



STM32WBA6xxx device errata

Applicability

This document applies to the part numbers of STM32WBA6xxx devices and the device variants as stated in this page. It gives a summary and a description of the device errata, with respect to the device datasheet and reference manual RM0515. Deviation of the real device behavior from the intended device behavior is considered to be a device limitation. Deviation of the description in the reference manual or the datasheet from the intended device behavior is considered to be a documentation erratum. The term “errata” applies both to limitations and documentation errata.

Table 1. Device summary

Reference	Part numbers
STM32WBA6xxx	STM32WBA62PG, STM32WBA62CG, STM32WBA62MG, STM32WBA62PI, STM32WBA62CI, STM32WBA62MI, STM32WBA63CG, STM32WBA63CI, STM32WBA64CG, STM32WBA64CI, STM32WBA65CG, STM32WBA65PG, STM32WBA65RI, STM32WBA65MI, STM32WBA65CI, STM32WBA65PI, STM32WBA65RG, STM32WBA65MG

Table 2. Device variants

Reference	Silicon revision codes	
	Device marking ⁽²⁾	DIE_ID ⁽¹⁾
STM32WBA6xxx	Z	0x1001

1. REV_ID[15:0] bitfield of BGMCU_IDCODE register.
2. Refer to the device datasheet for how to identify this code on different types of package.

1 Summary of device errata

The following table gives a quick reference to the STM32WBA6xxx device limitations and their status:

A	Limitation applicable. Workaround available
N	Limitation applicable. No workaround available
P	Limitation applicable. Partial workaround available
-	Limitation not applicable.

Applicability of a workaround may depend on specific conditions of target application. Adoption of a workaround may cause restrictions to target application. Workaround for a limitation is deemed partial if it only reduces the rate of occurrence and/or consequences of the limitation, or if it is fully effective for only a subset of instances on the device or in only a subset of operating modes, of the function concerned.

Table 3. Summary of device limitations

Function	Section	Limitation	Status
			Rev. Z
Core	2.1.1	Access permission faults are prioritized over unaligned device memory faults	N
	2.2.1	LSE crystal oscillator may be disturbed by transitions on PC13	N
System	2.2.2	Device-specific authentication ID is not accessible in RDP Level 0	A
	2.2.3	HSEPRE cannot be changed while HSE is set as system clock or PLL source	A
	2.2.4	RCC audio synchronization registers cannot be updated while the counter is enabled	A
	2.2.5	Bit LPWRRSTF of RCC_CSR can always be read	N
	2.2.6	Incorrect read of audio synchronization registers RCC_ASCNTR and RCC_ASCAR	A
	2.2.7	Glitches on PA2 and PA7 in retention Standby mode	A
	2.2.8	ICACHE clock requires register RCC_AHB1ENR to have a non-zero value	A
	2.2.9	RTC clocked by LSI stops working when a reset is triggered from the NRST pad	A
	2.2.10	Fast-mode Plus cannot be activated using SYSCFG_CFGR1 register	N
	2.2.11	Longer HSE32 stabilization time when the clock is stopped for a time between 2 and 5 ms	A
	2.2.12	No security gating is applied to MCO on PA8 when AF0 is selected	N
	2.2.13	Reset can cause the system to get stuck in Standby mode or STOP 2 LPMODE	N
	2.2.14	RCC_BDCR1 register reset behavior not correctly implemented	N
	2.2.15	Privilege and secure access to RCC_CCIPR2 register ASSEL and OTGHSSEL bits not correctly implemented	N
	2.2.16	VREFBUF control by VRS[2:0] not operational	A
	2.2.17	PD9 leakage issue in USB mode	N
	2.2.18	System cannot enter LPMODE if RCC CFGR2.HPRE is not equal to 0	A
	2.2.19	LSE in bypass mode may not be functional	N
Radio system	2.3.1	Bluetooth® LE frequency deviation	P
	2.3.2	Nonlinear behavior of Bluetooth® LE RSSI reporting	N
TIM	2.4.1	Unexpected PWM output when using ocref_clr	N
LPTIM	2.5.1	Device may remain stuck in LPTIM interrupt when entering Stop mode	A

Function	Section	Limitation	Status
			Rev. Z
LPTIM	2.5.2	ARRM and CMPM flags are not set when APB clock is slower than kernel clock	A
	2.5.3	Interrupt status flag is cleared by hardware upon writing its corresponding bit in LPTIM_DIER register	N
RTC	2.6.1	Alarm flag may be repeatedly set when the core is stopped in debug	N
	2.6.2	RTC calendar read may return transient incorrect value when BYPSHAD = 0	A
I2C	2.7.1	Wrong data sampling when data setup time ($t_{SU,DAT}$) is shorter than one I2C kernel clock period	P
	2.7.2	Spurious bus error detection in controller mode	A
USART	2.8.1	Wrong data received by SPI slave receiver in autonomous mode with CPOL = 1	A
	2.8.2	Received data may be corrupted upon clearing the ABREN bit	A
	2.8.3	Noise error flag set while ONEBIT is set	N
LPUART	2.9.1	Possible LPUART transmitter issue when using low BRR[15:0] value	P
SPI	2.10.1	RDY output failure at high serial clock frequency	N
OTG_HS	2.11.1	Potential unexpected transfer on the USB bus instead of a zero-length packet	A
	2.11.2	False detection of chirp-K when an FS device is connected	A

2 Description of device errata

The following sections describe the errata of the applicable devices and provide a workaround where available. They are grouped by device functions.

The applicable devices are based on Arm® Cortex® core.

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2.1 Core

Reference manual and errata notice for the Arm® Cortex®-M33 core revision r0p is available from <http://infocenter.arm.com>.

2.1.1 Access permission faults are prioritized over unaligned device memory faults

Description

A load or store which causes an unaligned access to device memory results in an UNALIGNED UsageFault exception. However, if the region is not accessible because of the MPU access permissions (as specified in MPU_RBAR.AP), then the resulting MemManage fault is prioritized over the UsageFault.

The failure occurs when the MPU is enabled and:

- A load/store access occurs to an address which is not aligned to the data type specified in the instruction.
- The memory access hits one region only.
- The region attributes (specified in the MAIR register) mark the location as device memory.
- The region access permissions prevent the access (that is, unprivileged or write not allowed).

The MemManage fault caused by the access permission violation is prioritized over the UNALIGNED UsageFault exception because of the memory attributes.

Workaround

None. However, it is expected that no existing software is relying on this behavior since it was permitted in Armv7-M.

2.2 System

2.2.1 LSE crystal oscillator may be disturbed by transitions on PC13

Description

On UFQFPN packages, the LSE crystal oscillator clock frequency can be incorrect when PC13 is toggling in input or output (for example when used for RTC_OUT1).

The external clock input (LSE bypass) is not impacted by this limitation.

The WLCSP and UFBGA packages are not impacted by this limitation.

Workaround

None.

Avoid toggling PC13 when LSE is used on UFQFPN packages.

2.2.2 Device-specific authentication ID is not accessible in RDP Level 0

Description

The AUTH_ID bitfield of the DBGMCU_DBG_AUTH_DEVICE register is not accessible in RDP Level 0. The read value is always 0. Therefore, this bitfield cannot be used to discriminate between different devices.

Workaround

Increase the RDP to Level 1 before reading the device-specific authentication ID. Then, decrease the RDP back to Level 0.

2.2.3 HSEPRE cannot be changed while HSE is set as system clock or PLL source

Description

The clock divider may produce glitches if changed while HSE is running.

Workaround

Set the system clock temporarily to HSI, then change the HSEPRE setting of the divider.

2.2.4 RCC audio synchronization registers cannot be updated while the counter is enabled

Description

The compare register ASCOR cannot be used when the synchronization has started.

Workaround

For writing, CEN should be set to zero leading to a reset of registers, including the free running counter.

2.2.5 Bit LPWRRSTF of RCC_CSR can always be read

Description

Bit LPWRRSTF of RCC_CSR can be always read regardless of the privilege level set in the RCC_PRIVCFGR register.

Workaround

None

2.2.6 Incorrect read of audio synchronization registers RCC_ASCNTR and RCC_ASCAR

Description

When the system frequency is lower than the audio synchronization frequency, reading the RCC_ASCAR and RCC_ASCNTR registers possibly gives out-of-date values.

Workaround

Repeat the read operation to get the current value.

2.2.7 Glitches on PA2 and PA7 in retention Standby mode

Description

When coming into or coming out of Standby mode with retention, PA2 and PA7 may show signal glitches. These glitches affect all the alternate functions available on PA2 and PA7 like ADC, USART, I2C, GPIO, TAMP, etc.

Workaround

Discard the IO retention feature, and force the pull-down on these two signals.

2.2.8 ICACHE clock requires register RCC_AHB1ENR to have a non-zero value

Description

ICACHE can be configured to perform an address remap to SRAM.

The ICACHE clock is disabled when all the bits of the RCC_AHB1ENR register are at zero.

A deadlock can occur when:

- code and data are stored in SRAM2,
- ICACHE is configured to remap the addresses 0x0A00/0x0E00 to 0x2000/0x3000,
- all the register RCC_AHB1ENR bits are at zero, and
- the CPU attempts to reboot from 0x0A00/0x0E00.

The device does not boot.

Workaround

Ensure that at least one bit of the RCC_AHB1ENR register is set.

2.2.9 RTC clocked by LSI stops working when a reset is triggered from the NRST pad

Description

An external trigger from the NRST pad resets the LSI1ON, LSI1PREDIV, and RADIOSTSEL bits of the RCC_BDCR1 register, causing RTC and TAMP to stop functioning.

Workaround

Use as the clock for RTC.

2.2.10 Fast-mode Plus cannot be activated using SYSCFG_CFGR1 register

Description

The activation of the Fast-mode Plus mode on GPIO PB3, PA15, PA7, or PA6 by setting the corresponding bit in the SYSCFG_CFGR1 register is ineffective.

Workaround

None.

2.2.11 Longer HSE32 stabilization time when the clock is stopped for a time between 2 and 5 ms

Description

When the HSE32 is restarted after having been off within a window of time between 2 and 5 ms, it may be not ready even if the HSERDY bit is set in the RCC_CR register. This may result in a CPU hard fault, wrong timer counting, or an incorrect behavior of the other peripherals that use the HSE32 clock.

In this case, the HSE32 oscillator stabilization time t_{STAB} may be increased by 1 ms (360 μ s typical).

Workaround

Apply the following measure in applications where the HSE32 clock is stopped for more than 2 ms and less than 5 ms:

1. Before stopping the HSE32 clock, deselect HSE32 for all the peripherals that use this clock as kernel clock:
 - SYSCLK via the SW[1:0] bitfield of the RCC_CFGR1 register
 - PLL1 via the PLL1SRC[1:0] bitfield of the RCC_PLL1CFGR register
 - RTC and TAMP via the RTCSEL[1:0] bitfield in the RCC_BDCR1 register
 - ADC4 via the ADCSEL[2:0] bitfield of the RCC_CCIPR3 register
 - 2.4 GHz RADIO sleep clock via the RADIOSTSEL[1:0] bitfield of the RCC_BDCR1 register.
 - 2.4 GHz RADIO baseband kernel clock shall be disabled via the BBCLKEN bitfield of the RCC_RADIOENR register.
2. Wait until HSERDY is set, then wait for an additional time of 200 μ s before using HSE32 again for the SYSCLK, PLL1, RTC, TAMP, ADC4, 2.4 GHz RADIO sleep clock, or 2.4 GHz RADIO baseband clock.
3. Keep the HSE clock security disabled, by clearing the HSECSSON bit in the RCC_CR register.

The above measure does not prevent the 2.4 GHz RADIO to occasionally miss some packets when t_{STAB} is higher than 360 μ s and smaller than 1 ms). To prevent this issue for occurring, the 2.4 GHz RADIO wake-up can be anticipated by 600 μ s.

2.2.12 No security gating is applied to MCO on PA8 when AF0 is selected

Description

When GPIO alternate function 0 is selected (AF0), the MCO is output on PA8. Setting the SYSCLKSEC bit of the RCC_SECCFGR register should make this output secure. Instead, the MCO is still output on PA8.

Workaround

None.

2.2.13 Reset can cause the system to get stuck in Standby mode or STOP 2 LPMODE

Description

If NRESET is activated after a few nanoseconds of an internal standby or stop 2 request, the system may be unable to exit Standby or Stop 2 mode, in which case a POR is necessary.

Workaround

None.

2.2.14 RCC_BDCR1 register reset behavior not correctly implemented

Description

The RCC_BDCR1 register resets with Backup domain power-on reset except for the BDRST bit, which resets on POR (power-on reset).

In the current implementation, some bits of the RCC_DBCR1 register are reset with padreset or poreset.

Workaround

None.

2.2.15 Privilege and secure access to RCC_CCIPR2 register ASSEL and OTGHSSEL bits not correctly implemented

Description

The configuration bits of the clock of one IPx can be accessed if the access is performed with the same or higher security of the IPx. The access can be secured by GTZC_TZSC registers IPxSEC bits. When in securemode, a nonsecure read/write access is RAZ/WI (Read As Zero/Write Ignored). This bit can be protected against unprivileged access when in secure mode using the RCC_SPRIV register, or when in nonsecure mode using the RCC_NSPRIV register.

However, the secure/privilege information for the SAI and OTGHS has not been correctly connected in the ASSEL and OTGHSSEL bitfields of the RCC_CCIPR2 register:

- ASSEL access depends on the OTGHS security/privilege attribute.
- OTGHSSEL[1] access depends on the SAI security/privilege attribute.
- OTGHSSEL[0] does not depend on any security/privilege attribute.

Workaround

None.

2.2.16 VREFBUF control by VRS[2:0] not operational

Description

Upon reset and upon writing the VRS[2:0] bitfield of the VREFBUF_CSR register, the TRIM[5:0] bitfield of the VREFBUF_CCR register is expected to automatically be filled with the corresponding factory VREFBUF calibration value. However, the TRIM[5:0] takes the value 0x3F upon reset and writing the VRS[2:0] bitfield has no effect on it.

Workaround

Upon reset and upon changing the VRS[2:0] value, copy (by software) the appropriate VREFBUFx_TRIM[5:0] calibration into the bitfield TRIM[5:0] of the VREFBUF_CCR register.

2.2.17 PD9 leakage issue in USB mode

Description

When the USB internal switches are activated, PD9 becomes a dedicated pad for USB (VBUS pad). In this USB scenario, a leakage current consumption of approximately 35 μ A occurs if an external pull-up or voltage (equal to V_{DDUSB}) is applied to PD9.

VBUS is used in device mode, not in host mode. This unexpected extraconsumption is not an issue for external devices. PD9 functions correctly in GPIO mode.

Workaround

None.

2.2.18 System cannot enter LPMODE if RCC_CFGR2.HPRE is not equal to 0

Description

The AHB4 clock can be configured to be equal to or a divided version of SYSCLK using the HPRE bitfield of the RCC_CFGR2 register.

RCC and PWRCTRL FSMs function with SYSCLK, but PWRCTRL FSM is gated by the synchronization phase of SYSCLK and CK AHB4. The system cannot enter LPMODE if SYSCLK and CK AHB4 have different frequency (which is set by the HPRE bits of the RCC_CFGR2 register). As a consequence:

- The system stays in Run mode.
- Clocks are stopped like in LPMODE.

Workaround

Clear the HPRE bitfield of the RCC_CFGR2 register to remove the CK AHB4 division factor before requesting entry into the LPMODE.

2.2.19 LSE in bypass mode may not be functional

Description

LSE in bypass mode fails on around 1% of produced parts. The failure rate increases with colder temperatures.

Workaround

None.

2.3 Radio system

2.3.1 Bluetooth® LE frequency deviation

Description

The channel 15 and 31 frequencies are slightly out of specification, which can create communication failures. The fact that the Bluetooth® LE stack handles retries upon failure and the Bluetooth® LE protocol uses channel hopping reduces the impact of such failures.

Note: The product still meets the Bluetooth® LE certification requirements.

Workaround

When the device plays a critical role in a Bluetooth® LE application, avoid using these channels by issuing the HCI update channel map command HCI_LE_SET_HOST_CHANNEL_CLASSIFICATION.

2.3.2 Nonlinear behavior of Bluetooth® LE RSSI reporting

Description

The RSSI is linear only in the range [-32 dBm; -70 dBm].

Workaround

None.

2.4 TIM

2.4.1 Unexpected PWM output when using ocref_clr

Description

In combined PWM mode 1, asymmetric PWM mode 1, or asymmetric PWM mode 2, using ocref_clr can cause the tim_ocxrefc output to be unexpectedly re-enabled or disabled. This behavior depends on the timing of when ocref_clr is activated and deactivated.

Workaround

None.

2.5 LPTIM

2.5.1 Device may remain stuck in LPTIM interrupt when entering Stop mode

Description

This limitation occurs when disabling the low-power timer (LPTIM).

When the user application clears the ENABLE bit in the LPTIM_CR register within a small time window around one LPTIM interrupt occurrence, then the LPTIM interrupt signal used to wake up the device from Stop mode may be frozen in active state. Consequently, when trying to enter Stop mode, this limitation prevents the device from entering low-power mode and the firmware remains stuck in the LPTIM interrupt routine.

This limitation applies to all Stop modes and to all instances of the LPTIM. Note that the occurrence of this issue is very low.

Workaround

In order to disable a low power timer (LPTIMx) peripheral, do not clear its ENABLE bit in its respective LPTIM_CR register. Instead, reset the whole LPTIMx peripheral via the RCC controller by setting and resetting its respective LPTIMxRST bit in the relevant RCC register.

2.5.2 ARRM and CMPM flags are not set when APB clock is slower than kernel clock

Description

When LPTIM is configured in one shot mode and APB clock is lower than kernel clock, there is a chance that ARRM and CMPM flags are not set at the end of the counting cycle defined by the repetition value REP[7:0]. This issue can only occur when the repetition counter is configured with an odd repetition value.

Workaround

To avoid this issue, the following formula must be respected:

$$\{ARR, CMP\} \geq KER_CLK / (2 * APB_CLK),$$

where APB_CLK is the LPTIM APB clock frequency, and KER_CLK is the LPTIM kernel clock frequency. ARR and CMP are expressed in decimal value.

Example: The following example illustrates a configuration where the issue can occur:

- APB clock source (MSI) = 1 MHz, kernel clock source (HSI) = 16 MHz
- The repetition counter is set with REP[7:0] = 0x3 (odd value)

The above example is subject to issues, unless the user respects:

$$\{CMP, ARR\} \geq 16 \text{ MHz} / (2 * 1 \text{ MHz})$$

→ ARR must be ≥ 8 and CMP must be ≥ 8

Note: REP set to 0x3 means that effective repetition is REP+1 (= 4) but the user must consider the parity of the value loaded in the LPTIM_RCR register (=3, odd) to assess the risk of issue.

2.5.3 Interrupt status flag is cleared by hardware upon writing its corresponding bit in LPTIM_DIER register

Description

When any interrupt bit of the LPTIM_DIER register is modified, the corresponding flag of the LPTIM_ISR register is cleared by hardware.

Workaround

None.

2.6 RTC

2.6.1 Alarm flag may be repeatedly set when the core is stopped in debug

Description

When the core is stopped in debug mode, the clock is supplied to subsecond RTC alarm downcounter even when the device is configured to stop the RTC in debug.

As a consequence, when the subsecond counter is used for alarm condition (the MASKSS[3:0] bitfield of the RTC_ALRMASSR and/or RTC_ALRMBSSR register set to a non-zero value) and the alarm condition is met just before entering a breakpoint or printf, the ALRAF and/or ALRBF flag of the RTC_SR register is repeatedly set by hardware during the breakpoint or printf, which makes any attempt to clear the flag(s) ineffective.

Workaround

None.

2.6.2 RTC calendar read may return transient incorrect value when BYPSHAD = 0

Description

When the BYPSHAD control bit in the RTC_CR register is cleared, reading the RTC calendar registers (RTC_SSR, RTC_TR, and RTC_DR) may seldom produce incorrect values. This issue occurs because internal timing can cause the asynchronous RTC calendar registers to be copied into their shadow registers during a transition of the asynchronous registers.

Since this copying process occurs every RTC kernel clock cycle, any erroneous value persists for only one RTC kernel clock cycle. The likelihood of this failure is very low and depends on several factors, including:

- RTC software configuration, such as the RTC kernel clock source, asynchronous prescaler factor, and calibration settings
- APB clock frequency
- Operating voltage and temperature
- The timing of the register read operation

Additionally, process variations may cause timing differences between samples, which can also influence the probability of this failure.

Workaround

To avoid this condition and ensure consistent calendar readings:

- Set the BYPSHAD control bit to 1 in the RTC_CR register to bypass shadow registers.
- Read the RTC calendar registers twice.
- Compare the two readings. If the values differ, repeat the read and compare sequence until two consecutive readings match.

This software method ensures a reliable calendar value under all operating conditions. For further details, see section *Reading the calendar – When the BYPSHAD control bit is set in the RTC_CR register (bypass shadow registers)* in the reference manual.

2.7 I2C

2.7.1 Wrong data sampling when data setup time ($t_{\text{SU,DAT}}$) is shorter than one I2C kernel clock period

Description

The I²C-bus specification and user manual specify a minimum data setup time ($t_{\text{SU,DAT}}$) as:

- 250 ns in Standard mode
- 100 ns in Fast mode
- 50 ns in Fast mode Plus

The device does not correctly sample the I²C-bus SDA line when $t_{SU,DAT}$ is smaller than one I2C kernel clock (I²C-bus peripheral clock) period: the previous SDA value is sampled instead of the current one. This can result in a wrong receipt of target address, data byte, or acknowledge bit.

Workaround

Increase the I2C kernel clock frequency to get I2C kernel clock period within the transmitter minimum data setup time. Alternatively, increase transmitter's minimum data setup time. If the transmitter setup time minimum value corresponds to the minimum value provided in the I²C-bus standard, the minimum I2CCLK frequencies are as follows:

- In Standard mode, if the transmitter minimum setup time is 250 ns, the I2CCLK frequency must be at least 4 MHz.
- In Fast mode, if the transmitter minimum setup time is 100 ns, the I2CCLK frequency must be at least 10 MHz.
- In Fast-mode Plus, if the transmitter minimum setup time is 50 ns, the I2CCLK frequency must be at least 20 MHz.

2.7.2 Spurious bus error detection in controller mode

Description

In controller mode, a bus error can be detected spuriously, with the consequence of setting the BERR flag of the I2C_SR register and generating bus error interrupt if such interrupt is enabled. Detection of bus error has no effect on the I²C-bus transfer in controller mode and any such transfer continues normally.

Workaround

If a bus error interrupt is generated in controller mode, the BERR flag must be cleared by software. No other action is required and the ongoing transfer can be handled normally.

2.8 USART

2.8.1 Wrong data received by SPI slave receiver in autonomous mode with CPOL = 1

Description

The SPI slave receiver device receives wrong data when all the following conditions are met:

- The USART is used in SPI master transmitter mode
- The autonomous mode is used
- The CPOL bit of the USART_CR2 register is set

Workaround

When the autonomous mode is used, do not set the CPOL bit in USART_CR2.

2.8.2 Received data may be corrupted upon clearing the ABREN bit

Description

The USART receiver may miss data or receive corrupted data when the auto baud rate feature is disabled by software (ABREN bit cleared in the USART_CR2 register) after an auto baud rate detection, while a reception is ongoing.

Workaround

Do not clear the ABREN bit.

2.8.3 Noise error flag set while ONEBIT is set

Description

When the ONEBIT bit is set in the USART_CR3 register (one sample bit method is used), the noise error (NE) flag must remain cleared. Instead, this flag is set upon noise detection on the START bit.

Workaround

None.

Note: Having noise on the START bit is contradictory with the fact that the one sample bit method is used in a noise free environment.

2.9 LPUART

2.9.1 Possible LPUART transmitter issue when using low BRR[15:0] value

Description

The LPUART transmitter bit length sequence is not reset between consecutive bytes, which could result in a jitter that cannot be handled by the receiver device. As a result, depending on the receiver device bit sampling sequence, a desynchronization between the LPUART transmitter and the receiver device may occur resulting in data corruption on the receiver side.

This happens when the ratio between the LPUART kernel clock and the baud rate programmed in the LPUART_BRR register (BRR[15:0]) is not an integer, and is in the three to four range. A typical example is when the 32.768 kHz clock is used as kernel clock and the baud rate is equal to 9600 baud, resulting in a ratio of 3.41.

Workaround

Apply one of the following measures:

- On the transmitter side, increase the ratio between the LPUART kernel clock and the baud rate. To do so:
 - Increase the LPUART kernel clock frequency, or
 - Decrease the baud rate.
- On the receiver side, generate the baud rate by using a higher frequency and applying oversampling techniques if supported.

2.10 SPI

2.10.1 RDY output failure at high serial clock frequency

Description

When acting as slave with RDY alternate function enabled through setting the RDIOM bit of the SPI_CFG2 register, the device may fail to indicate its *Not ready* status in time through the RDY output signal to suspend communication. This may then lead to data overrun and/or underrun on the device side. The failure occurs when the serial clock frequency exceeds:

- Twice the APB clock frequency, with data sizes from 8 to 15 bits
- Six times the APB clock frequency, with data sizes from 16 to 23 bits
- Fourteen times the APB clock frequency, with data sizes from 24 to 32 bits

Workaround

None.

2.11 OTG_HS

2.11.1 Potential unexpected transfer on the USB bus instead of a zero-length packet

Description

In both buffer DMA and slave modes, when a zero-length packet must be transmitted on the USB bus, an incorrect data packet can be sent on the USB bus.

Workaround

In buffer DMA mode:

1. Program DIEPCTLx.EPENA=1, DIEPCTLx.SNAK=1, DIEPCTLx.CNAK=0.
2. Wait for 15 AHB clock cycles.
3. Program DIEPCTLx.CNAK=1, DIEPCTLx.SNAK=0.

The above steps must be performed for all IN transfers that involve a zero-length packet transmission.

In target mode:

1. Program DIEPCTLx.SNAK=1, DIEPCTLx.CNAK=0.
2. Wait for 20 AHB clock cycles (this value is determined by considering the fastest AHB clock and slowest phy_clk combination).
3. Program DIEPCTLx.EPENA=1.
4. Wait for 15 AHB clock cycles (fixed safe delay).
5. Program DIEPCTLx.CNAK=1 and DIEPCTLx.SNAK=0.

The above steps must be performed for all IN transfers that involve a zero-length packet transmission in device mode (DIEPTSIZx.XFRSIZ=0 and DIEPTSIZx.PKTCNT=1).

2.11.2 False detection of chirp-K when an FS device is connected

Description

When the host controller is programmed in high-speed mode and the port reset (OTG_HPRT.PRST) is programmed within 150 PHY clock cycles after a full-speed device connection is detected, the controller can detect a false chirp-K. This causes the controller to switch to high-speed operation even though no chirp is received from the connected device.

Workaround

1. Program the OTG_GINTMSK.PRTIM bit to unmask.
2. Configure the OTG_HCFG register to select either the full-speed host or high-speed host.
3. Set the OTG_HCFG.PPWR bit to 1.
4. Wait for the OTG_HPRT.PCDET interrupt, which indicates that a device is connected to the port.
5. Wait for 150 PHY clock cycles.
6. Set the OTG_HPRT.PRST bit to 1 to start the reset process.

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Revision history

Table 4. Document revision history

Date	Version	Changes
14-Feb-2025	1	Initial release.
04-Jul-2025	2	Modified errata: - VREFBUF control by VRS[2:0] not operational - Bluetooth® LE frequency deviation
19-Mar-2026	3	Added: - Incorrect read of audio synchronization registers RCC_ASCNTR and RCC_ASCAR - LSE in bypass mode may not be functional - Unexpected PWM output when using ocref_clr - RTC calendar read may return transient incorrect value when BYPSHAD = 0 - Potential unexpected transfer on the USB bus instead of a zero-length packet - False detection of chirp-K when an FS device is connected Removed : - Reset can cause the system to get stuck in Standby mode or STOP 2 LPMODE - Data transfer from TAMP_BKPxR to key registers must be done only in ascending order when KEYSEL[2:0] is set to 010 or 100
23-Jun-2026	4	Added Reset can cause the system to get stuck in Standby mode or STOP 2 LPMODE wrongly deleted in revision 3.

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