

Inrush current limitation when charging a DC bus capacitor for IEC 61000-3-3 compliance

Introduction

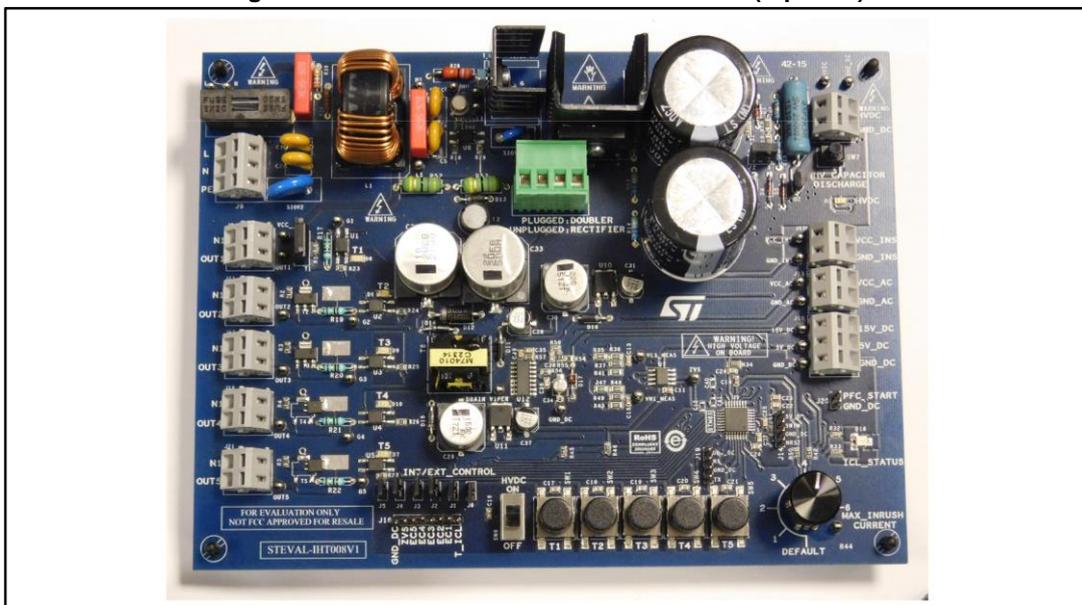
The STEVAL-IHT008V1 evaluation board limits the inrush current charging a DC bus capacitor so that it is compliant with the IEC 61000-3-3 standard. This inrush current is based on a soft-start procedure for the rectifier bridge achieved with a Triac added in series with the mains line, which is controlled through progressive phase-control during the startup phase.

This solution drastically reduces standby losses as the DC bus can be totally disconnected from the AC mains when it is not required. The DC bus is easily turned off by turning off the series Triac, without needing an additional relay to open the circuit in standby.

Steady-state losses are also reduced because NTC resistors, traditionally used to limit inrush current, are not required; nor are the corresponding relays to bypass them.

This board also demonstrates that AC loads can be driven with an isolated easy-to-design solution by using the same power supply as the whole system and some opto-transistors which control the AC switches.

Figure 1: STEVAL-IHT008V1 evaluation board (top view)



Contents

1	Evaluation board objectives	3
1.1	What does this evaluation board aim to demonstrate?	3
1.2	Principal board blocks	3
1.3	Targeted applications	4
1.4	Main part numbers	4
1.5	Operating range and performances	5
1.6	Stand-by consumption	7
2	Getting started	9
2.1	Safety instruction	9
2.2	Board connection and start-up	9
2.3	DC bus capacitor discharge for demonstration purpose	10
2.4	LED indications	10
2.5	Possible board adaptations	11
2.5.1	ACST use and MOV removal	11
2.5.2	EMI filter and DC bus capacitors change	11
2.5.3	Power factor circuit connection	12
2.5.4	Motor Inverter connection	12
2.5.5	Control with an external microcontroller	12
3	Conclusion	13
4	STEVAL-IHT008V1 circuit schematics	14
5	STEVAL-IHT008V1 power supplies and typical consumption... ..	17
6	Inrush-current limitation	19
7	Mains voltage dips and interruptions	23
8	AC voltage monitoring and zero-voltage synchronisation	26
9	Triacs and AC switches insulated control	29
10	EN55014 test results	31
11	STEVAL-IHT008V1 silk-screen	32
12	Test points	35
13	Revision history	36

1 Evaluation board objectives

1.1 What does this evaluation board aim to demonstrate?

This board offers an efficient solution, balancing the following requirements:

- Inrush current limitation without inrush current resistor
- Standby losses in line with ECO European directive
- Low cost and reliable solution to drive AC loads using a single MCU and referenced to the DC bus ground

The STEVAL-IHT008V1 board is designed to demonstrate these criteria independently; you only need to connect the AC loads to check this part.

The STEVAL-IHT008V1 board is also intended as a development tool for designers who want to design a whole system (appliance, air conditioning system, telecom power supply, etc.).

For this purpose, connectors are available to add an external Power Factor Corrector, an Intelligent Power Module (IPM) or to use an external microcontroller (see [Section 2.5: "Possible board adaptations"](#)).

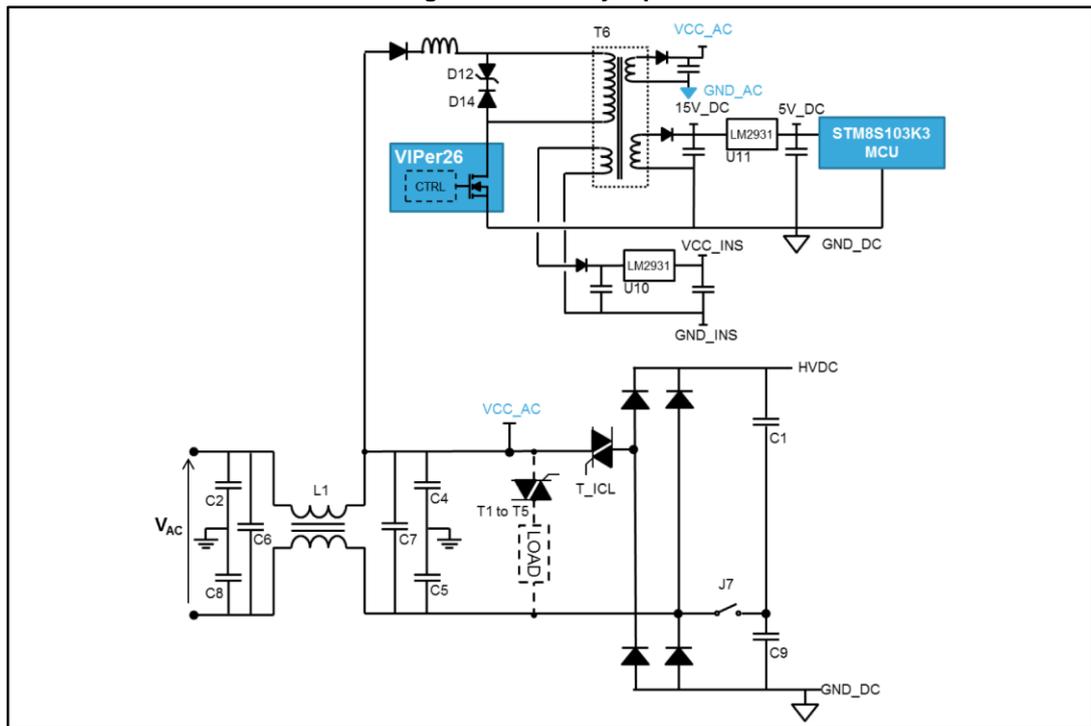
1.2 Principal board blocks

[Section 5: "STEVAL-IHT008V1 power supplies and typical consumption"](#) details the STEVAL-IHT008V1 schematics.

[Figure 2: "Board synopsis"](#) summarizes the STEVAL-IHT008V1 board with the following main components:

- The Triac (T_ICL) in series with the diode bridge
- The AC switches (T1 to T5) connected on AC side to control AC loads. It should be noted that their drive reference (A1) is also connected to the A1 terminal of T_ICL. All A1 terminals are connected to the VCC_AC terminal, allowing this power supply to provide a trigger current to all AC switches gates.
- The MCU, which drives all the AC switches (through opto-transistors, refer to) and can also control any supply or motor inverter referenced to the DC bus ground (GND_DC) in a final application.
- The flyback power converter providing:
 - VCC_AC: 5 V output connected to the Line L1 to implement a negative power supply. This supply is used for the Triac and AC switches control. Maximum output current: 200 mA.
 - 5V_DC: 5 V positive output, referenced to the DC bus Ground (GND_DC). This output supplies the MCU and all the control circuit. Maximum output current: 90 mA.
 - 15V_DC: 15 V positive output, referenced to the DC bus Ground (GND_DC). This output can be used to supply an IPM to control a three-phase motor in a final application. Maximum output current: 500 mA (together with 5V_DC consumption).
 - VCC_INS: 5 V insulated output. This supply can be used if certain components, like sensors, must be insulated from the mains voltage. This output is not used in the demo board. Maximum output current: 90 mA.
 - For further information on the SMPS outputs, please refer to [Section 5: "STEVAL-IHT008V1 power supplies and typical consumption"](#).

Figure 2: Board synopsis



1.3 Targeted applications

Target applications include all applications using a diode-bridge to rectify the line AC voltage and require the removal of the NTC (or PTC) resistor and the limitation of standby losses. Such applications include:

- telecom power supplies
- televisions, DVD and CD players, set-top boxes, etc.
- computers
- lighting equipment

This demo board is also particularly interesting for applications where AC loads have to be controlled, such as for valves, fans, pumps, heating resistors, etc. Such applications include:

- wet appliances (washing machines; dish machines; laundry dryers)
- cold appliances (fridges, freezers)
- air conditioning units

1.4 Main part numbers

The main part number references used in this demo board are:

- Microcontroller Unit (MCU): STM8S103K3
- Flyback IC: VIPER26LD
- Inrush current limiter Triac: T1635T-8FP or ACST1635-8FP (pin-to-pin compatible with T1635T-8FP, SIOV1 can be removed)
- AC loads AC switches:
 - T1: ACST210-8FP (TO-220FPAB package)
 - T2 and T3: ACS108-8SN (SOT223 package)

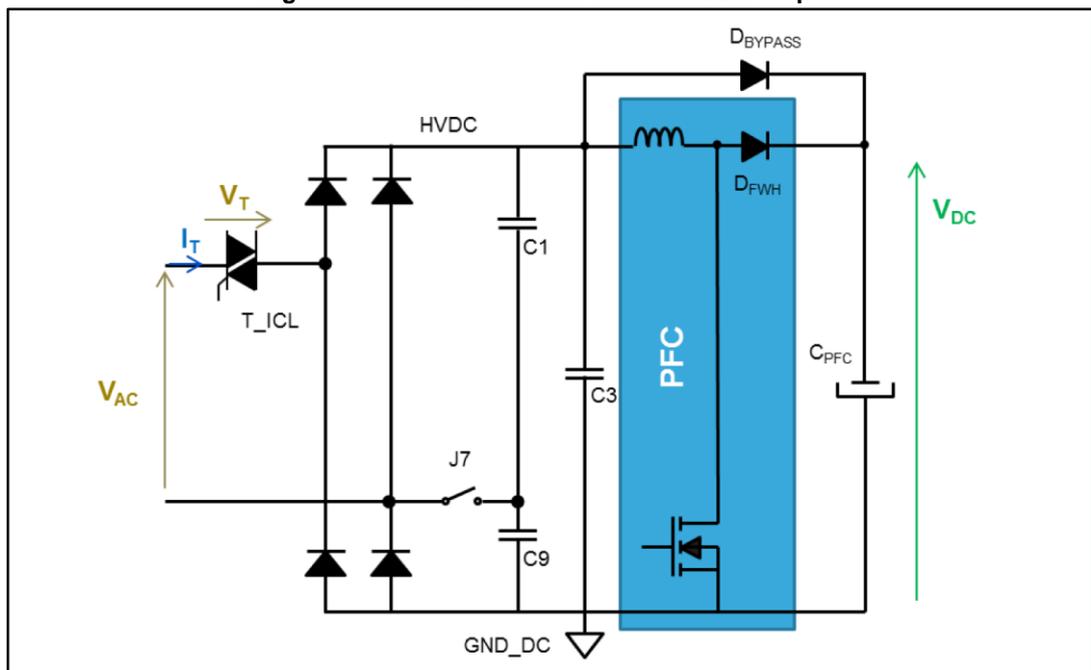
- T4 and T5: Z0109MUF (SMD package)

1.5 Operating range and performances

The STEVAL-IHT008V1 board is designed to operate inside the following operating ranges:

- Line voltage, 2 ranges are possible:
 - 198-264 V RMS, 50 or 60 Hz
 - 90-132 V RMS, 50 or 60 Hz. For this voltage range, operation both in rectifier mode (DC peak voltage = peak line voltage) or in doubler mode are possible (see [Section 2.2: "Board connection and start-up"](#)).
- Ambient temperature: 0°C to 60°C
- Maximum DC load power:
 - DC load (connected between HVDC and GND-DC): 1000 W or 500 W respectively for operation on 230 V or 120 V mains.
- Maximum AC load power:
 - T1: maximum load RMS current has to be lower than 1.1 A, this allows 250 VA or 130 VA power for operation on 230 V or 120 V mains, respectively. This Triac can be used to control a heating resistor or a pump.
 - T2 to T5: the footprint for each of these devices allow either a SMBflat-3L or a SOT-223 package to be soldered. By default, two ACS108-8SN (SOT-223) are used for T2 and T3, with a 5.5 mm² copper area under the tab. These devices can control an RMS load current up to 0.6 A. This allows a 100 VA or 50 VA power load to be controlled on 230 V or 120 V mains, respectively. By default, two Z0109MUF (SMBflat-3L) are used for T4 and T5, with a 33.6 mm² copper area under the tab. These devices can control an RMS load current up to 0.44 A. This allows a 140 VA or 70 VA power load to be controlled on 230 V or 120 V mains, respectively. These four Triacs can be used to control a pump, a fan or any electromagnet (valve, damper, door-lock, etc.).
- Allowed DC output capacitor (or DC bus capacitor) range: 50 µF to 500 µF (in rectifier mode) or to 1000 µF (in doubler mode).
 - This DC output capacitor value is the equivalent value of all capacitors placed in parallel at the bridge output, like C1, C9, C3, and CPFC at PFC output (refer to [Figure 3: "Connection of a PFC at the HVDC output"](#)). If an interleaved PFC is used, all the output capacitors of each PFC must be added.
 - If the J7 connector is closed (doubler mode), no PFC should be used. C3 is also not added. In this case, the equivalent capacitor is only C1 (or C9 as they both have the same value).

Figure 3: Connection of a PFC at the HVDC output



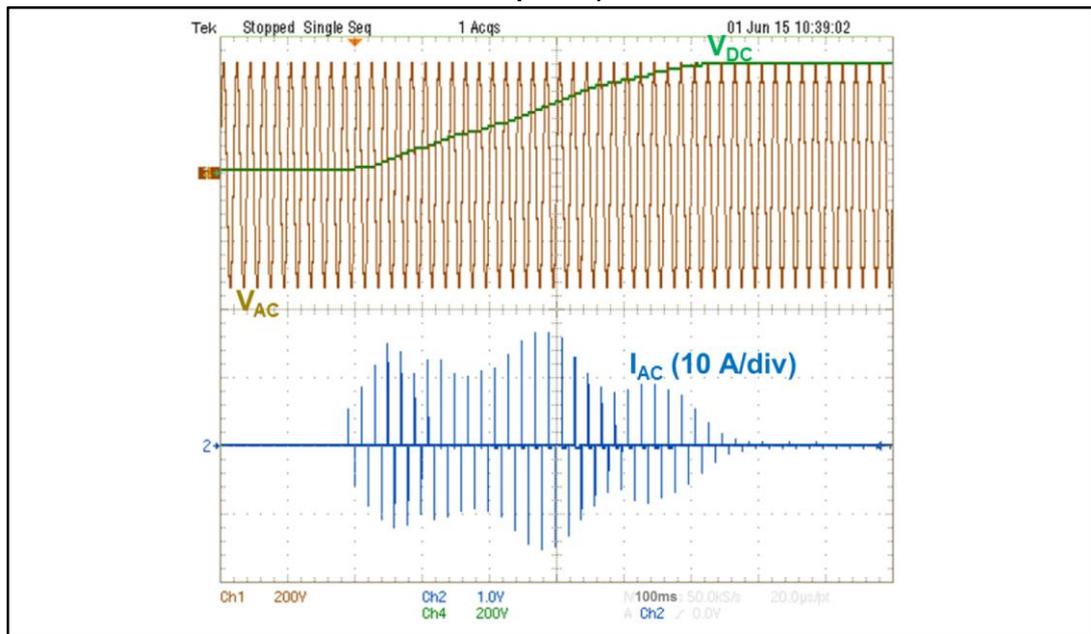
The main STEVAL-IHT008V1 board performance characteristics are:

- Efficiency at 230 V 50 Hz 1000 W (only DC resistive load) = 97%
- Efficiency at 120 V 60 Hz 500 W (only resistive DC load, rectifier or double modes) = 96%
- Standby losses < 150 mW (refer also to section 2.6)
- Compliance with IEC 61000-3-3 (with potentiometer "MAX_INRUSH CURRENT" set to default position; refer to [Section 6: "Inrush-current limitation"](#))
- Compliance with EN55014 (CIPSPR 22 method B; refer to [Section 10: "EN55014 test results"](#))
- IEC 61000-4-4: 2 kV criteria A, T_ICL Triac withstands a 5 kV level without triggering. This is to avoid undesirable triggering and uncontrolled inrush current due to EMI noise.
- IEC 61000-4-5: 2 kV criteria A
- IEC61000-4-11: criteria A for dips down to 100% of the line voltage during 1 cycle; criteria B for interrupts up to 300 cycles or more (refer to [Section 7: "Mains voltage dips and interruptions"](#)).

Figure 4: "Inrush current at STEVAL-IHT008V1 startup on 230 V line (500 μ F output DC capacitor)" shows an example of the progressive DC capacitor charge ensured by the T_ICL Triac. The test is performed at startup when the STEVAL-IHT008V1 board is connected to a 230 V 50 Hz grid, while the output DC capacitor is completely uncharged (initial voltage is zero). The output DC capacitor is implemented in this case via the series association of C1 and C9, hence the equivalent capacitance is 500 μ F.

The output capacitor is charged in 550 ms with the input RMS current remaining far below the 16.1 A limit. IEC 61000-3-3 compliance is therefore easily achieved.

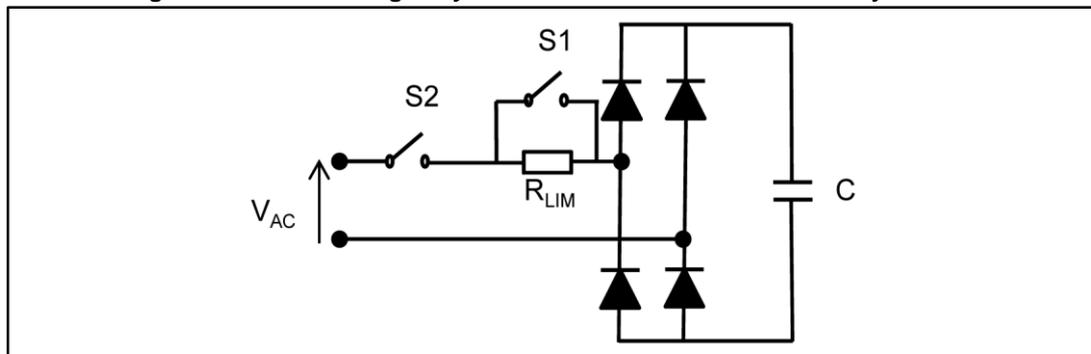
Figure 4: Inrush current at STEVAL-IHT008V1 startup on 230 V line (500 μ F output DC capacitor)



1.6 Stand-by consumption

One of the main advantages of using the T_ICL Triac in front of the rectifier bridge is that it allows full bridge disconnection during standby to suppress losses. This can also be achieved by adding a front-end relay (like S2 in [Figure 5: "Solution using relays to limit inrush current and standby losses"](#)). But, thanks to the T_ICL Triac, this function is already available by simply turning off this Triac.

Figure 5: Solution using relays to limit inrush current and standby losses



To give an idea of the benefits of such bridge disconnection, we measured the typical losses of the STEVAL-IHT008V1 board in standby mode. Three cases are tested:

- Case 1: STEVAL-IHT008V1 board (unmodified) with T_ICL in OFF state ("HVDC" switch in OFF position).
- Case 2: as above, but with a PTC (EPCOS B59107J0130A020) plugged in place of the T_ICL Triac to simulate the losses for a classic solution using only one PTC and

one bypass relay (refer to RLIM and S1 on [Figure 5: "Solution using relays to limit inrush current and standby losses"](#)).

- Case 3: as above, but circuits used solely for demonstration purposes and which consume undesired power at standby are disconnected. These circuits are the "HV Capacitor Discharge" circuit (where R7 and R10 are connected to the DC bus) and the "HVDC" LED (D2) indicating presence of high voltage (where D1, R12, and R13 are connected to the DC bus).

[Table 1: "Comparison of standby losses"](#) gives the experimental results for the three cases in the three different modes of operation (230 V, 110 V line voltage in rectifier and doubler mode). The tests results clearly show that the Triac solution is the only one to achieve a power consumption level lower than 0.5 W, as currently required by European directive 2005/32/EC.

The losses measured for case 3 are mainly due to the resistor divider circuit (R9, R11, R14, R16) used to balance the voltage across the 2 series capacitors (C1 and C9) and the other resistor divider circuit (R30, R31) used to sense the HVDC voltage. On our board, the HVDC voltage is monitored to check proper soft-start operation and to avoid that the DC capacitor charge duration is too long (if, for example, a load remains connected to the DC bus before start-up). In standard circuits, however, such a voltage sensor is often required (to start the PFC or the DC-DC supplies, for example).

The losses for a 230 V rectified voltage equal 520 mW for the 200 kΩ R9, R11, R14 and R16 equivalent resistor, and 52 mW for the 2 MΩ R30 and R31 equivalent resistor.

Table 1: Comparison of standby losses

Mode of operation	Case 1 T_ICL OFF	Case 2 PTC instead of Triac	Case 3 PTC discharge and D2 LED circuits removed
230 V	125 mW	1.7 W	950 mW
110 V / rectifier mode	70 mW	0.6 W	280 mW
110 V / doubler mode	70 mW	1.5 W	860 mW

2 Getting started

2.1 Safety instruction



The high voltage levels used to operate the STEVAL-IHT008V1 evaluation board can represent a serious electrical shock hazard. This evaluation board must be used in a suitable laboratory only by qualified personnel who are familiar with the installation, use, and maintenance of power electrical systems.

The STEVAL-IHT008V1 evaluation board is designed for demonstration purposes only, and must never be used for either domestic or industrial installations.

2.2 Board connection and start-up

Please follow this procedure to use the STEVAL-IHT008V1 board:

1. If you want to operate the board on a 98-132 V line voltage and have a DC bus voltage two times higher than the peak line voltage, plug the jumper (see [Figure 6: "\(a\) J7 jumper plugged on board \(doubler mode\)"](#)) to the position indicated by the silk-screen (refer to [Figure 7: "\(b\) Jumper position left free \(rectifier mode\)"](#)). If you want the rectifier to operate in a classic rectifier circuit, do not plug the J7 jumper.
2. Connect the AC load terminals (if used) to the associated headers (e.g., for AC switch T1, refer to the "N1-OUT1" label in [Figure 23: "STEVAL-IHT008V1 silk-screen \(Top side\)"](#)).
3. Connect the L, N and PE (if required) of J9 header to an unpowered mains plug.
4. Apply the mains voltage. From this moment on, avoid any contact with live parts subject to line voltage.
5. Switch the "HVDC ON" toggle button to the "ON" position" to start charging the DC capacitors.
6. The AC loads are switched on and off each time the associated push-buttons (T1 to T5) are pressed. These loads are controlled even if the "HVDC ON" button is kept in the OFF position.
7. The rate of DC capacitor charging can be increased if the allowed peak current is increased. To do this, turn the "MAX-INRUSH CURRENT" potentiometer clockwise.



compliance with the IEC 61000-3-3 standard is only guaranteed when the potentiometer is set to the default position (between 0 and 1 mark) and with original values of the EMI filter and output DC capacitors.

The following figures show the J7 jumper connection for doubler mode (a) or rectifier mode (b).

Figure 6: (a) J7 jumper plugged on board (doubler mode)

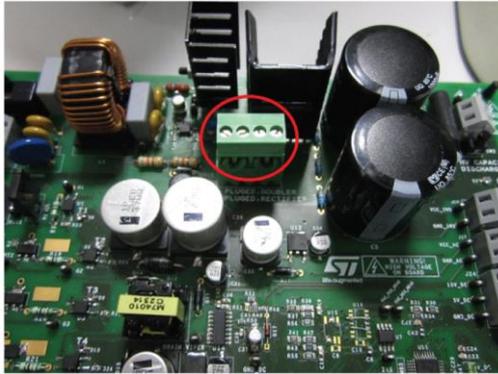


Figure 7: (b) Jumper position left free (rectifier mode)



2.3 DC bus capacitor discharge for demonstration purpose

With default STEVAL-IHT008V1 1000 μF output capacitors (C1, C5) and associated 50 k Ω resistors (R9, R11, R14, R16) used in parallel to balance the voltage across the two series capacitor, the DC bus discharging time takes a few minutes if no load is connected.

A circuit is included to accelerate this discharging time, especially if several startups need to be performed inside a short time interval for test or demonstration purposes. This circuit is made with the Q2 MOSFET and R8 Resistor. Q2 remains on for as long as the SW7 SPDT toggle (refer to the "HV CAPACITOR DISCHARGE" label in [Figure 23: "STEVAL-IHT008V1 silk-screen \(Top side\)"](#)) is switched to the momentary ON position.

The two 1000 μF capacitors are then discharged within two seconds, approximately. The SW2 switch must at least be kept in the momentary ON position during these two seconds. The D2 LED (refer to the "HVDC" label in [Figure 23: "STEVAL-IHT008V1 silk-screen \(Top side\)"](#)) remains lit while the HVDC voltage is above 50 V, so the SW2 switch can be released and a new startup can begin as soon as this LED turns off.

2.4 LED indications

Several LEDs are available to signal useful information:

- ICL-STATUS" (LED D18): indicates several things according to its color:
 - When the board is powered, the LED passes from red, to orange, to green, which indicates that the microcontroller has finished startup (correct mains connection and line frequency measurement, power supply available, etc.) and the board is ready. The green LED then switches off to reduce the board consumption in standby. From this moment, the DC output capacitor can be charged when the "HVDC" switch (SW6) is set to the "ON" position.
 - Green flashing indicates the DC bus capacitors are charging (flashing starts after setting the "HVDC" button to the ON position and ends when the DC bus capacitors are fully charged). This flashing mode can last less than 1 second and may therefore go undetected by the end-user.
 - Green constant indicates the DC bus is charged to the correct voltage.
 - Orange flashing indicates the DC bus capacitors are charging but the output DC voltage rate of increase is too low. This may occur if a power load is connected to

- the HVDC bus during charging and sinks a current which is too high, preventing the DC capacitor from being charged efficiently.
- Orange constant indicates the output DC capacitor is not charged to the peak line voltage. This may occur when the bridge is started, but a power load is already connected to the HVDC bus and sinks a current which is too high, preventing the DC capacitor from being fully charged.
 - Red constant indicates the board is connected to a 198-264 V line while the doubler jumper is connected.
 - Red flashing indicates the MCU detected an error (e.g., the line voltage is outside the two correct operating ranges: 90-132 V and 198-264 V; the line frequency is not detected as stable for 50 or 60 Hz).
 - "HVDC" (LED2): this LED lights red when a voltage higher than 50 V is present between HVDC and GND_DC terminals (refer to [Section 2.3: "DC bus capacitor discharge for demonstration purpose"](#) for further information).
 - "OUT1" to "OUT5" (LED6 to LED10) are ON when the corresponding AC switch (T1 to T5) is turned on.

2.5 Possible board adaptations

The STEVAL-IHT008V1 board allows certain external components to be added to the front-end circuit, so designers can validate an entire system. The main possible modifications are listed below.

2.5.1 ACST use and MOV removal

The T1635T-8FP Triac used for T_ICL can be replaced by an ACST1635-8FP. Both devices are indeed pin-to-pin compatible. The MOV used to protect the T1635T-8FP (SIOV1) can be removed as the ACST1635T is an overvoltage protected device.



if the ACST1635-8FP is triggered in breakover mode, the applied current and its rate of increase (di/dt) must remain below the values specified in the datasheet: 290 A peak current (8/20 μ s waveform) and 150 A/ μ s, respectively.

For a high output DC capacitor value, the current may exceed this datasheet limit.

On our board, the input varistor (SIOV2) clamps the voltage applied to the ACST1635-8FP below the typical clamping voltage of the device (VCL) for surges up to 2 kV. This prevents ACST1635-8FP turn-on in breakover.

2.5.2 EMI filter and DC bus capacitors change

The EMI filter and DC capacitors only use through-hole devices to facilitate unsoldering them to replacing them with ones used in the target application. This allows a designer to adapt the EMI filter and HVDC voltage ripple to specific application requirements (such as the power rating).

Obviously, as soon as these component values are modified, the control law of the T_ICL Triac has to be updated to ensure ongoing compliance with the IEC 61000-3-3 limits. For this purpose, the maximum peak current during startup can be adjusted with the "MAX-INRUSH CURRENT" potentiometer. When this potentiometer is turned clockwise, the Triac is turned sooner at each half-cycle, leading to a higher peak current.

The maximum RMS current or voltage fluctuation (when a normalized line impedance is used) must then be measured according to the potentiometer position to check compliance with IEC 61000-3-3.



if the EMI filter capacitors (C3, C4, C44 to C47) values are increased, the values of R9, R11, R14 and R16 may be decreased so the capacitors can still discharge to below a safe voltage level (120 V for a DC voltage) in less than one or two seconds. Indeed the EMI filter capacitors voltage is applied to the power plug when the board is unplugged, so power terminals with accessible live parts represent an electric shock hazard.

2.5.3 Power factor circuit connection

A PFC can be connected on the HVDC bus through the HVDC and GND_DC connections (J12 header). To ensure the correct operation of this PFC circuit, capacitors C1 and C9 must be unsoldered. C3 (no capacitor is soldered here by default) may be used to add a 630 V DC film capacitor.

As the T_ICL Triac is controlled by a DC gate current when the HVDC voltage has reached its steady-state value, either a discontinuous mode or a continuous mode PFC can be used.

For correct operation of the STEVAL-IHT008V1 front-end circuit with a PFC, the PFC must be activated after the "PFC_START" signal has been set to a 5 V high level. This signal is referenced to the GND_DC terminal. It is available through the J20 header.



the PFC DC storage capacitor (ref. CPFC in [Figure 3: "Connection of a PFC at the HVDC output"](#)) has to within the value range defined in [Section 1.5: "Operating range and performances"](#).

2.5.4 Motor Inverter connection

An inverter or any other DC-DC power converter can be added after the PFC or directly behind the HVDC bus output.

A 15 V positive output referenced to the DC Bus Ground (GND_DC) is available through header J10 to supply an IPM module if needed. Ensure that the maximum current which is sunk from this supply is well below the limit given in [Figure 12: "Typical output characteristics of the 5 V and 15 V positive supplies \(5V_DC / 15V_DC\)"](#).

2.5.5 Control with an external microcontroller

It is possible to control the STEVAL-IHT008V1 front-end circuit with an external MCU, instead of using the embedded STM8S103K3. This allows the end-user to directly check the compliance of his or her own firmware with this kind of circuit.

For this purpose, all control signals required to drive the different AC switches are available on the J16 header. EC1 to EC5 are the external control signals of AC switches T1 to T5; T_ICL is the connection to externally drive the T_ICL Triac. The GND_DC and ZVS signals are also available on this header to synchronize the control signals of the external MCU.

For correct operation with external signals, jumpers J1 to J6 (refer to the "INT/EXT_CONTROL" label [Figure 23: "STEVAL-IHT008V1 silk-screen \(Top side\)"](#)) must be removed. The removal of these jumpers indeed allows the disconnection of the opto-transistor input LEDs from the U9 microcontroller outputs ([Figure 8: "STEVAL-IHT008V1 power side and insulated control schematic"](#)).

3 Conclusion

This evaluation provides an innovative front-end circuit to allow both inrush current limitation and power loss reduction. Above and beyond the simple demonstration of the efficiency and the robustness of this solution by STMicroelectronics, this front-end circuit also represents the starting point for building entire system and accelerating the time-to-market of new application designs.

Figure 9: STEVAL-IHT008V1 control circuit schematic (1 of 3)

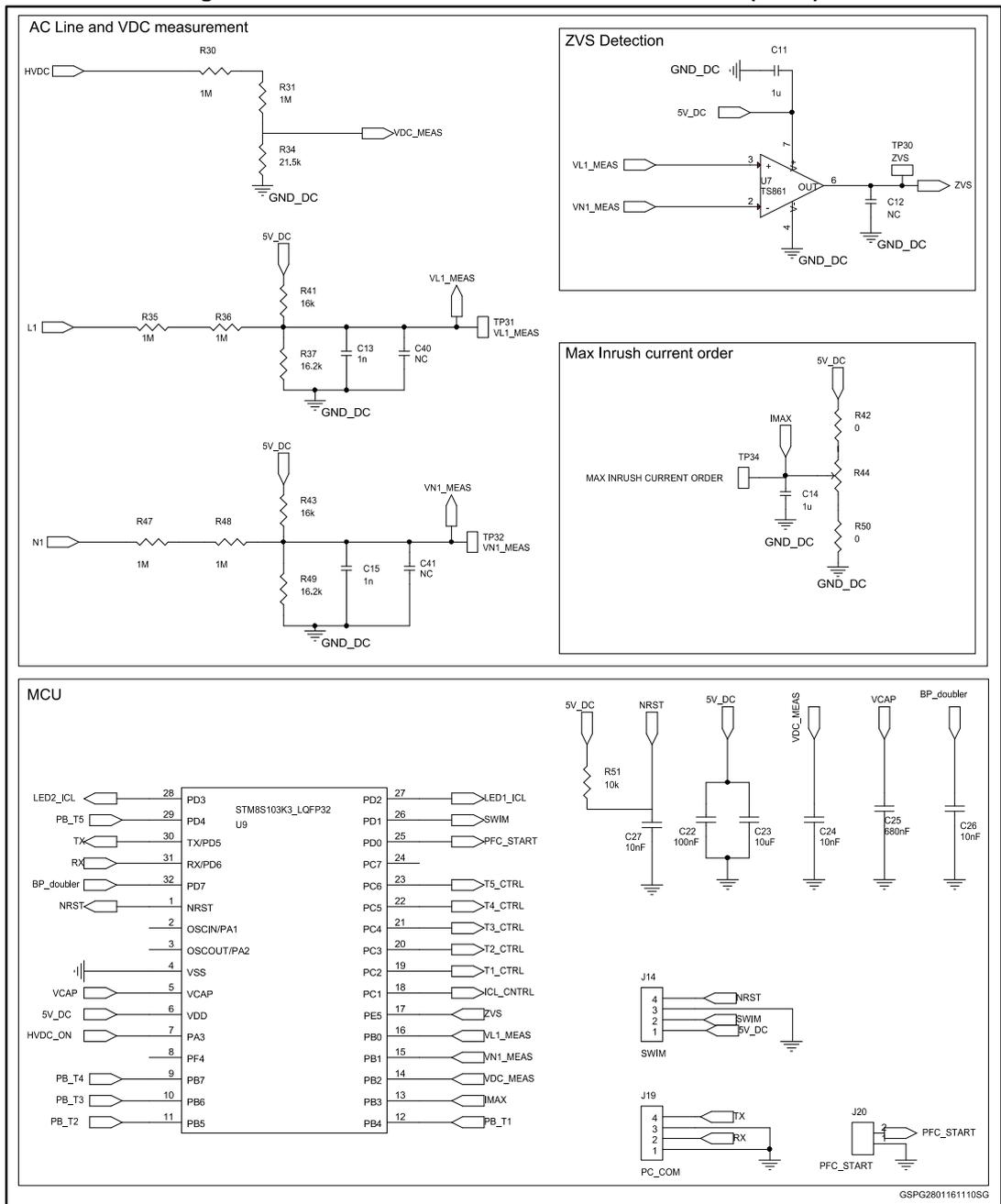


Figure 10: STEVAL-IHT008V1 control circuit schematic (2 of 3)

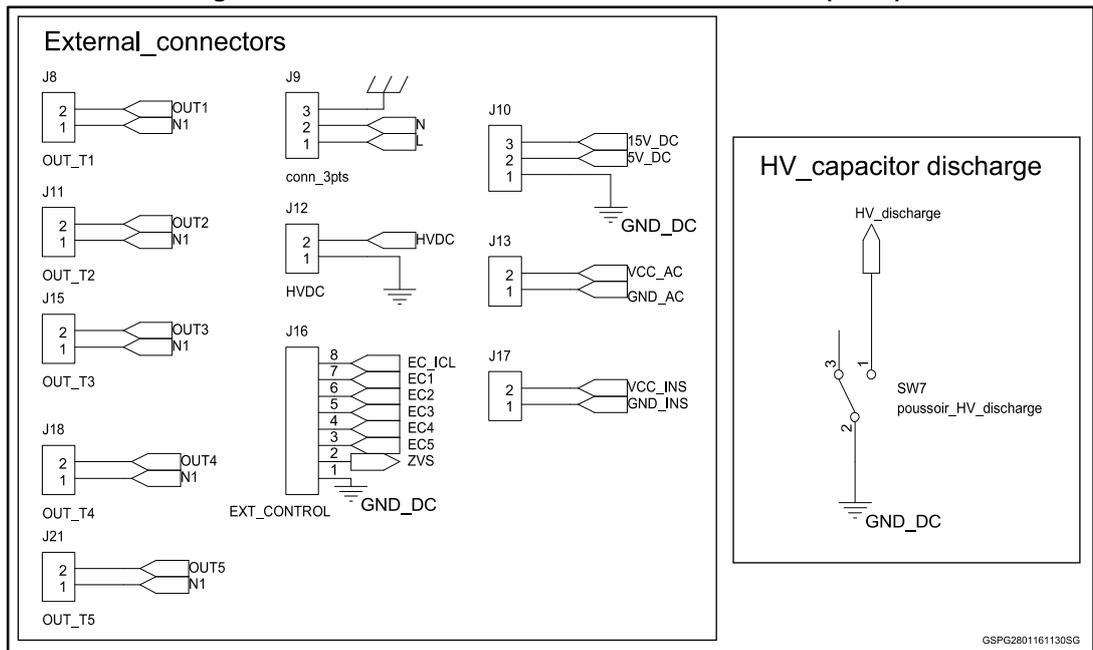
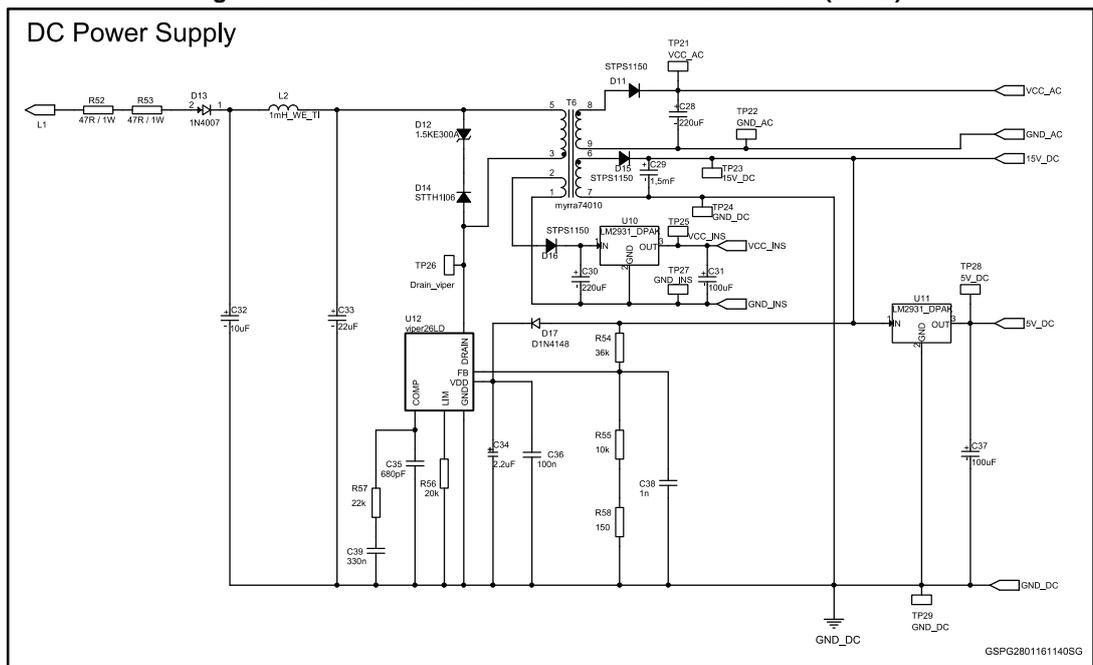


Figure 11: STEVAL-IHT008V1 control circuit schematic (3 of 3)



5 STEVAL-IHT008V1 power supplies and typical consumption

Table 2: "Typical STEVAL-IHT008V1 control-circuit consumption" gives the typical current consumed from the 5V_DC output for the different operating modes of the STEVAL-IHT008V1 board.

Table 2: Typical STEVAL-IHT008V1 control-circuit consumption

Operating mode	Current sunk from 5V_DC (mA)
MCU in standby mode	2
MCU running with 1 ACS switch ON (T2 to T5)	14
MCU running with T_ICL ON	17
MCU running with T_ICL and 1 ACS switch ON	24
MCU running with T_ICL and 4 ACS switches ON	45

As listed in [Section 1.2: "Principal board blocks"](#), the Flyback implements four output supplies. The non-regulated 5 V VCC_AC negative supply is used for the Triac and ACS control. The 15 V and 5 V positive supplies (15V_DC and 5V_DC outputs) are used to supply circuits referenced to the DC bus Ground (MCU, IPM if one is added).

The 5 V insulated supply (VCC_INS / GND_INS) can be used for sensors if needed. On original STEVAL-IHT008V1 manufactured boards, this insulated supply is not used.

Only the 15 V positive output is regulated by the VIPer26LD circuit as this supply is always loaded when the other outputs are loaded. The two 5 V positive supplies (5V_DC, VCC_INS) are also regulated thanks to two LM2931 positive voltage regulators.

The VCC_AC level is not regulated. Its voltage level will be higher if it is not loaded and if the 15 V positive supply is loaded with its highest maximum current.

The current capabilities of the different outputs are (for the whole operating range):

- for 5V_DC: 90 mA
- for VCC_AC (non-regulated 5 V negative output): 200 mA
- for 15V_DC: 500 mA (with 5V_DC consumption included)
- for VCC_INS (optional 5 V regulated output): 90 mA

Figure 13: "Typical output characteristics of the 5 V negative supply (VCC_AC) and 5 V insulated supply (VCC_INS)" and *Figure 14: "Inrush current during STEVAL-IHT008V1 startup on 230 V line (500 µF output DC capacitor)"* give the typical output voltage for the current which is sunk from each output. These measurements are performed with the STEVAL-IHT008V1 connected to either a 230 V or 120 V line, with the bridge operating in rectifier mode (not doubler) and across the entire operating temperature range (0-60 °C). The 15 V_DC, and the 5 V outputs (5V_DC and VCC_INS) are well regulated thanks to the VIPer26LD and the LM2931 devices, respectively.

For the VCC_AC, two curves are given to give the minimum and maximum values of this output. The minimum voltage is reached when the SMPS is delivering the minimum output current (no current sunk from the 15V_DC and the VCC_INS outputs; the 5V_DC is only loaded by the MCU, which is controlling one ACS ON).

The VCC_AC measurement is also performed when only one ACS switch is ON as VCC_AC is dedicated to the Triac and ACS switches driving. So the minimum available voltage (to define the gate resistor value to apply enough gate current) is an important value, at least when one AC switch is on.



For Figure 14: "Inrush current during STEVAL-IHT008V1 startup on 230 V line (500 μ F output DC capacitor)", the output current of the horizontal axis gives the extra current sunk from the output voltage when one ACS switch is ON. This means that for a zero current, a current close to 20 mA is already sunk from the VCC_AC supply. This is not the case for the VCC_INS output.

The maximum VCC_AC voltage is reached when the SMPS 15V_DC output is loaded to the maximum output current (500 mA), while only one AC switch is ON. Indeed if more ACS switch gate currents are sunk from VCC_AC, this level decreases.

Figure 12: Typical output characteristics of the 5 V and 15 V positive supplies (5V_DC / 15V_DC)

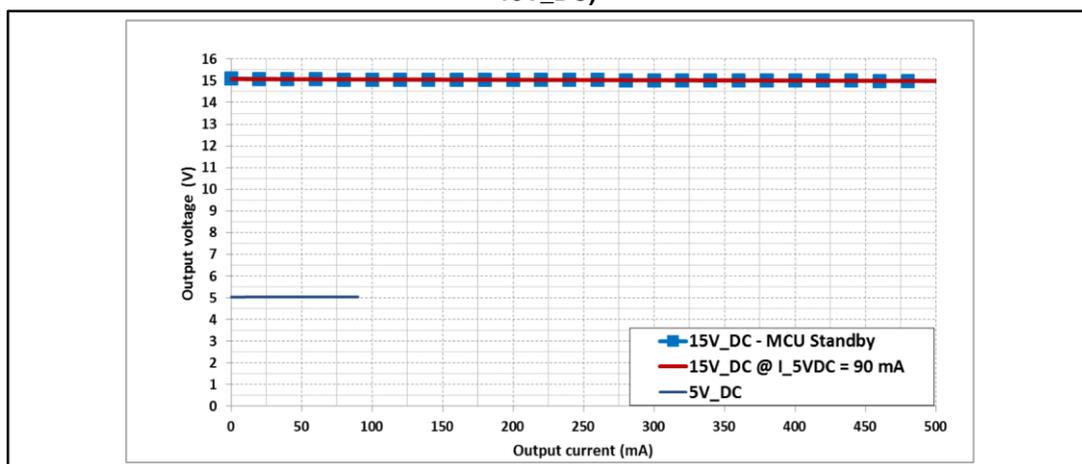
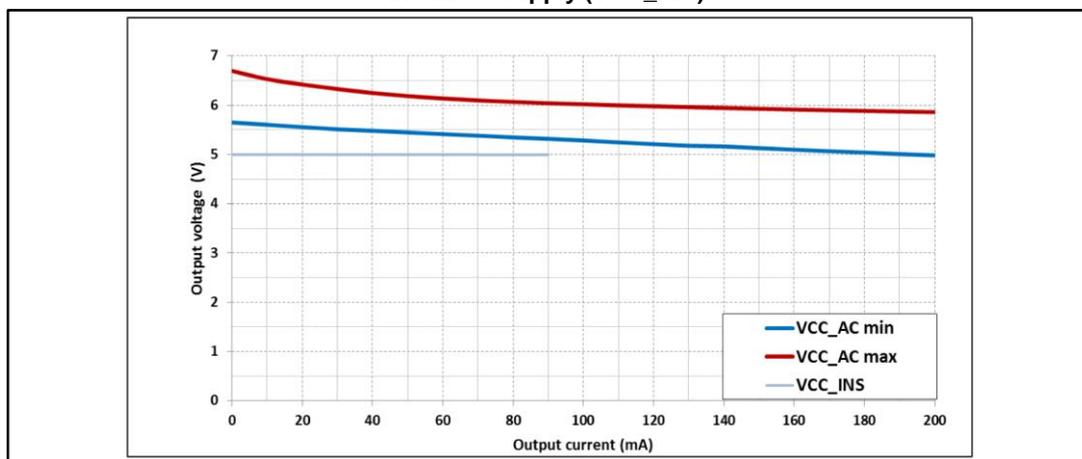


Figure 13: Typical output characteristics of the 5 V negative supply (VCC_AC) and 5 V insulated supply (VCC_INS)



6 Inrush-current limitation

IEC 61000-3-3 standard reminder

The IEC 61000-3-3 standard gives the limitation of voltage changes and fluctuations for equipment with rated RMS current lower than 16 A connected to a public low-voltage grid. These voltage fluctuations are indeed caused by the equipment if too high a current is sunk from the grid. A voltage drop is then caused due to the line impedance.

The mains voltage fluctuation causes an undesirable variation in the brightness of lamps and displays; namely, the flicker phenomenon. This is why designers must keep the inrush current sunk by their equipment to below specific limits.

The following equation explains the link between the line current variation ΔI_{input} (due to the equipment operation) and the relative mains voltage variation (ΔU), which must be lower than the maximum allowed value (d_{max} given in %).

$$\Delta U = \Delta I_{\text{input}} \times Z_{\text{ref}} / U \times 100 < d_{\text{max}}$$

where Z_{ref} is the normalized line impedance (0.6 Ω with 796 μH in series for a single-phase grid) and U is the nominal RMS line voltage.

The d_{max} level should not exceed 4%. A 6% or 7% limit is also allowed according to the way the equipment is switched (manually or automatically, delayed or not, etc.) or for specific appliances.

If the ΔU variation exceeds 3.3% during a single voltage change, this should not last more than 500 ms.

[Table 3: "Maximum input RMS current variation for 230 V single-phase grid according to IEC 61000-3-3"](#) gives the associated maximum input current variation related to these different d_{max} levels. To simplify the analysis, it could be said that an appliance will fulfill with the IEC 61000-3-3 limit at startup if its RMS current remains below 16.1 A. The relative variation is thus lower than 3.3% and compliance is ensured even if startup lasts more than 500 ms. It is clear that this is a restricted case for simplification purposes, higher current variations may also still allow compliance with this standard.

Table 3: Maximum input RMS current variation for 230 V single-phase grid according to IEC 61000-3-3

d_{max} (%)	ΔU (V)	I_{input} (A)
3.3	7.6	16.1
4	9.2	19.5
6	13.8	29.3
7	16.1	34.1

STEVAl-IHT008V1 compliance with the IEC 61000-3-3 limit

Currently, one of the most used solutions to limit inrush current consists of adding a resistor (refer to RLIM in [Figure 5: "Solution using relays to limit inrush current and standby losses"](#)) in series with the DC capacitor (refer to C). This resistor must then be bypassed to limit power losses during steady-state operation. Usually, a relay or a Triac (S1) is used for this purpose. To disconnect the DC bus during standby mode, a second switch (S2) is required.

To avoid the use of the RLIM resistor, a different startup procedure can be implemented. With the Triac T_ICL placed in series with the diode bridge, the capacitor can be charged smoothly through progressive phase control. As long as the Triac is not triggered, the bridge does not conduct any current, and the DC bus capacitor is not charged. To start

charging the DC capacitor, the Triac must be turned on. To reduce the inrush current, the Triac is first triggered at the end of the line voltage cycle, just a few hundred microseconds before the line zero voltage. This allows the output capacitor (refer to C in [Figure 5: "Solution using relays to limit inrush current and standby losses"](#)) to be charged to a low level (around 10 to 30 V) and not directly to the peak line voltage. The current driven from the line is then much lower than in case of directly charging the DC capacitor completely.

This soft-start solution can only work when an inductor is present on the line side as the current increase rate must also be limited to avoid Triac damage. Such an inductor is already present for most applications where the EMI filter usually embeds a common-mode choke which has a differential-mode parasitic inductor due to the copper turns of the windings.

In our STEVAL-IHT008V1, the EMI filter is implemented by C6-C7 X2 capacitors, C2-C4-C5-C8 Y2 capacitors, and the L1 common-mode inductor. This inductor features a 12 mH value in common-mode but also a 10 μ H inductor in differential mode. This is the differential-mode value which allows the reduction of the rate of increase of the line current each time Triac T_ICL is turned on.

To allow a complete charge of this capacitor to the peak line voltage, the Triac must be triggered on the following cycle with a shorter turn-on delay than the first one used to start the charge. In this way, by reducing the Triac turn-on delay by a few tens or hundreds of microseconds from half-cycle to half-cycle, the output capacitor is progressively charged while the line current is kept low.

In the STEVAL_IHT008V1 MCU firmware, the Triac turn-on delay reduction step is constant from one half-cycle to the following one. This step is called `Step_Phase_Control` in the firmware. It is set by the `Max_Inrush_Current_Order` routine which reads the voltages set by the "MAX_INRUSH CURRENT" potentiometer.

When the T_ICL Triac turn-on delay is lower than 3 ms, the gate pulse is directly set to a continuous DC pulse (starting typically 70 μ s after VAC zero voltage). Indeed, below a delay of approximately 5 ms or 4.2 ms (for 50 and 60 Hz line frequencies, respectively), the output DC capacitor is fully charged. Therefore, it is not necessary to ensure a soft start for turn-on delays much lower than a fourth cycle.



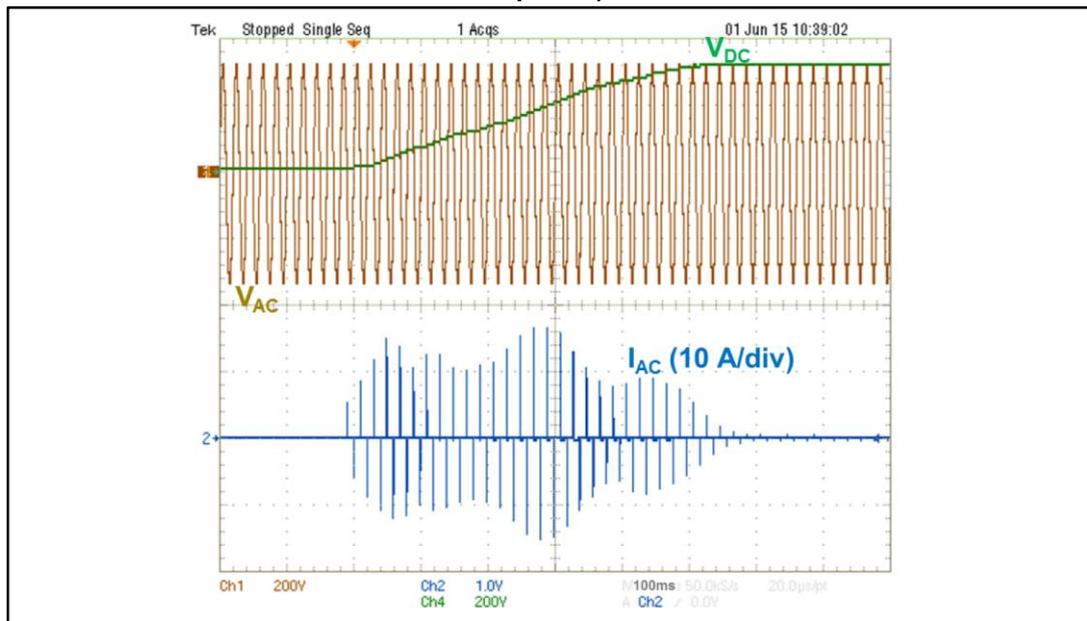
the max T_ICL turn-on delay is defined by the `ICL_CTRL_Delay` in the firmware. The minimum value of 3 ms is defined by the `Phase_Control_ON_Max` which sets the maximum T_ICL ON time (7 ms, refer to directive definitions in the firmware).

[Figure 14: "Inrush current during STEVAL-IHT008V1 startup on 230 V line \(500 \$\mu\$ F output DC capacitor\)"](#) (same as [Figure 4: "Inrush current at STEVAL-IHT008V1 startup on 230 V line \(500 \$\mu\$ F output DC capacitor\)"](#)) shows an example of such progressive DC capacitor charging. The test is performed at startup when the STEVAL-IHT008V1 board is connected to a 230 V 50 Hz grid, while the output DC capacitor is completely uncharged (i.e., its initial voltage is null). The output DC capacitor is implemented in this case by the series association of C1 and C9 for an equivalent capacitance of 500 μ F.



the electric parameters of [Figure 15: "Triac current zoom for the highest peak current during start-up"](#) are defined in [Figure 3: "Connection of a PFC at the HVDC output"](#) (arrow head gives the hot-point of the voltage). In [Figure 3: "Connection of a PFC at the HVDC output"](#), VDC is actually the voltage across capacitor C3 as no PFC is used.

Figure 14: Inrush current during STEVAL-IHT008V1 startup on 230 V line (500 μ F output DC capacitor)



Here, the MCU firmware is the default program, so:

- the first T_ICL turn-on is set to 410 μ s before next line Zero Voltage. As the first gate current pulse lasts 50 μ s, the gate current can be removed 360 μ s before the next half cycle and avoid full-wave conduction in the next half-cycle.
- This 360 μ s interval includes the ZVS signal delay (which can equal up to 70 μ s, see [Section 8: "AC voltage monitoring and zero-voltage synchronisation"](#)), the MCU data treatment time before setting the ICL_CTRL I/O pin to high (40 μ s) and the delay required transistor Q3 to become unsaturated, which drives T_ICL (150 μ s). The total delay time therefore equals 260 μ s; 150 μ s is added as the safety margin. This delay is called `ICL_TRIAC_OFF_Delay` in the firmware. As the timer is launched both in count-up and count-down modes, half of the desired value must be given in this parameter.
- Next T_ICL turn-on occurs 50 μ s sooner each time when the "MAX_INRUSH CURRENT" potentiometer is set to the DEFAULT position. This minimum step value is defined in the directive section of the firmware (`Step_Phase_Control_Min`).



the DEFAULT position corresponds to the slowest output DC capacitor charge and therefore the shortest `Step_Phase_Control` value. When the "MAX_INRUSH CURRENT" potentiometer is turned clockwise after point 1, `Step_Phase_Control` increases roughly linearly from around 50 μ s (position 1) to 600 μ s (position 6).

- When the T_ICL Triac turn-on delay goes lower than 3 ms, the Triac is triggered by a DC gate current.

Figure 15: "Triac current zoom for the highest peak current during start-up" shows that, in these conditions, the inrush peak current remains below 17.4 A. The RMS current is thus far below the 16.1 A limit (as explained below). This means that the relative variation is lower than 3.3%. It is therefore not necessary to check the duration of the accumulated

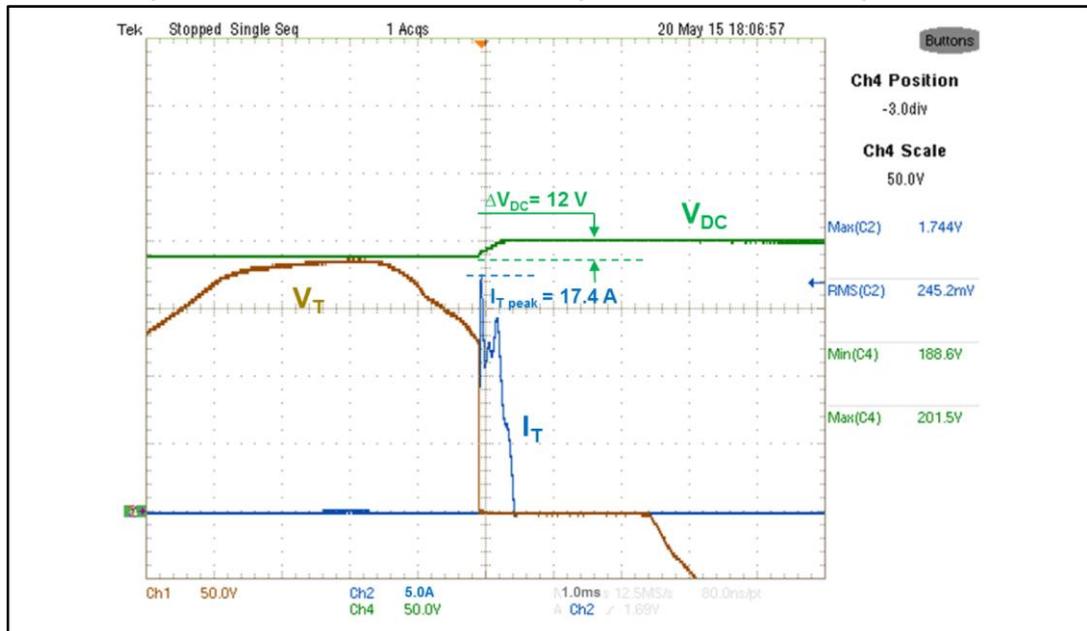
time of deviation exceeding 3.3%. Here, the output capacitor is charged in 550 ms and compliance with IEC 61000-3-3 is achieved.

It should also be noted that the peak current during output capacitor charge is not constant. Indeed, only the step of the reduction of the T_ICL Triac turn-on delay is constant. Hence, depending on when this Triac turns on, the peak current can vary slightly from one period to another.

It can also be noted that we have limited the inrush peak current to below 17.4 A, but the IEC 61000-3-3 limit actually applies to the RMS current. As the T_ICL Triac conducts for a few hundred microseconds each half-cycle, the RMS current is much lower than the peak value. *Figure 16: "(a) Board operation during 1-cycle line interruption"* gives of a zoom of the Triac current for the highest peak current event measured in *Figure 15: "Triac current zoom for the highest peak current during start-up"*. The Triac conduction lasts 560 μ s, its RMS current equals then 2.45 A, which is much lower than the measured 17.4 A peak current.

This figure also shows that the output DC voltage is increased by 12 V during this single Triac conduction.

Figure 15: Triac current zoom for the highest peak current during start-up



7 Mains voltage dips and interruptions

IEC 61000-4-11 standard defines the test conditions to evaluate the immunity of equipment to voltage dips or interruptions. This electromagnetic standard is given as a test method reference by other standards. For example, product standards like EN55014-2 for appliances or EN 55024 for IT equipment, which require product compliance in order to be sold on the European open market, specify the tests to be performed according to IEC 61000-4-11 standard and the expected corresponding tests results.

If a product is not listed in a specific product standard, the general electromagnetic standard applies according to the use environment (residential or industrial, for example).

As any appliance connected to the mains can be subjected to line voltage dips or interruptions, a high input current may occur when the line voltage suddenly increases back to its nominal value to rectifier circuits charging DC capacitors. This high current may damage the front-end circuit components like the bridge diodes, the AC fuse, etc.

Table 4: "Required dips and interruptions tests and STEVAL-IHT008V1 performance" gives the different requirements in terms of line voltage dips and interruptions for the different electromagnetic immunity standards. In summary, the worst cases to account for are:

- Voltage dips: 1 cycle with a 0% residual voltage, and 50 cycles with a 70% residual voltage
- Voltage interruptions: 0% residual voltage during 250 or 300 cycles respectively for 50 and 60 Hz line frequency.

A criteria B is requested for the 0% voltage test during 1 cycle, while the other tests require only a criteria C.

The MCU firmware of the STEVAL-IHT008V1 board is programmed in order to comply with these different standard tests with the following strategy:

- If the line voltage remains higher than 70% to the reference voltage (measured at board startup), no change applies to all the Triacs (including T_ICL) orders.
- If the line voltage falls below 70% of the reference voltage during at least 1.5 cycles, all the Triacs (including T_ICL) are switched off. The DC bus voltage will be discharged by its load current. When the line voltage is reapplied, the T_ICL Triac is controlled in soft-start again to ensure recharging current limitation. It is clear that T_ICL restart only occurs if the HVDC ON SPST switch (SW6) is kept to ON position.



the 1.5 cycle duration to detect whether a voltage dip lasts too long is given by the parameter `Nb_Peak_VAC_Dips`, which is set to 3 by default (meaning 3 times a low peak AC voltage measured). The ratio of voltage decrease from which value an undervoltage is taken into account is set by the parameter `VAC_Variation_Dips` in the firmware (the default value is 0.3 for 30% maximum mains voltage reduction).

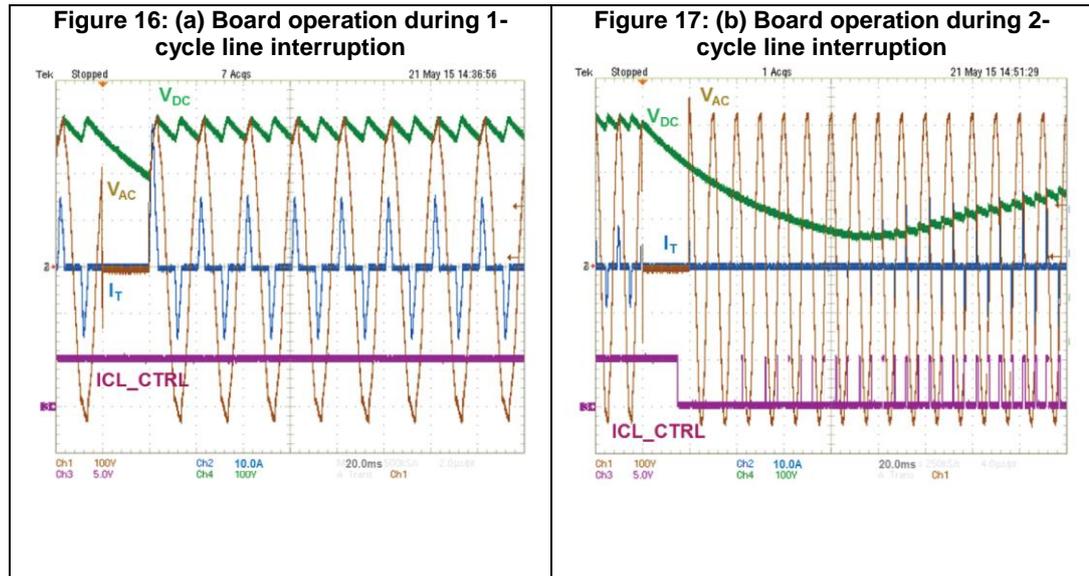
Table 4: "Required dips and interruptions tests and STEVAL-IHT008V1 performance" also provides the test results of the STEVAL-IHT008V1 inrush current limitation function (i.e., the T_ICL control). A criteria A is ensured for all dips, even with a 0% residual line voltage, shorter than 1 cycle. Criteria B is ensured for longer interruptions, even for 300 cycles or more. The performance of the STEVAL-IHT008V1 board is therefore well above the performance levels required by international standards.

Figure 16: "(a) Board operation during 1-cycle line interruption" and *Figure 17: "(b) Board operation during 2-cycle line interruption"* illustrate board behavior, operating at 230 V with a 1000 W DC resistive load, for two different voltage dips with a 0% residual voltage applied during 20 ms (case a) or 40 ms (case b). For case a, the T_ICL Triac is kept ON

during the line interrupt. When the voltage is reapplied, the peak current is only 30 A as the DC voltage only decreased by 60 V during the absence of AC voltage.

For case b, as the interrupt lasts more than 30 ms, the T_ICL Triac is re-triggered when the AC voltage is reapplied. To avoid an excessive inrush current caused by long interrupts, the T_ICL Triac is controlled in a soft-start procedure like for any system startup. The DC capacitor thus starts being recharged when the T_ICL gate current is applied while the AC voltage is higher than the C voltage. In [Figure 17: "\(b\) Board operation during 2-cycle line interruption"](#), this point occurs around 45 ms after the line voltage is reapplied. The peak current is then only 10 A, which is only around two times the nominal current, comfortably low enough to avoid any component damage.

[Figure 16: "\(a\) Board operation during 1-cycle line interruption"](#) and [Figure 17: "\(b\) Board operation during 2-cycle line interruption"](#) illustrate board operation during a 1-cycle (a) or 2-cycle (b) line interruption.



[Table 4: "Required dips and interruptions tests and STEVAL-IHT008V1 performance"](#) lists the different dips or interruption tests required for the different standards listed at the beginning of this section. The test results of the STEVAL-IHT008V1 board are also given for all tests.



These tests results only apply to the inrush current limitation function (thus T_ICL Triac control).

Table 4: Required dips and interruptions tests and STEVAL-IHT008V1 performance

Standard	Application	Test type	% residual voltage	Number of cycles	Required criteria by standard	STEVAL-IHT008V1 result
IEC 61000-6-1	residential, commercial and light-industrial environments	Dips	0	0.5	B	A
			0	1	B	A
			70	25 ¹ /30 ²	C	A
		Interruptions	0	250 ¹ /300 ²	C	A
IEC	industrial	Dips	0	1	B	A

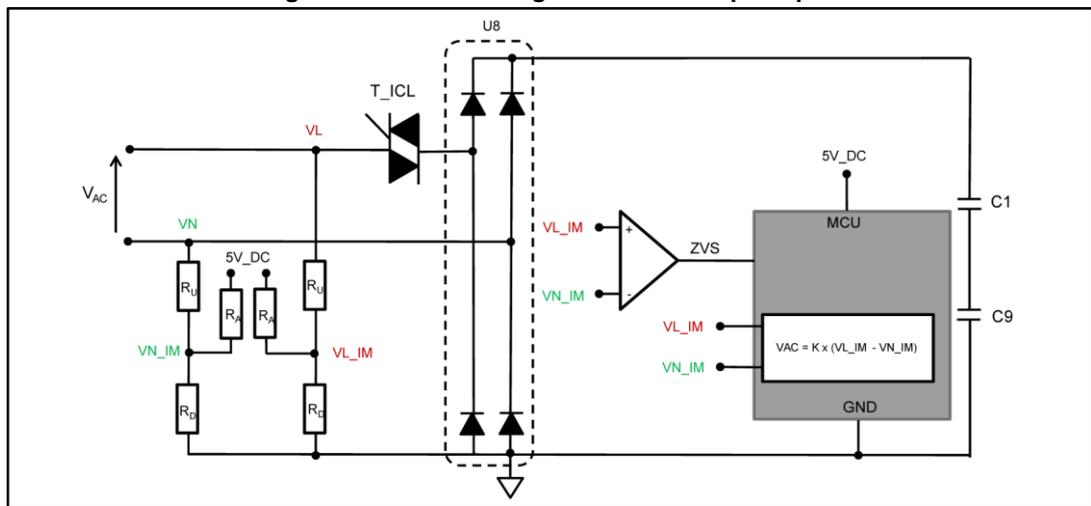
Standard	Application	Test type	% residual voltage	Number of cycles	Required criteria by standard	STEVAL-IHT008V1 result
61000-2-1	environments		40	10 ¹ /12 ²	C	B
			70	25 ¹ /30 ²	C	A
		Interruptions	0	250 ¹ /300 ²	C	B
EN55024	Information technology equipment		< 5	0.5	B	A
			70	25	C	A
			< 5	250	C	B
EN55014-2	appliances, electric tools, etc.		0	0.5	C	A
			40	10	C	B
			70	50	C	A

8 AC voltage monitoring and zero-voltage synchronisation

Zero-Voltage and AC line voltage sensor circuits

The AC line voltage (V_{AC}) must be measured to detect the AC line voltage level and to manage the AC line dips (as described in [Section 7: "Mains voltage dips and interruptions"](#)). As the MCU is connected after the diode bridge, a differential measurement must be performed to measure the AC line voltage (V_{AC}). The V_{AC} measurement is based on the line voltage (V_L) and the neutral voltage (V_N) measurement ($V_{AC} = V_L - V_N$). To sense V_L and V_N , a resistor divider bridge, with a DC offset (V_{OFFSET}) is used (see [Figure 18: "AC line voltage measurement principle"](#)). Thanks to this offset, the images of the V_L (V_{L_IM}) and V_N (V_{N_IM}) remain positive. That means the ICL demo board only requires a single voltage supply, and not a supplementary negative one to measure V_{AC} .

Figure 18: AC line voltage measurement principle



Given the V_L and V_N images, the MCU is able to calculate V_{AC} as per the equation below, where V_{AC_IM} is the image of the AC line voltage and K the proportional coefficient between V_{AC} and V_{AC_IM} defined by the resistor divider bridge.

$$V_{AC} = (V_L - V_N) = K \times (V_{L_IM} - V_{N_IM}) = K \times V_{AC_IM}$$

Choosing the R_U resistance and given that we set V_{L_IM} and V_{N_IM} to be centered around $5V_{DC} / 2$, the equation below shows how the user can determine the resistance R_D , where $V_{AC_RMS_Max}$ is the maximum RMS AC line voltage which can be applied in the application and $V_{AC_IM_Max}$ is the maximum AC line voltage image voltage that can be applied in the MCU ADC input specified by the user.

$$R_D = R_U \times \left(\frac{2 \times V_{AC_IM_Max}}{\sqrt{2} \times V_{AC_RMS_Max} - (2 \times V_{AC_IM_Max})} \right)$$

The following equation shows how the end user should choose resistance R_A

$$R_A = \frac{R_U \times R_D}{R_U + R_D}$$

The next equation gives the proportional coefficient between V_{AC} and V_{AC_IM} .

$$K = \frac{(R_U \times R_D) + (R_A \times R_U) + (R_A \times R_D)}{R_A + R_D}$$

For example, with $R_U = 2 \text{ M}\Omega$, $V_{AC_RMS_Max} = 264 \text{ V}$, and $V_{AC_IM_Max} = 4 \text{ V}$, the following resistor values and the K parameter are determined. For high accuracy, a 1% resistor tolerance is recommended.

$$\begin{cases} R_U = 2 \text{ M}\Omega \\ R_D = 16.2 \text{ k}\Omega \\ R_A = 16 \text{ k}\Omega \\ K = 249.5 \end{cases}$$



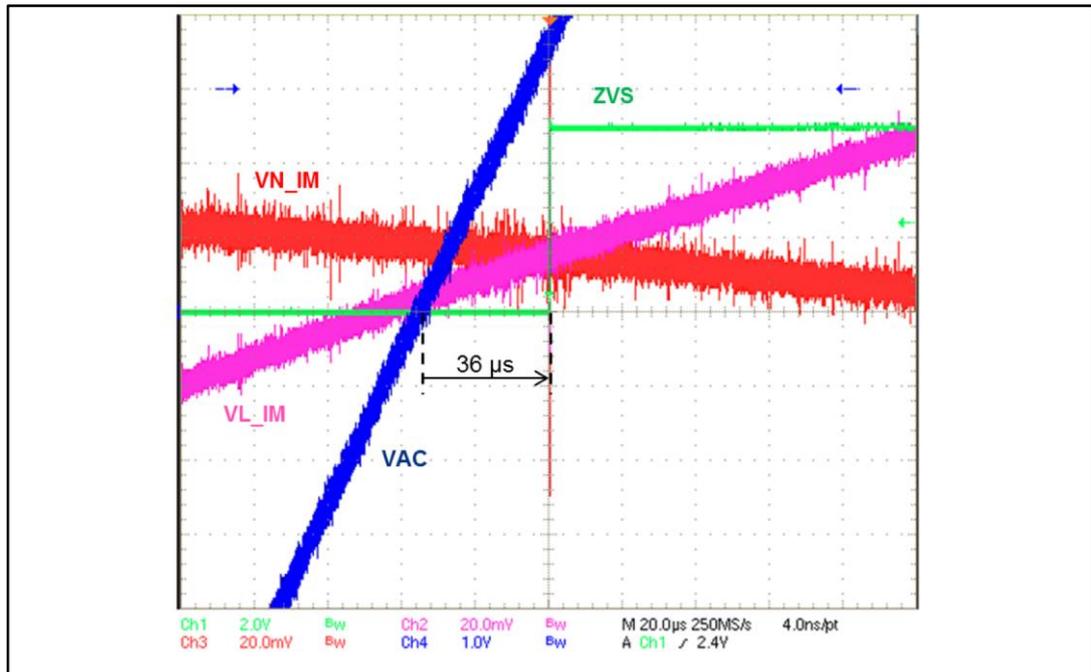
on the I_{CL} board schematic, the resistor bridges are defined with the following values:

$$\begin{cases} R_U / 2 = R_{35} = R_{36} = R_{47} = R_{48} = 1 \text{ M}\Omega \\ R_D = R_7 = R_{49} = 16.2 \text{ k}\Omega \\ R_A = R_{41} = R_{43} = 16 \text{ k}\Omega \\ K = 249.5 \end{cases}$$

Zero AC line voltage detection

The TRIAC phase-control needs to be synchronized with the AC line voltage. The zero AC line voltage crossing detection uses the AC line voltage measurement. Indeed, the zero AC line voltage occurs when the line voltage (V_L) and the neutral voltage (V_N) are equal. In this case, a comparator (U7), connected to the pin 17 of the MCU, compares the V_{L_IM} and V_{N_IM} voltage. As soon as V_{L_IM} is lower than V_{N_IM} the output comparator switches to the low level, as shown in [Figure 18: "AC line voltage measurement principle"](#). This figure shows that the typical delay of the ZVS signal versus the real VAC zero is 36 μs for a 230 V 50 Hz grid voltage.

Figure 19: Zero AC line voltage crossing detection



9 Triacs and AC switches insulated control

The VIPer26LD flyback provides a 5 V DC output voltage. The high terminal of this output is connected to the line (terminal L1, after the EMI filter); this is why this output is called VCC_AC, as it is referenced to the AC voltage, not to the DC bus. Moreover, as the upper level of this output is connected to L1, it allows a negative supply to be implemented. A negative supply is indeed required to sink the current from the AC switch gates. All the AC switches on the STEVAL-IHT008V1 boards are so controlled in quadrants 2 and 3. For more information regarding this, refer to AN3168 or AN4564.

As the MCU is not at the same ground reference as AC switches, optocouplers are needed to control them. The optocoupler must be chosen to generate enough output current (optocoupler collector current) to control AC switches according to the input current (optocoupler LED forward current). In this case, the optocoupler gain, expressed as a current transfer ratio (CTR), must be chosen according to the equation below, where IGT is the AC switch gate current and IO_MCU is the output current supplied by the MCU to control the optocoupler LED.

$$CTR(\%) > \frac{IGT}{IO_MCU}$$

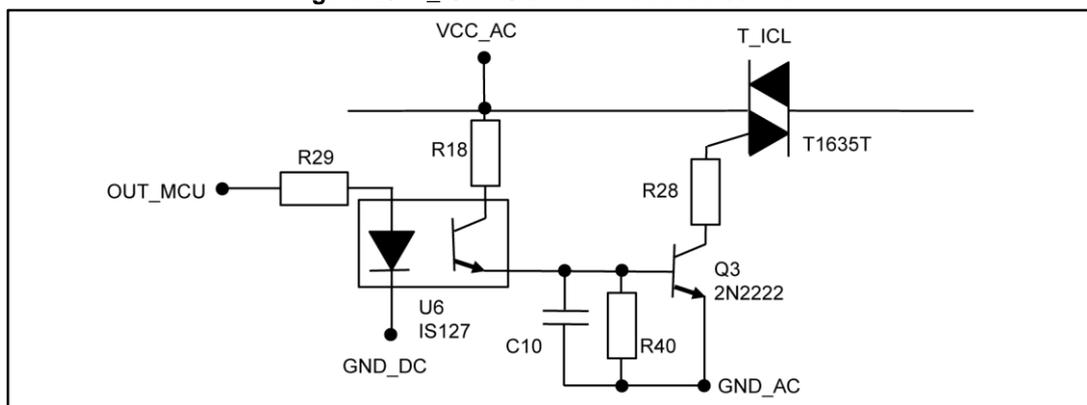
Given the AC switch gate current (IGT), the gate resistor to limit the AC switch gate current can be defined according to the following equation, where VCC_AC is the power supply to provide the gate current to all AC switches and VCE(SAT)_Opto is the transistor collector-emitter of the optocoupler.

$$R_g < \frac{VCC_AC - VCE(SAT)_Opto}{IGT}$$

In our case, the AC switches (T1 to T5) are controlled by using the IS127 optocoupler (U1, U2, U3, U4 and U5), see . The CTR of this optocoupler is 1000 and can provide a 20 mA gate current (which is two times above the 10 mA IGT of the ACS108-8Sx, ACST210 and Z0109 devices) with $R_{17} = R_{19} = R_{20} = R_{21} = R_{22} = 91 \Omega$.

To control the T_ICL AC switch, an optocoupler (U6) associated with a NPN transistor (Q3) is used as shown in the following figure. Moreover, to improve the NPN transistor immunity, a RC filter is connected between the base and the emitter of the NPN transistor ($R_{40} = 4.7 \text{ k}\Omega$ and $C_{10} = 1 \text{ nF}$).

Figure 20: T_ICL AC switch insulated control



The gate resistance (R_{28}) of the T_ICL AC switch is given in the equation below, where VCC_AC is the power supply to provide the gate current to the AC switch, $VCE(SAT)_{NPN}$ is

the NPN transistor collector-emitter, I_{GT} the TRIAC gate current and V_{GT} is the TRIAC gate triggering voltage.

$$R_{28} = \frac{VCC_AC - VCE(SAT)_{NPN} - V_{GT}}{I_{GT}}$$

The collector resistor (R_{18}) of the NPN transistor is defined in the next equation, with R_{40} being the NPN transistor resistor filter, VCC_AC the power supply to provide the gate current to the AC switch, $VCE(SAT)_{Opto}$ the transistor collector-emitter of the optocoupler, I_{GT} the TRIAC gate current, β_{NPN} is the NPN transistor gain and $VBE(SAT)_{NPN}$ is the NPN transistor base-emitter.

$$R_{18} = \frac{VCC_AC - VCE(SAT)_{Opto} - VBE(SAT)_{NPN}}{\frac{I_{GT}}{\beta_{NPN}} + \frac{VBE(SAT)_{NPN}}{R_{40}}}$$

Given the optocoupler and the R_{28} resistor value, the LED resistor R_{29} of the optocoupler is defined by the equation below.

$$R_{29} = \frac{VOH_Min_MCU - VF_{Opto}}{\frac{1}{CTR} \times \frac{VCC_AC - VCE(SAT)_{Opto} - VBE(SAT)_{NPN}}{R_{18}}}$$

in our example, with the IS127 optocoupler and the 2N2222 NPN transistor, the following resistor values should therefore be chosen.

$$\begin{cases} R_{28} = 36\Omega \\ R_{18} = 1.5k\Omega \\ R_{29} = 2.7k\Omega \\ R_{40} = 4.7\Omega \\ C_{10} = 1nF \end{cases}$$

10 EN55014 test results

Figure 21: EMI noise test with 1000 W load

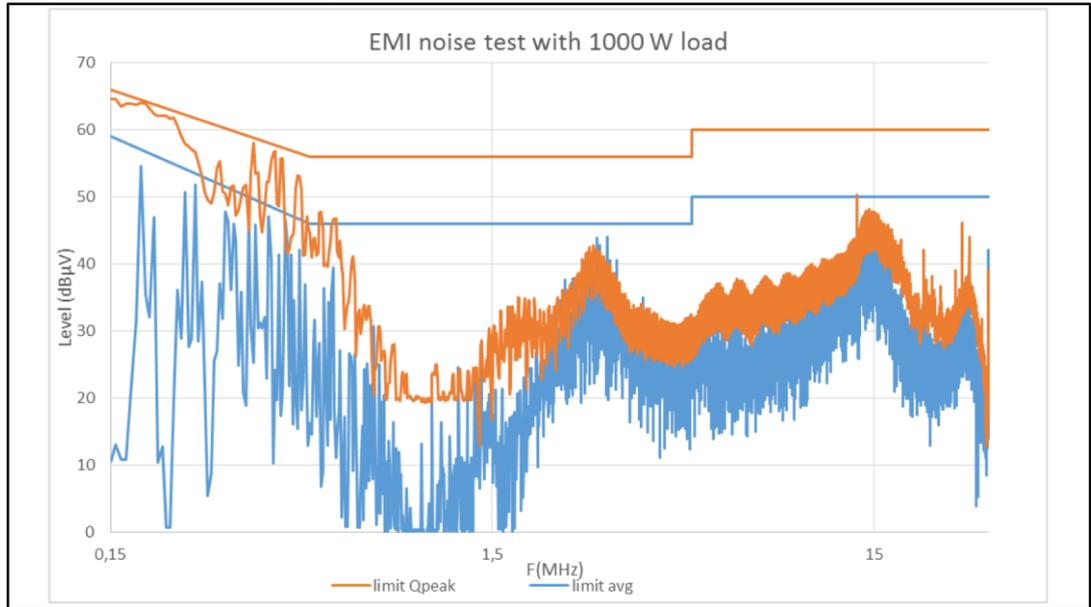
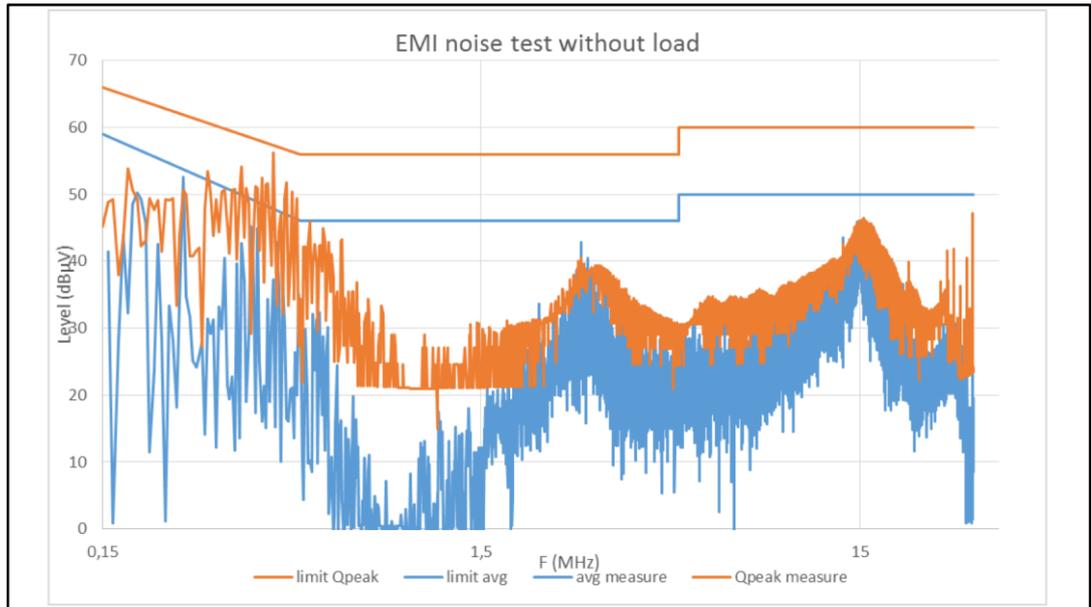


Figure 22: EMI noise test without load



11 STEVAL-IHT008V1 silk-screen

Figure 23: STEVAL-IHT008V1 silk-screen (Top side)

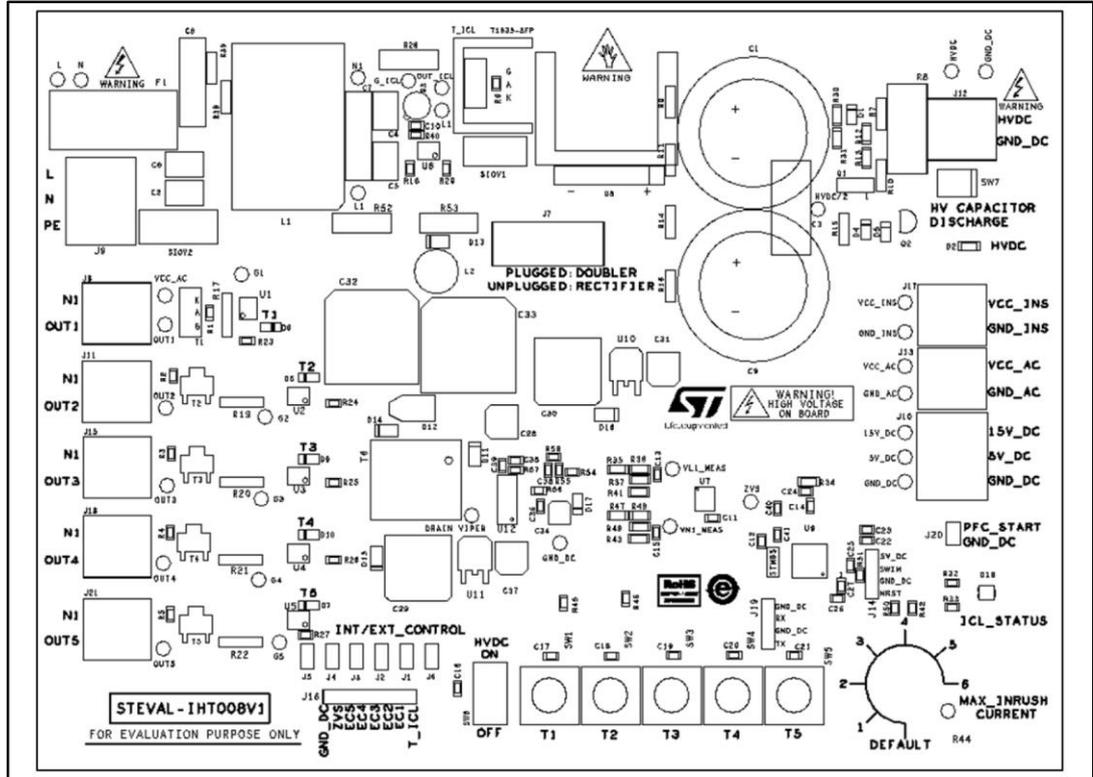


Table 5: Bill of material

Reference	Part / Value
C1, C9	1000 μ F / 250 V
C2, C4, C5, C8	2.2 nF / 440 VAC
C6, C7	56 nF / 300 V
C10	1 nF / 50 V
C11, C14	1 μ F / 25 V
C13, C15, C38	1 nF / 50 V
C16, C17, C18, C19, C20, C21, C24, C26, C27	10 nF / 50 V
C22	100 nF / 50 V
C23	10 μ F / 16 V
C25	680 nF / 25 V
C28	220 μ F / 16 V
C29	1.5 mF / 16 V
C30	220 μ F / 63 V
C31, C37	100 μ F / 16 V
C32	10 μ F / 450 V

Reference	Part / Value
C33	22 μ F / 450 V
C34	2.2 μ F / 63 V
C35	680 pF / 50 V
C36	100 nF / 50 V
C39	330 n / 50 V
D1	BZX55C30
D2, D6, D7, D8, D9, D10	LED
D4	BZX55C5V6
D5	BZX55C15
D11, D15, D16	STPS1150
D12	1.5KE300A
D13	1N4007
D14	STTH1I06
D17	D1N4148
D18	bicolor LED
F1	10 A fuse / 250 V
J1, J2, J3, J4, J5, J6, J20	2 way header_ 2.54 mm pitch
J7	4 way header _ 5.08 pitch
J8, J11, J15, J18, J21, J12, J13, J17	2 way plug _ 5.08 pitch
J9, J10	3 way plug _ 5.08 pitch
J14, J19	4 way header _ 2.54 mm pitch
J16	8 way header _ 2.54 pitch
L1	0.012 H / 10 A
L2	1 mH
Q1	BUX87
Q2	STQ1NK80ZR-AP
Q3	2N2222
R1, R2, R3, R4, R5	220 R / 0.125 W
R6	470 R / 0.125 W
R7, R10	250 k / 0.25 W
R8	2.5 k / 5 W
R9, R11, R14, R16	50 k / 0.25 W
R12, R13	250 k / 0.125 W
R15	3.3 k / 0.25 W
R17, R19, R20, R21, R22	91 R / 0.5 W
R18	1.5 k / 0.125 W
R23, R24, R25, R26, R27	270 R / 0.125 W
R28	36 R / 2 W
R29	2.7 k / 0.125 W
R30, R31, R35, R36, R47, R48	1 M / 0.25 W

Reference	Part / Value
R32, R33	300 R / 0.125 W
R34	21.5 k / 0.25 W
R37, R49	16.2 k / 0.25 W
R38, R39	2.7 M / 0.25 W
R40	4.7 k / 0.125 W
R41, R43	16 k / 0,25 W
R42, R50	0 R / 0.125 W
R44	10 kΩ linear potentiometer
R45, R46	100 k / 0.125 W
R51	10 k / 0.125 W
R52, R53	47 R / 1 W
R54	36 k / 0.125 W
R55	10 k / 0.125 W
R56	20 k / 0.125 W
R57	22 k / 0.125 W
R58	150 R / 0.125 W
SIOV1	S07K300 / 300 VAC
SIOV2	S14K300 / 300 VAC
SW1, SW2, SW3, SW4, SW5	micro_switch
SW6	switch_HVDC
SW7	HV_discharge push button
TP1 to TP34	pcb test point terminals
T_ICL	T1635T-8FP
T1	ACST210-8FP
T2, T3	ACS108-8SN
T4, T5	Z0109MUF
T6	myrra74010
U1, U2, U3, U4, U5, U6	IS127
U7	TS861
U8	GBU1007 bridge rectifier /1000 V / 10 A
U9	STM8S103K3
U10, U11	LM2931
U12	viper26LD

12 Test points

The different test points available on the STEVAL-IHT008V1 are given in the table below.

Table 6: Test points

Reference	Designation	Definition
TP1	L1	Line after EMI filter
TP2, TP21, TP33	VCC_AC	
TP3	HVDC	
TP4	L	Line before EMI filter
TP5	OUT_ICL	A2 output of T_ICL
TP6	OUT1	A2 output of T1
TP7	OUT2	A2 output of T2
TP8	OUT3	A2 output of T3
TP9	OUT4	A2 output of T4
TP10	OUT5	A2 output of T5
TP11	HVDC/2	
TP12	N	Neutral before EMI filter
TP13	N1	Neutral after EMI filter
TP14, TP24,TP29	GND_DC	
TP15	G1	Gate signal of T1
TP16	G2	Gate signal of T2
TP17	G3	Gate signal of T3
TP18	G4	Gate signal of T4
TP19	G5	Gate signal of T5
TP20	G_ICL	Gate signal of T_ICL
TP22	GND_AC	
TP23	15V_DC	
TP25	VCC_INS	
TP26	Drain_viper	
TP27	GND_INS	
TP28	5V_DC	
TP30	ZVS	
TP31	VL1_MEAS	MCU input for line measurement
TP32	VN1_MEAS	MCU input for neutral measurement
TP34	MAX INRUSH CURRENT ORDER	

13 Revision history

Table 7: Document revision history

Date	Revision	Changes
09-Mar-2016	1	Initial release.

IMPORTANT NOTICE – PLEASE READ CAREFULLY

STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, enhancements, modifications, and improvements to ST products and/or to this document at any time without notice. Purchasers should obtain the latest relevant information on ST products before placing orders. ST products are sold pursuant to ST's terms and conditions of sale in place at the time of order acknowledgement.

Purchasers are solely responsible for the choice, selection, and use of ST products and ST assumes no liability for application assistance or the design of Purchasers' products.

No license, express or implied, to any intellectual property right is granted by ST herein.

Resale of ST products with provisions different from the information set forth herein shall void any warranty granted by ST for such product.

ST and the ST logo are trademarks of ST. All other product or service names are the property of their respective owners.

Information in this document supersedes and replaces information previously supplied in any prior versions of this document.

© 2016 STMicroelectronics – All rights reserved