 Modulation

The output modulation scheme of the BTL is called unipolar pulse width modulation (PWM). The differential output voltages change between 0 V and \( +V_{\text{CC}} \) and between 0 V and \( -V_{\text{CC}} \). This is in contrast to the traditional bipolar PWM outputs which change between \( +V_{\text{CC}} \) and \( -V_{\text{CC}} \).

An advantage of this scheme is that it effectively doubles the switching frequency of the differential output waveform on the load then reducing the current ripple accordingly. The OUTP and OUTN are in the same phase almost overlapped when the input is zero under this condition, then the switching current is low and the related losses in the load are low. In practice, a short delay is introduced between these two outputs in order to avoid the BTL outputs switching simultaneously when the input is zero.

*Figure 31* shows the resulting differential output voltage and current when a positive, zero and negative input signal is applied. The resulting differential voltage on the load has a double frequency with respect to outputs OUTP and OUTN then resulting in reduced current ripple.

*Figure 31. Unipolar PWM output*
5.6.1 Reconstruction low-pass filter

Standard applications use a low-pass filter before the speaker. The cut-off frequency should be higher than 22 kHz and much lower than the output switching frequency. It is necessary to choose the L-C component values depending on the loudspeaker impedance. Some typical values, which give a cut-off frequency of 27 kHz, are shown in Figure 32 and Figure 33 below.

Figure 32. Typical LC filter for an 8-Ω speaker

![Typical LC filter for an 8-Ω speaker](image1)

Figure 33. Typical LC filter for a 4-Ω speaker

![Typical LC filter for a 4-Ω speaker](image2)

5.6.2 Filterless modulation

TDA7491LP can be used without a filter at the IC outputs, because the frequency of the TDA7491LP output is beyond the audio frequency, the audio signal can be recovered by the inherent inductance of the speaker and natural filter of the human ear.

The reconstruction of the audio signal on the load is usually achieved using a complete LC filter (such as a Butterworth) solution that guarantees good audio performance, high efficiency and EMI suppression. The LC component values should be computed by considering the target audio band and the PWM switching frequency. The cut-off frequency must lie well below the switching frequency and above the upper audio frequency. In particular, the following schematic gives a guideline for a cut-off frequency of about 30 kHz for both 6- and 8-Ω speakers.

Thanks to its advanced modulation approach, aimed to improve both driving efficiency and radiating emissions, the device is even able to drive a load with a very low component count. With this cost-saving filtering scheme the TDA7491LP complies with the EMI specifications FCC class B. Figure 34 on page 30 shows the simplified schematic adopted for the test and the relevant emission curve at full output power.
Emission tests have been performed with a 1-m length of twisted speaker wire with ferrite beads. Changing the type of the ferrite bead requires care due to factors such as its effectiveness in the EMC frequency range and impedance stability over the rated current range. An output snubber network further improves the emissions and this should be tuned according to the actual PCB, layout and component characteristics.

Figure 34. Filterless application schematic
5.7 Protection functions

The TDA7491LP is fully protected against undervoltages, overcurrents and thermal overloads as explained here.

Undervoltage protection (UVP)

If the supply voltage drops below the value of \( V_{UVP} \) given in Table 5: Electrical specifications on page 10 the undervoltage protection is activated which forces the outputs to the high-impedance state. When the supply voltage recovers the device restarts.

Overcurrent protection (OCP)

If the output current exceeds the value of \( I_{OCP} \) given in Table 5: Electrical specifications on page 10 the overcurrent protection is activated which forces the outputs to the high-impedance state. Periodically, the device attempts to restart. If the overcurrent condition is still present then the OCP remains active. The restart time, \( T_{OC} \), is determined by the R-C components connected to pin STBY.

Thermal protection (OTP)

If the junction temperature, \( T_j \), reaches 145 °C (nominal), the device goes to mute mode and the positive and negative PWM outputs are forced to 50% duty cycle. If the junction temperature reaches the value for \( T_j \) given in Table 5: Electrical specifications on page 10 the device shuts down and the output is forced to the high impedance state. When the device cools sufficiently the device restarts.

5.8 Diagnostic output

The output pin DIAG is an open drain transistor. When the protection is activated it is in the high-impedance state. The pin can be connected to a power supply (<18 V) by a pull-up resistor whose value is limited by the maximum sinking current (200 \( \mu \)A) of the pin.

Figure 35. Behavior of pin DIAG for various protection conditions
5.9 Heatsink requirements

Due to the high efficiency of the class-D amplifier a 2-layer PCB can easily provide the heatsinking capability for low to medium power outputs.

Using such a PCB with a copper ground layer of 3 x 3 cm² and 16 vias connecting it to the contact area for the exposed pad, a thermal resistance, junction to ambient (in natural air convection), of 24 °C/W can be achieved.

The dissipated power within the device depends primarily on the supply voltage, load impedance and output modulation level. With the TDA7491LP driving 2 x 8 Ω with a supply of 9 V then the maximum device dissipation is approximately 1 W.

When this power is dissipated at the maximum ambient temperature of 85 °C and the device is mounted on the above PCB then the junction temperature could reach:

$$T_j = T_{amb} + P_d \times R_{j-amb} = 85 + 1 \times 24 = 109 \degree C$$

However, this temperature is sufficiently low to avoid triggering thermal warning.

With a musical program the dissipated power is about 40% less than the above maximum value. This leads to a junction temperature of around only 99 °C with the 9 cm² copper ground. A commensurately smaller heatsink can thus be used.

*Figure 36* shows the power derating curve for the PowerSSO-36 package on PCBs with copper areas of 2 x 2 cm² and 3 x 3 cm².

*Figure 36. Power derating curves for PCB used as heatsink*
5.10 Test board

Figure 37. Test board (TDA7491LP) layout
6 Package mechanical data

The TDA7491LP comes in a 36-pin PowerSSO package with exposed pad down (EPD).

Figure 38 below shows the package outline and Table 9 gives the dimensions.

Table 9. PowerSSO-36 EPD dimensions

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Dimensions in mm</th>
<th>Dimensions in inches</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Min</td>
<td>Typ</td>
</tr>
<tr>
<td>A</td>
<td>2.15</td>
<td>-</td>
</tr>
<tr>
<td>A2</td>
<td>2.15</td>
<td>-</td>
</tr>
<tr>
<td>a1</td>
<td>0.00</td>
<td>-</td>
</tr>
<tr>
<td>b</td>
<td>0.18</td>
<td>-</td>
</tr>
<tr>
<td>c</td>
<td>0.23</td>
<td>-</td>
</tr>
<tr>
<td>D</td>
<td>10.10</td>
<td>-</td>
</tr>
<tr>
<td>E</td>
<td>7.40</td>
<td>-</td>
</tr>
<tr>
<td>e</td>
<td>-</td>
<td>0.5</td>
</tr>
<tr>
<td>e3</td>
<td>-</td>
<td>8.5</td>
</tr>
<tr>
<td>F</td>
<td>-</td>
<td>2.3</td>
</tr>
<tr>
<td>G</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>H</td>
<td>10.10</td>
<td>-</td>
</tr>
<tr>
<td>h</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>k</td>
<td>0</td>
<td>-</td>
</tr>
<tr>
<td>L</td>
<td>0.60</td>
<td>-</td>
</tr>
<tr>
<td>M</td>
<td>-</td>
<td>4.30</td>
</tr>
<tr>
<td>N</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>O</td>
<td>-</td>
<td>1.20</td>
</tr>
<tr>
<td>Q</td>
<td>-</td>
<td>0.80</td>
</tr>
<tr>
<td>S</td>
<td>-</td>
<td>2.90</td>
</tr>
<tr>
<td>T</td>
<td>-</td>
<td>3.65</td>
</tr>
<tr>
<td>U</td>
<td>-</td>
<td>1.00</td>
</tr>
<tr>
<td>X</td>
<td>4.10</td>
<td>-</td>
</tr>
<tr>
<td>Y</td>
<td>6.50</td>
<td>-</td>
</tr>
</tbody>
</table>

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com. ECOPACK® is an ST trademark.
Figure 38. PowerSSO-36 EPD outline drawing
7 Revision history

Table 10. Document revision history

<table>
<thead>
<tr>
<th>Date</th>
<th>Revision</th>
<th>Changes</th>
</tr>
</thead>
<tbody>
<tr>
<td>02-Jul-2007</td>
<td>1</td>
<td>Initial release.</td>
</tr>
<tr>
<td>15-Oct-2008</td>
<td>2</td>
<td>Updated characterization curves.</td>
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</tbody>
</table>
| 23-Jun-2009| 3        | Updated text concerning oscillator R and C in Section 3.3: Electrical specifications on page 10  
Updated condition for Iq test, added V_{UVP} maximum value, updated THD maximum value, updated STBY and MUTE voltages in Table 5: Electrical specifications on page 10  
Updated equation for f_{SW} on page 11 and on page 27  
Updated Figure 26: Applications circuit for class-D amplifier on page 24  
Updated Section 5.7: Protection functions on page 31. |
| 04-Sep-2009| 4        | Added text for exposed pad in Figure 2 on page 7  
Added text for exposed pad in Table 2 on page 8  
Updated exposed pad Y (Min) dimension in Table 9 on page 34  
Updated supply voltage for pin DIAG pull-up resistor in Section 5.8 on page 31. |
| 23-Mar-2011| 5        | Updated operating temperature range in Table 1 on page 1  
Modified description of pins 10, 11 in Table 2 on page 8  
Added V_{I} and updated operating temperature range in Table 3: Absolute maximum ratings on page 9  
Updated Table 4: Thermal data on page 9  
Updated Table 5: Electrical specifications on page 10  
Updated introduction and characterization curves in Section 4 on page 12  
Moved test board layout to Section 5.10 on page 33  
Moved package mechanical data to Section 6 on page 34  
Updated applications circuit in Figure 26 on page 24  
Updated Table 7: Gain settings on page 26  
Updated Section 5.6: Modulation on page 28  
Added Figure 34: Filterless application schematic on page 30  
Removed overvoltage protection from Section 5.7: Protection functions on page 31  
Updated Section 5.9: Heatsink requirements on page 32  
Updated exposed pad dimension Y in Table 9 on page 34. |
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Doc ID 13541 Rev 5